

# Space-Time Covariance Matrix Factorisation and Estimation for Broadband Multichannel Problems, Part 2: Eigenvalue Decomposition

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# Eigenvalue Decomposition

1. Overview
2. Analytic eigenvalue decomposition
3. Polynomial eigenvalue decomposition
4. Time domain algorithms
5. DFT domain algorithms
6. Summary

## 2. Analytic Eigenvalue Decomposition

1. Overview
2. Analytic eigenvalue decomposition
  - 2.1 ordinary EVD
  - 2.2 existence of an analytic EVD
  - 2.3 some properties of the analytic EVD
3. Polynomial eigenvalue decomposition
4. Time domain algorithms
5. DFT domain algorithms
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## 2.1 Ordinary Eigenvalue Decomposition

- ▶ For a Hermitian matrix  $\mathbf{R} = \mathbf{R}^H$ , we know that an eigenvalue decomposition (EVD)  $\mathbf{R} = \mathbf{Q}\mathbf{\Lambda}\mathbf{Q}^H$  exists [32, 35];
- ▶ for eigenvalues  $\mathbf{\Lambda} = \text{diag}\{\lambda_1, \dots, \lambda_M\}$  and eigenvectors  $\mathbf{Q} = [\mathbf{q}_1, \dots, \mathbf{q}_M]$ :

$$\mathbf{R}\mathbf{q}_m = \lambda_m\mathbf{q}_m$$

- ▶ eigenvalues  $\lambda \in \mathbb{R}$ ;
- ▶ eigenvectors can be chosen as orthonormal, but may have an arbitrary phase shift:  $\mathbf{q}'_m = e^{j\varphi}\mathbf{q}_m$  is also an eigenvector;
- ▶ in case of an algebraic multiplicity  $C$ :  $\lambda_m = \lambda_{m+1} = \dots = \lambda_{m+C-1}$ , only a  $C$ -dimensional subspace is defined, within which the eigenvectors can form an arbitrary orthonormal basis, with any unitary  $\mathbf{V}$ :

$$[\mathbf{q}'_m, \dots, \mathbf{q}'_{m+C-1}] = [\mathbf{q}_m, \dots, \mathbf{q}_{m+C-1}] \mathbf{V}. \quad (1)$$

## 2.2 Existence of an Analytic EVD on a Real Interval

- ▶ A standard EVD can diagonalise  $\mathbf{R}(z)$   $\bullet \rightarrow \circ \mathbf{R}[\tau]$  only for one specific value of  $z$  or of  $\tau$ , respectively;
- ▶ Franz Rellich (1939, [67]) for a self-adjoint, analytic  $\mathbf{R}(t) = \mathbf{R}^H(t)$ ,  $t \in \mathbb{R}$ :

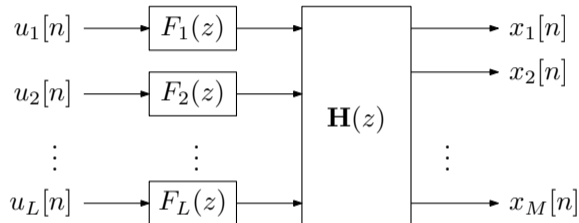
$$\mathbf{R}(t) = \mathbf{Q}(t)\mathbf{\Lambda}(t)\mathbf{Q}^H(t) ;$$

- ▶  $\mathbf{Q}(t)$  and  $\mathbf{\Lambda}(t)$  can be chosen analytic;
- ▶ similarly for an arbitrary (i.e. not necessarily Hermitian or square) analytic matrix, de Moor & Boyd (1989, [24]) and Bunse-Gerstner (1991, [8]) established an analytic SVD.



## Analyticity of $\mathbf{R}(z)$

- ▶ The analyticity of  $\mathbf{R}(z) = \mathcal{E}\{\mathbf{x}[n]\mathbf{x}^H[n - \tau]\}$  can be tied to a source model [63, 84] with white  $u_\ell[n] \in \mathcal{N}(0, 1)$ :



- ▶ the innovation filters  $F_\ell(z)$ ,  $\ell = 1, \dots, L$  describe the spectral shape of the  $L$  contributing source signals;
- ▶ a convolutive mixing system  $\mathbf{H}(z) : \mathbb{C} \rightarrow \mathbb{C}^{M \times N}$  models the transfer paths between the  $L$  sources and  $M$  sensors;
- ▶ if  $F_\ell(z)$  and  $\mathbf{H}(z)$  are stable and causal, then  $\mathbf{R}(z) = \mathbf{H}(z)\mathbf{F}(z)\mathbf{F}^P(z)\mathbf{H}^P(z)$  is analytic.

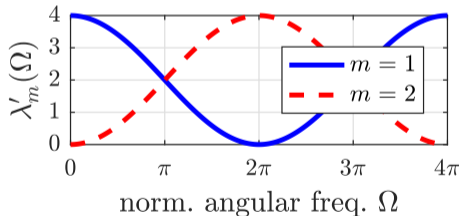
## Analytic EVD on the Unit Circle

- ▶ Analyticity of  $\mathbf{R}(z)$  permits a restricted evaluation on the unit circle  $z = e^{j\Omega}$ ;
- ▶ due to Rellich [67]:

$$\mathbf{R}(e^{j\Omega}) = \mathbf{Q}(\Omega) \mathbf{\Lambda}(\Omega) \mathbf{Q}^H(\Omega), \quad (2)$$

- ▶ unfortunately, while analytic in  $\Omega \in \mathbb{R}$ ,  $\mathbf{\Lambda}(\Omega)$  and  $\mathbf{Q}(\Omega)$  can be  $2\pi L$ -periodic, with some  $L \in \mathbb{Z}$  [85, 6];
- ▶ example [20, 72, 85]:

$$\mathbf{R}(z) = \frac{1}{2} \begin{bmatrix} 2 & 1 + z^{-1} \\ 1 + z & 2 \end{bmatrix},$$
$$\rightarrow \lambda_{1,2}(z) = 2 \pm (z^{\frac{1}{2}} + z^{-\frac{1}{2}}),$$
$$\lambda'_{1,2}(\Omega) = 2 \pm \cos(\Omega/2);$$



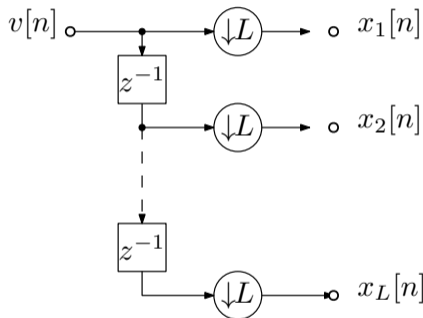
- ▶ while  $\cos(\Omega/2)$  is analytic in  $\Omega$ , a fractional delay  $z^{-\frac{1}{2}}$  is not analytic: its time domain equivalent decays too slowly [47].

## Non-Existence of an Analytic EVD of $\mathbf{R}(z)$

- ▶ The case  $L > 1$  can be tied to multiplexing operation [85];
- ▶ assume  $\mathbf{x}[n]$  is  $L$ -fold demultiplexed,  
 $\mathbf{R}(z) \bullet \text{---} \circ \mathcal{E} \{ \mathbf{x}[n] \mathbf{x}^H[n - \tau] \}$ ;
- ▶  $\mathbf{R}(z)$  will be pseudo-circulant [75] with modulated eigenvalues [85, 6];
- ▶  $\mathbf{Q}(\Omega)$  and  $\mathbf{\Lambda}(\Omega)$  will be  $2\pi L$ -periodic;
- ▶ as such, we can only find an analytic EVD if  $\mathbf{R}(z)$  is  $L$ -fold oversampled [85]:

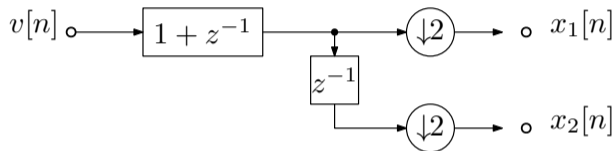
$$\mathbf{R}(z^L) = \mathbf{Q}(z) \mathbf{\Lambda}(z) \mathbf{Q}^P(z). \quad (3)$$

- ▶ a similar effect occurs with the analytic SVD [6, 88], which can be linked to the analytic EVD [79].



## Return to Example

- ▶ The previous example of  $\mathbf{R}(z) = [2, 1 + z^{-1}; 1 + z, 2]$  arises from the following arrangement with white  $v[n] \in \mathcal{N}(0, 1)$ :



- ▶ therefore we require oversampling by  $L = 2$ :

$$\mathbf{R}(z^2) = \begin{bmatrix} 1 & 1 \\ z & -z \end{bmatrix} \begin{bmatrix} z + 2 + z^{-1} & \\ & -z + 2 - z^{-1} \end{bmatrix} \begin{bmatrix} 1 & z^{-1} \\ 1 & -z^{-1} \end{bmatrix};$$

- ▶ multiplexing is linked to a pseudo-circulant property of  $\mathbf{R}(z)$  [74]; this may be obscured by paraunitary similarity transforms [85, 6].

## Analytic EVD of a Parahermitian Matrix

- ▶ For an analytic parahermitian matrix  $\mathbf{R}(z)$ ,  $z \in \mathbb{C}$ , that is not connected to multiplexing, we can find [84, 85]

$$\mathbf{R}(z) = \mathbf{Q}(z) \mathbf{\Lambda}(z) \mathbf{Q}^P(z), \quad (4)$$

with analytic factors;

- ▶  $\mathbf{Q}(z) = [\mathbf{q}_1(z), \dots, \mathbf{q}_M(z)]$  must be paraunitary [74, 76], such that

$$\mathbf{Q}(z)\mathbf{Q}^P(z) = \mathbf{Q}^P(z)\mathbf{Q}(z) = \mathbf{I}; \quad (5)$$

- ▶  $\mathbf{\Lambda}(z) = \text{diag}\{\lambda_1(z), \dots, \lambda_M\}$  must be diagonal and parahermitian;
- ▶ the parahermitian property implies that on the unit circle,  $\lambda(e^{j\Omega}) = \lambda(z)|_{z=e^{j\Omega}} \in \mathbb{R}$ .

## 2.3 Properties: Uniqueness and Ambiguities

- ▶ For the analytic EVD [84, 85, 6]

$$\mathbf{R}(z) = \mathbf{Q}(z) \cdot \mathbf{\Lambda}(z) \cdot \mathbf{Q}^P(z) ; \quad (6)$$

- ▶ the eigenvalues in  $\mathbf{\Lambda}(z)$  are unique up to a permutation;
- ▶ if eigenvalues are distinct, then eigenvectors are unique up to an allpass filter  $\psi_\ell(z)$ ;
- ▶ with  $\mathbf{\Psi}(z) = \text{diag}\{\psi_1(z), \dots, \psi_M(z)\}$ ,

$$\begin{aligned} \mathbf{R}(z) &= \mathbf{Q}(z) \mathbf{\Psi}(z) \mathbf{\Lambda}(z) \mathbf{\Psi}^P(z) \mathbf{Q}^P(z) \\ &= \mathbf{Q}(z) \mathbf{\Lambda}(z) \mathbf{\Psi}(z) \mathbf{\Psi}^P(z) \mathbf{Q}^P(z) \\ &= \mathbf{Q}(z) \mathbf{\Lambda}(z) \mathbf{Q}^P(z) ; \end{aligned}$$

- ▶ an analytic allpass  $\psi_m(z)$  does not affect analyticity, but will affect the support of  $\mathbf{Q}[n] \circ \text{---} \bullet \mathbf{Q}(z)$ .

## Properties: Support of EVD Factors

- ▶ We calculate the analytic EVD of an arbitrary parahermitian  $\mathbf{R}(z) : \mathbb{C} \rightarrow \mathbb{C}^{2 \times 2}$ ;
- ▶ eigenvalues  $\gamma_{1,2}(z)$  can be directly computed in the  $z$ -domain as the roots of

$$\det\{\gamma(z)\mathbf{I} - \mathbf{R}(z)\} = \gamma^2(z) - T(z)\gamma(z) + D(z) = 0$$

- ▶ determinant  $D(z) = \det\{\mathbf{R}(z)\}$  and trace  $T(z) = \text{trace}\{\mathbf{R}(z)\}$ ;
- ▶ this leads to

$$\gamma_{1,2}(z) = \frac{1}{2}T(z) \pm \frac{1}{2}\sqrt{T(z)T^P(z) - 4D(z)} ; \quad (7)$$

- ▶ awkward:  $T(z)T^P(z) - 4D(z) = S(z)S^P(z)$  is parahermitian, but so must be the result of the square root.

## Exact Calculation cont'd

- ▶ Maclaurin series: for every root of  $S(z)$ ,

$$\sqrt{1 - \beta z^{-1}} = \sum_{n=0}^{\infty} \xi_n \beta^n z^{-n} \quad (8)$$

$$\frac{1}{\sqrt{1 - \alpha z^{-1}}} = \left( \sum_{n=0}^{\infty} \xi_n \alpha^n z^{-n} \right)^{-1} = \sum_{n=0}^{\infty} \chi_n \alpha^n z^{-n} \quad (9)$$

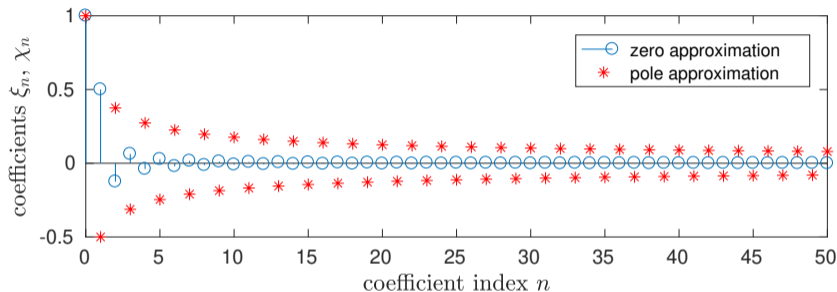
- ▶ with coefficients [7]

$$\xi_n = (-1)^n \binom{\frac{1}{2}}{n} = \frac{(-1)^n}{n!} \prod_{i=0}^{n-1} \left( \frac{1}{2} - i \right), \quad (10)$$

$$\chi_n = (-1)^n \binom{-\frac{1}{2}}{n} = \frac{(-1)^{n-1}}{n!} \prod_{i=0}^{n-1} \left( \frac{1}{2} + i \right). \quad (11)$$

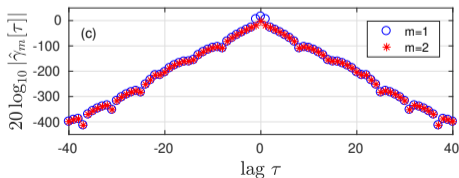
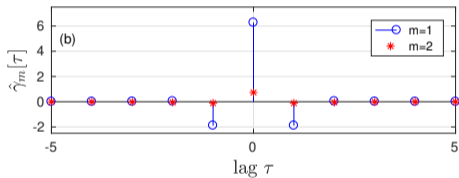
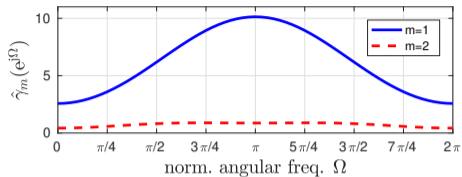
# Maclaurin Series

- ▶ Coefficients  $\xi_n$  and  $\chi_n$  for  $n = 0 \dots 50$  [84]:



- ▶ these coefficients additionally dampen a geometric series in (8) and (9);
- ▶ only if  $S(z)$  has double zeros (and double poles) is a polynomial (rational) solution possible;
- ▶ in general, the result are transcendental eigenvalues.

# Numerical Example



- ▶ Example from Icart & Comon (2012, [34]):

$$\mathbf{R}(z) = \begin{bmatrix} 1 & 1 \\ 1 & -2z + 6 - 2z^{-1} \end{bmatrix}$$

- ▶ (top) solution on unit circle;
- ▶ (middle) coefficients of analytic eigenvalues;
- ▶ (bottom) decay of coefficients;
- ▶ solution generally can be transcendental, i.e. neither finite nor rational.

## 3. Polynomial Eigenvalue Decomposition

1. Overview
2. Analytic eigenvalue decomposition
3. Polynomial eigenvalue decomposition
  - 3.1 spectral majorisation
  - 3.2 relation to analytic EVD
  - 3.3 numerical example
4. Time domain algorithms
5. DFT domain algorithms
6. Summary

## 3.1 Polynomial EVD and Spectral Majorisation

- ▶ Polynomial EVD or McWhirter decomposition [49] of the CSD matrix

$$\mathbf{R}(z) \approx \mathbf{U}(z) \mathbf{\Gamma}(z) \mathbf{U}^P(z) \quad (12)$$

- ▶ with paraunitary, polynomial  $\mathbf{U}(z)$ , s.t.  $\mathbf{U}(z)\mathbf{U}^P(z) = \mathbf{I}$ ;
- ▶ diagonal Laurent polynomial matrix

$$\mathbf{\Gamma}(z) = \text{diag}\{\gamma_1(z), \dots, \gamma_M(z)\}, \quad (13)$$

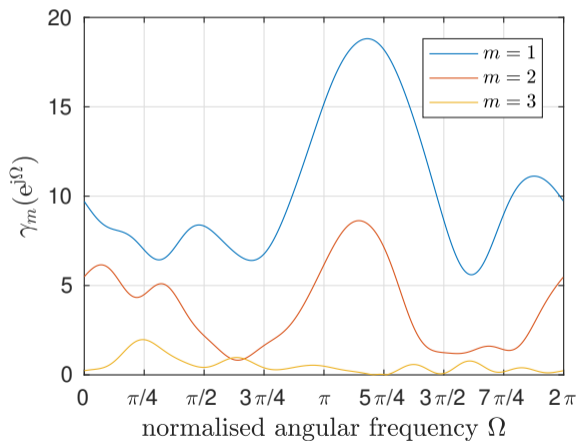
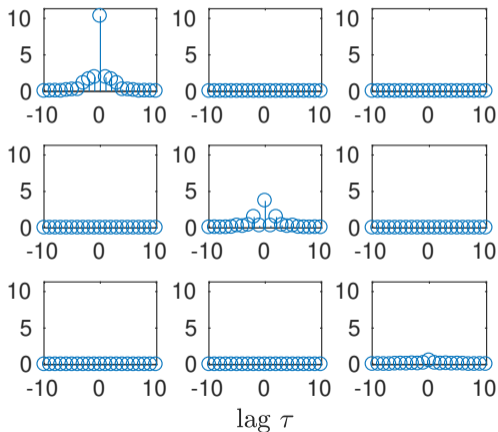
- ▶ approximation sign due to restriction to polynomials [34];
- ▶ the eigenvalues are spectrally majorised [73], i.e. on the unit circle satisfy

$$\gamma_m(e^{j\Omega}) \geq \gamma_{m+1}(e^{j\Omega}), \quad \forall \Omega, \quad m = 1, \dots, (M - 1). \quad (14)$$



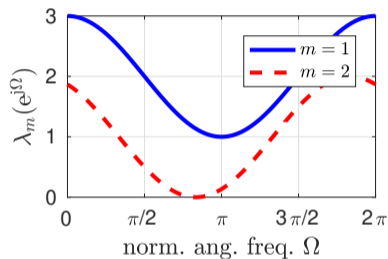
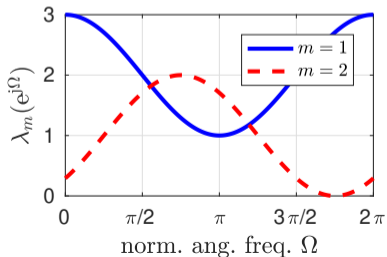
# Polynomial Eigenvalues and Spectral Majorisation

► Example for polynomial eigenvalues  $\gamma_m[\tau]$   $\circ$ — $\bullet$   $\gamma_m(e^{j\Omega})$  of a  $3 \times 3$  matrix:



## 3.2 Relation to Analytic EVD

- ▶ If the analytic eigenvalues do not intersect on the unit circle, then analytic EVD and polynomial EVD (with sufficiently high order) are 'identical';
- ▶ the polynomial EVD has a strict ordering of eigenvalues;
- ▶ specific polynomial/analytic eigenvector solution may differ — recall the allpass ambiguity;



- ▶ if analytic eigenvalues intersect, then the solutions of analytic EVD and polynomial EVD differ;
- ▶ we explore by way of an example ...

### 3.3 Numerical Example

- ▶ We pick our own eigenvalues (order 2) and eigenvectors (order 1):

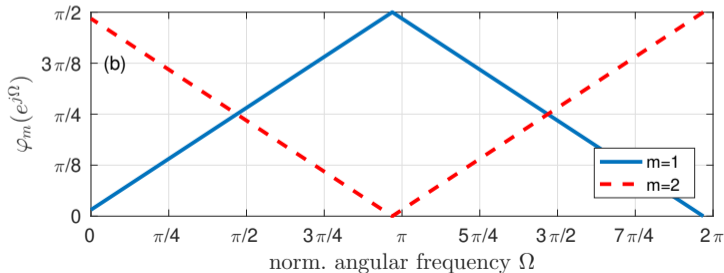
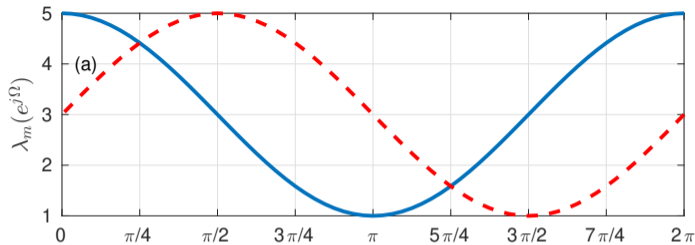
$$\mathbf{\Lambda}(z) = \begin{bmatrix} z + 3 + z^{-1} & \\ & -jz + 3 + jz^{-1} \end{bmatrix}$$

$$\mathbf{Q}(z) = [\mathbf{q}_1(z), \mathbf{q}_2(z)] \quad \text{with} \quad \mathbf{q}_{1,2}(z) = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ \pm z^{-1} \end{bmatrix};$$

- ▶ parahermitian matrix  $\mathbf{R}(z) = \mathbf{Q}(z)\mathbf{\Lambda}(z)\mathbf{Q}^P(z)$ :

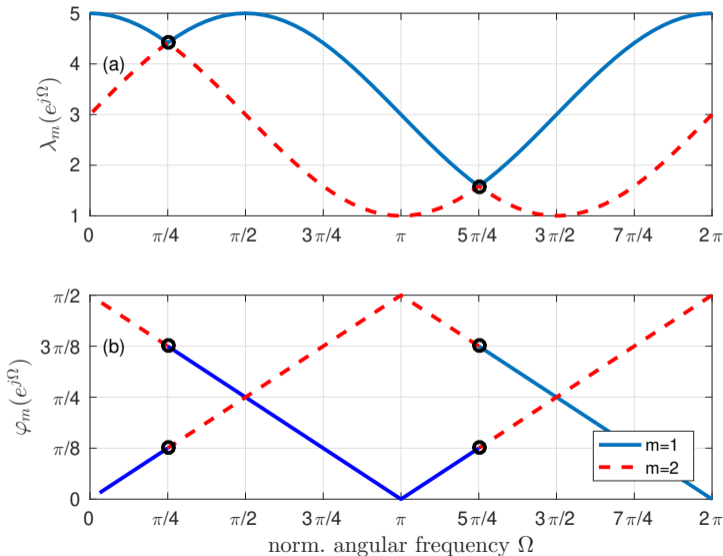
$$\mathbf{R}(z) = \begin{bmatrix} \frac{1-j}{2}z + 3 + \frac{1+j}{2}z^{-1} & \frac{1+j}{2}z^2 + \frac{1-j}{2} \\ \frac{1+j}{2} + \frac{1-j}{2}z^{-2} & \frac{1-j}{2}z + 3 + \frac{1+j}{2}z^{-1} \end{bmatrix}.$$

## Numerical Example — Analytic Solution



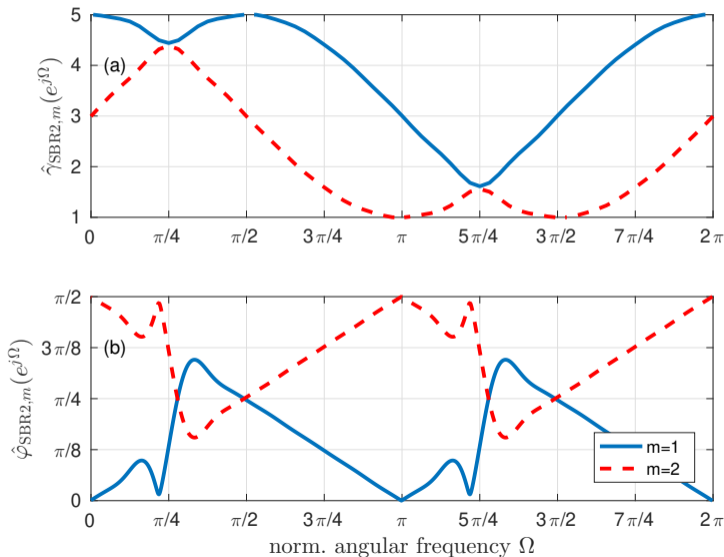
- ▶ Analytic (and therefore infinitely differentiable) eigenvalues  $\lambda_m(e^{j\Omega})$ ;
  - ▶ smooth Hermitian angles
- $$\cos \varphi_m = |\mathbf{q}_1^H(e^{j0}) \cdot \mathbf{q}_m(e^{j\Omega})|.$$

## Numerical Example — Ideal Spectral Majorisation



- ▶ Analytic eigenvalues are permuted where they intersect;
- ▶ resulting spectrally majorised eigenvalues are piecewise analytic but not differentiable;
- ▶ corresponding eigenvectors are piecewise analytic but not continuous.

## Numerical Example — PEVD Algorithmic Solution



- ▶ Using the SBR2 algorithm in [49] to approximate the McWhirter factorisation;
- ▶ trimming is applied to PEVD factors [15, 31, 16, 71];
- ▶ spectrally majorised eigenvalues  $\mathbf{\Gamma}(z)$  of order 24;
- ▶ corresponding eigenvectors in  $\mathbf{U}(z)$  of order 84;
- ▶ SBR2's spectral majorisation can be beneficial or detrimental in applications.

## 4. Time Domain Algorithms

1. Overview
2. Analytic eigenvalue decomposition
3. Polynomial eigenvalue decomposition
4. Time domain algorithms
  - 4.1 iterative PEVD approaches
  - 4.2 second order sequential best rotation (SBR) algorithm
  - 4.3 sequential matrix diagonalisation algorithm
  - 4.4 comparison
5. DFT domain algorithms
6. Summary

## 4.1 Iterative PEVD Approach

- ▶ Second order sequential best rotation (SBR2, McWhirter 2007, [49, 63, 66, 77]);
- ▶ iterative approach based on an elementary paraunitary operation:

$$\begin{aligned} \mathbf{S}^{(0)}(z) &= \mathbf{R}(z) \\ &\vdots \\ \mathbf{S}^{(i+1)}(z) &= \left\{ \mathbf{H}^{(i+1)}(z) \right\}^P \mathbf{S}^{(i)}(z) \mathbf{H}^{(i+1)}(z) \end{aligned}$$

- ▶  $\mathbf{H}^{(i)}(z)$  is an elementary paraunitary operation, which at the  $i$ th step eliminates the largest off-diagonal element in  $\mathbf{S}^{(i-1)}(z)$ ;
- ▶ stop after  $I$  iterations:

$$\hat{\mathbf{\Gamma}}(z) = \mathbf{S}^{(I)}(z) \quad , \quad \hat{\mathbf{U}}(z) = \prod_{i=1}^I \mathbf{H}^{(i)}(z)$$

- ▶ sequential matrix diagonalisation (SMD) [10, 11, 12, 13, 14, 15, 17, 18, 19, 21, 58, 64] follows a similar scheme.

## Elementary Paraunitary Operation

- ▶ An elementary paraunitary matrix [74] is defined as

$$\mathbf{H}^{(i)}(z) = \mathbf{I} - \mathbf{v}^{(i)}\mathbf{v}^{(i),H} + z^{-1}\mathbf{v}^{(i)}\mathbf{v}^{(i),H}, \quad \|\mathbf{v}^{(i)}\|_2 = 1$$

- ▶ we utilise a different definition:

$$\mathbf{H}^{(i)}(z) = \mathbf{D}^{(i)}(z)\mathbf{Q}^{(i)}$$

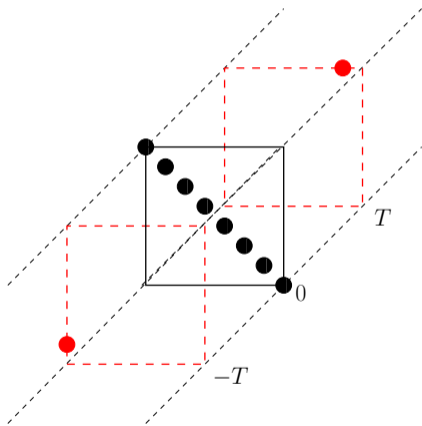
- ▶  $\mathbf{D}^{(i)}(z)$  is a delay matrix:

$$\mathbf{D}^{(i)}(z) = \text{diag}\{1 \dots 1 z^{-\tau} 1 \dots 1\}$$

- ▶  $\mathbf{Q}^{(i)}(z)$  is a Givens rotation.

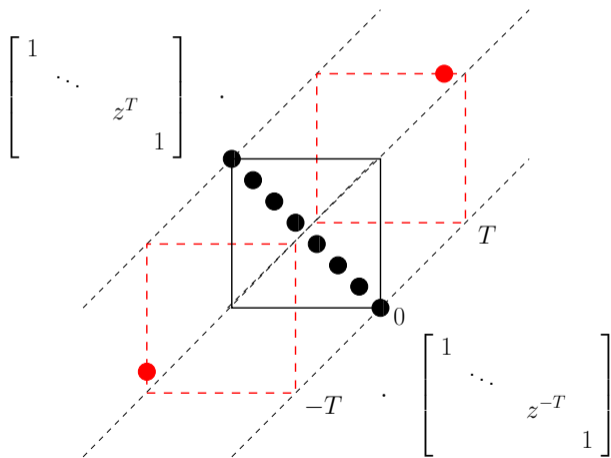
## 4.2 Sequential Best Rotation Algorithm (McWhirter [49])

- ▶ At iteration  $i$ , consider  $\mathbf{S}^{(i-1)}(z) \circ \mathbf{S}^{(i-1)}[\tau]$  (max. off-diag. value:  $\bullet$ )



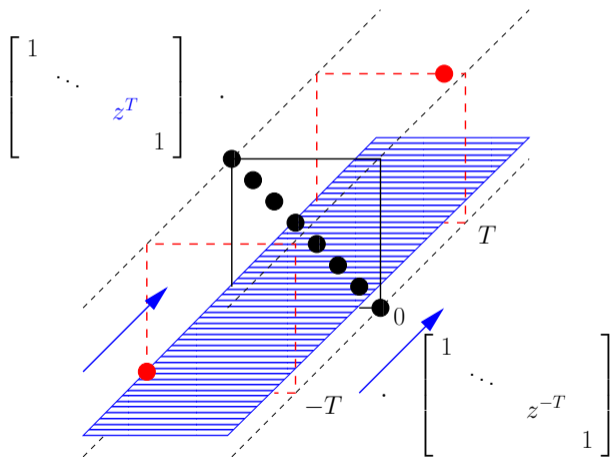
## 4.2 Sequential Best Rotation Algorithm (McWhirter [49])

►  $\tilde{D}^{(i)}(z)\mathbf{S}^{(i-1)}(z)\mathbf{D}^{(i)}(z)$



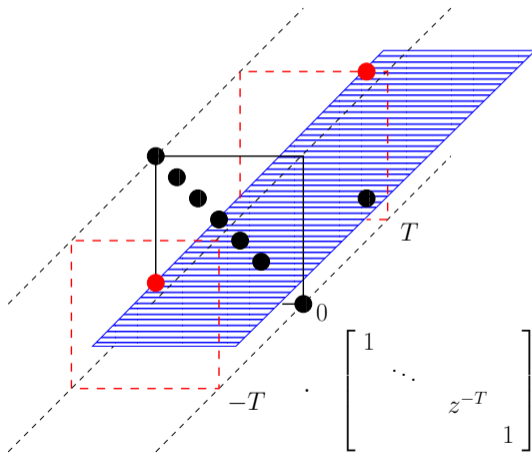
## 4.2 Sequential Best Rotation Algorithm (McWhirter [49])

- ▶  $\tilde{D}^{(i)}(z)$  advances a row-slice of  $S^{(i-1)}(z)$  by  $T$



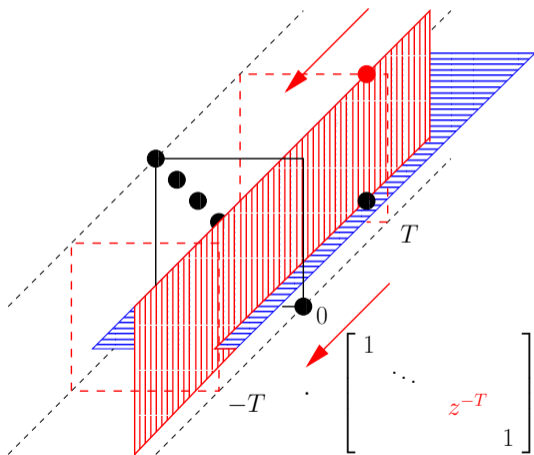
## 4.2 Sequential Best Rotation Algorithm (McWhirter [49])

- ▶ the off-diagonal element at  $-T$  has now been translated to lag zero



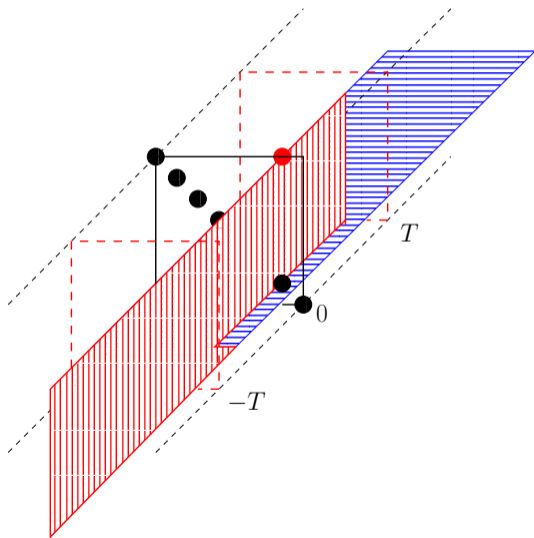
## 4.2 Sequential Best Rotation Algorithm (McWhirter [49])

- ▶  $\mathbf{D}^{(i)}(z)$  delays a column-slice of  $\mathbf{S}^{(i-1)}(z)$  by  $T$



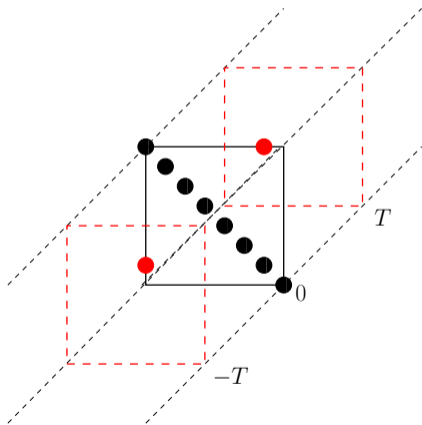
## 4.2 Sequential Best Rotation Algorithm (McWhirter [49])

- ▶ the off-diagonal element at  $-T$  has now been translated to lag zero



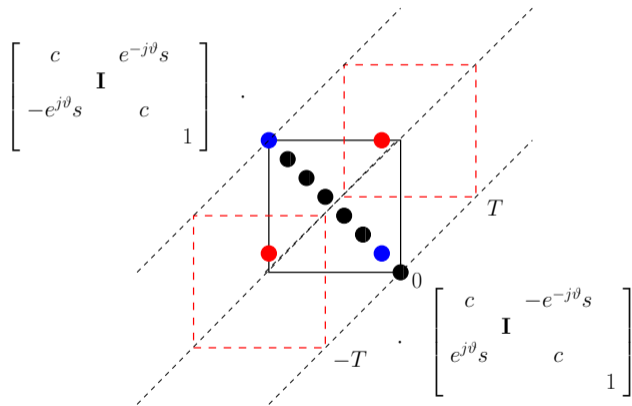
## 4.2 Sequential Best Rotation Algorithm (McWhirter [49])

- ▶ the step  $\tilde{D}^{(i)}(z)\mathbf{S}^{(i-1)}(z)\mathbf{D}_{(i)}(z)$  has brought the largest off-diagonal elements to lag 0.



## 4.2 Sequential Best Rotation Algorithm (McWhirter [49])

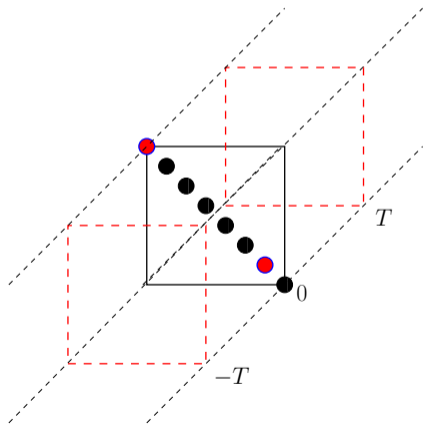
- Jacobi step to eliminate largest off-diagonal elements by  $\mathbf{Q}^{(i)}$



## 4.2 Sequential Best Rotation Algorithm (McWhirter [49])

- ▶ iteration  $i$  is completed, having performed

$$\mathbf{S}^{(i)}(z) = \mathbf{Q}^{(i)} \mathbf{D}^{(i)}(z) \mathbf{S}^{(i-1)}(z) \tilde{\mathbf{D}}^{(i)}(z) \tilde{\mathbf{Q}}^{(i)}(z)$$



## SBR2 Outcome

- ▶ At the  $i$ th iteration, the zeroing of off-diagonal elements achieved during previous steps may be partially undone;
- ▶ the algorithm has proven convergence, transferring energy onto the main diagonal at every step [49];
- ▶ after  $I$  iterations, we reach an approximate diagonalisation

$$\hat{\Gamma}(z) = \mathbf{S}^{(L)}(z) = \hat{\mathbf{U}}^{\text{P}}(z)\mathbf{R}(z)\hat{\mathbf{U}}(z)$$

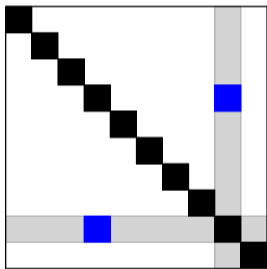
with

$$\hat{\mathbf{U}}(z) = \prod_{i=1}^I \mathbf{D}^{(i)}(z)\mathbf{Q}^{(i)}$$

- ▶ the factors may require trimming of trailing zeros or very small coefficients [15, 16, 31, 37, 71].

## SBR2 — Givens Rotation

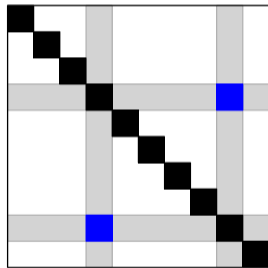
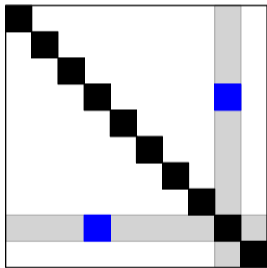
- ▶ A Givens rotation eliminates the maximum off-diagonal element once brought onto the lag-zero matrix;
- ▶ note I: in the lag-zero matrix, one column and one row are modified by the shift:



- ▶ note II: a Givens rotation only affects two columns and two rows in every matrix;
- ▶ Givens rotation is relatively low in computational cost, but the zero lag component is not diagonal.

## SBR2 — Givens Rotation

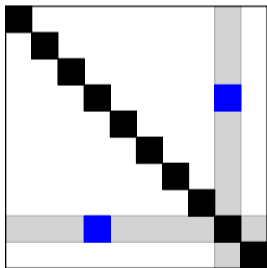
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## 4.3 Sequential Matrix Diagonalisation (SMD, [64])

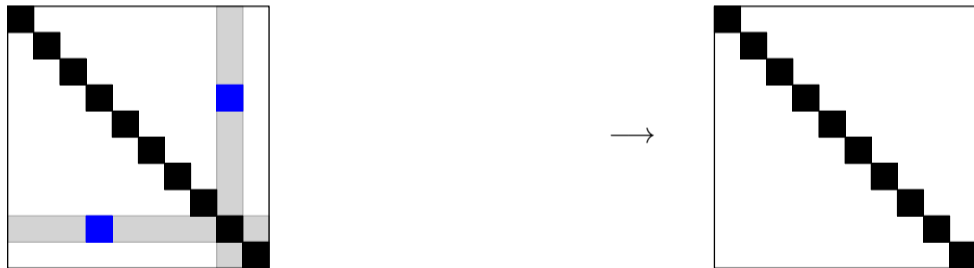
- ▶ Main idea — the zero-lag matrix is diagonalised in every step;
- ▶ initialisation: diagonalise  $\mathbf{R}[0]$  by EVD and apply modal matrix to all matrix coefficients  $\rightarrow \mathbf{S}^{(0)}$ ;
- ▶ at the  $i$ th step as in SBR2, the maximum element (or column with max. norm) is shifted to the lag-zero matrix:



- ▶ an EVD is used to re-diagonalise the zero-lag matrix;
- ▶ a full modal matrix is applied at all lags — more costly than SBR2.

## 4.3 Sequential Matrix Diagonalisation (SMD, [64])

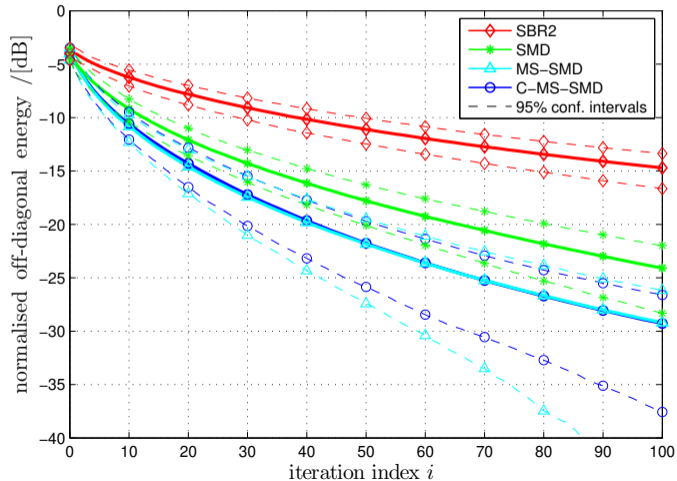
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## 4.4 Comparison: SBR2/SMD Convergence

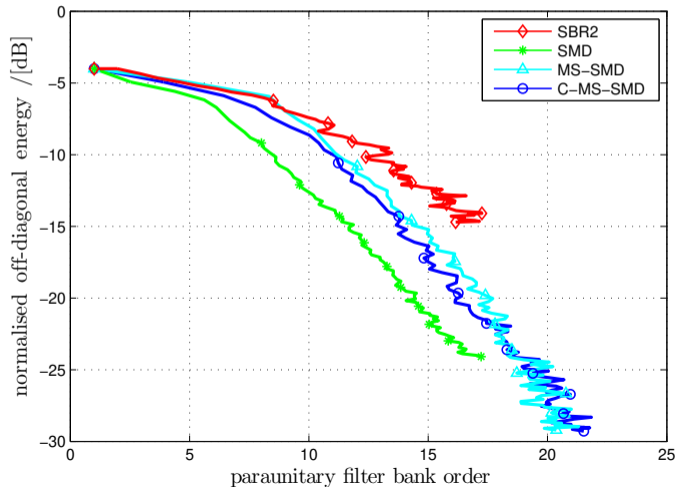
- ▶ Measuring the remaining normalised off-diagonal energy over an ensemble of space-time covariance matrices:



- ▶ SMD [64] and evolved schemes (multiple shift SMD [12] and constrained multiple shift SMD [13]) transferring additional energy on the zero lag component converge faster per iteration;
- ▶ the computation cost per iteration is not comparable: SMD and variants are significantly more complex.

# SBR2/SMD Application Cost 1

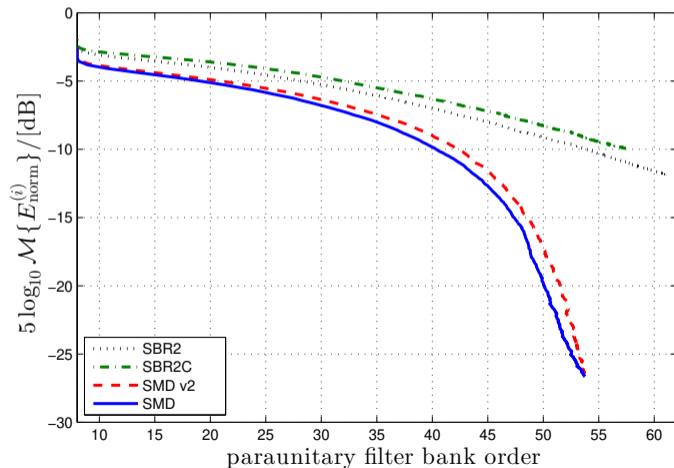
- ▶ Ensemble average of remaining off-diagonal energy vs. order of paraunitary filter banks to decompose 4x4 matrices of order 15:



- ▶ for modestly-sized matrices, SMD a better diagonalisation with lower orders of  $Q(z)$  than other variants;
- ▶ this reflects the cost when applying the PEVD factors e.g. for a subspace decomposition.

## SBR2/SMD Application Cost 2

- ▶ Ensemble average of remaining off-diagonal energy vs. order of paraunitary filter banks to decompose 8x8 matrices of order 63:



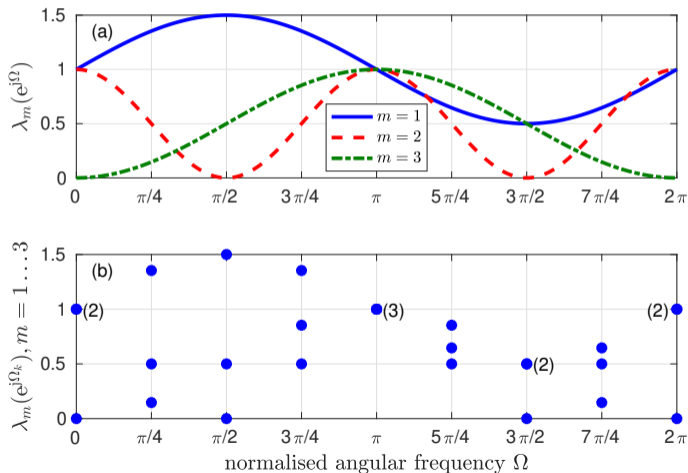
- ▶ for larger matrices of higher order, SMD (and variants) provide a better diagonalisation than SBR2 [49] (and variants [63, 66]) for any given order of  $Q(z)$ .

## 5. DFT Domain Algorithms

1. Overview
2. Analytic eigenvalue decomposition
3. Polynomial eigenvalue decomposition
4. Time domain algorithms
5. DFT domain algorithms
  - 5.1 analytic eigenvalue extraction
  - 5.2 analytic eigenvector extraction
  - 5.3 comparison
6. Summary

## 5.1 Analytic Eigenvalue Extraction

- ▶ Idea for DFT-based algorithms: calculate an EVD in every DFT bin and join the dots;



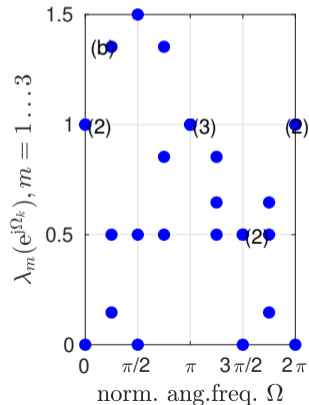
- ▶ spectral coherence must be re-established across bins;
- ▶ we exploit that the solution must be analytic, i.e. infinitely differentiable;
- ▶ we first extract eigenvalues, which are less volatile under perturbation [35];

# Analytic Eigenvalue Extraction Algorithm I

- ▶ Bin-wise EVD yields:

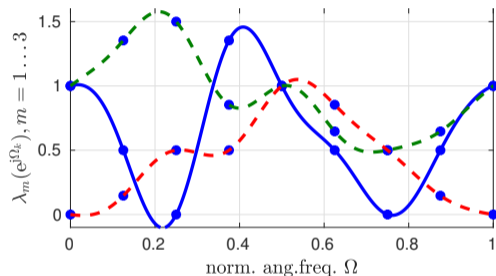
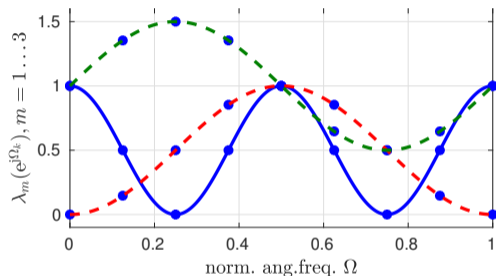
$$\mathbf{R}(e^{j\Omega_k}) = \mathbf{Q}_k \mathbf{\Lambda}_k \mathbf{Q}_k^H = \underbrace{\mathbf{Q}_k \mathbf{\Psi}_k \mathbf{P}_k}_{\mathbf{Q}(e^{j\Omega_k})} \cdot \underbrace{\mathbf{P}_k^T \mathbf{\Lambda}_k \mathbf{P}_k}_{\mathbf{\Lambda}(e^{j\Omega_k})} \cdot \underbrace{\mathbf{P}_k^T \mathbf{\Psi}_k^H \mathbf{Q}_k^H}_{\mathbf{Q}^H(e^{j\Omega_k})}$$

- ▶  $\mathbf{P}_k$  is a permutation matrix, since in the analytic EVD, eigenvalues can intersect and are not necessarily majorised;
- ▶ for distinct eigenvalues:  $\mathbf{\Psi}_k$  is a diagonal matrix that accounts for the phase ambiguity of eigenvectors;
- ▶ in case of a  $C$ -fold algebraic multiplicity:  $\mathbf{\Psi}_K$  is block diagonal, with a  $C \times C$  unitary matrix accounting for eigenvectors forming an arbitrary basis within a  $C$ -dimensional subspace;
- ▶ a predecessor algorithm [72] can fail on this;



## Analytic Eigenvalue Extraction Algorithm II

- ▶ To find the smoothest association of  $M$  functions across  $K$  frequency bins, we compare the power in the  $p$ -th derivative of a Dirichlet interpolation [83, 91, 96]:



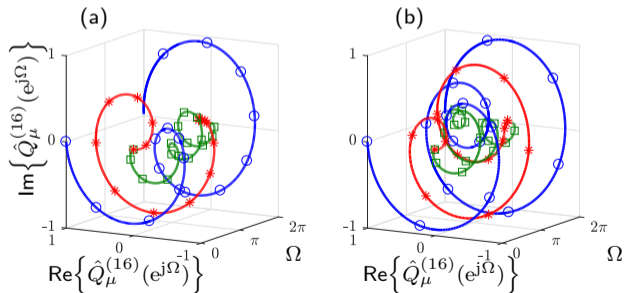
- ▶ for an exhaustive search, there would be  $M!^{K-1}$  associations to check;
- ▶ a Viterbi-type scheme operates iteratively across bins [96], and only retains viable associations [89, 90];
- ▶ DFT length  $K$  can be increased until a criterion based on time-domain aliasing is met.

## 5.2 Analytic Eigenvector Extraction

- ▶ From the eigenvalue extraction, the correct association across frequency bins defines  $\mathbf{P}_k$  [86]:

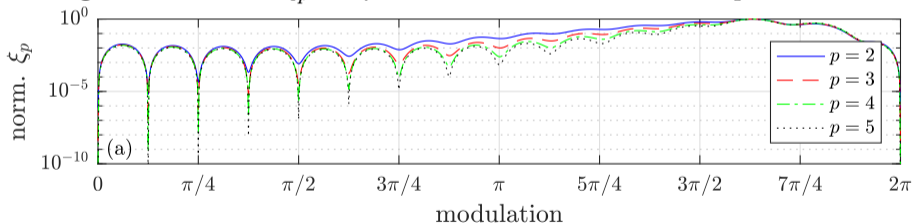
$$\mathbf{R}(e^{j\Omega_k}) = \mathbf{Q}_k \mathbf{\Lambda}_k \mathbf{Q}_k^H = \underbrace{\mathbf{Q}_k \mathbf{\Psi}_k \mathbf{P}_k}_{\mathbf{Q}(e^{j\Omega_k})} \cdot \underbrace{\mathbf{P}_k^T \mathbf{\Lambda}_k \mathbf{P}_k}_{\mathbf{\Lambda}(e^{j\Omega_k})} \cdot \underbrace{\mathbf{P}_k^T \mathbf{\Psi}_k^H \mathbf{Q}_k^H}_{\mathbf{Q}^H(e^{j\Omega_k})}$$

- ▶ for the eigenvalue extraction, it remains to find the correct phase adjustment  $\mathbf{\Psi}_k$ ;
- ▶ again the smoothness of a Dirichlet interpolation can lead to the analytic solution;
- ▶ example:  $M = 3$  components of one eigenvector with different  $\mathbf{\Psi}_k$ .



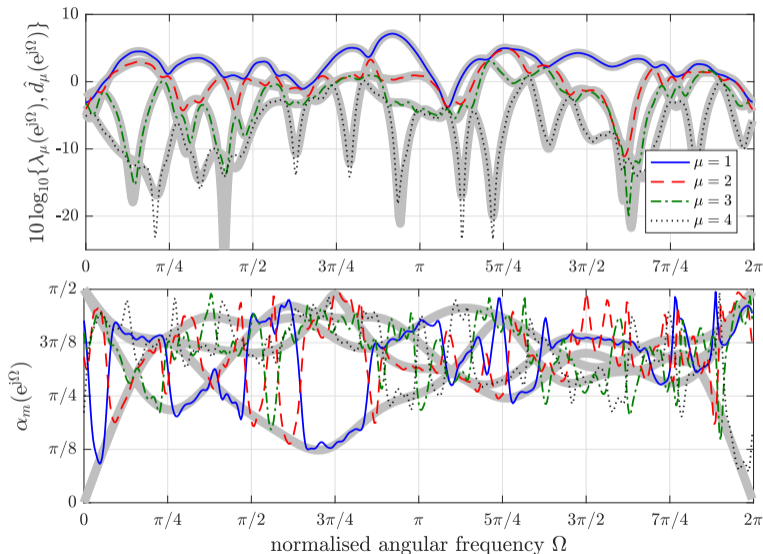
# Analytic Eigenvector Extraction Algorithm

- ▶ The main task for the extraction of analytic eigenvectors is the adjustment of a smooth phase progression  $\Psi_k$  across bins;
- ▶ this problem is NP hard [68], but the specific smoothness cost function possesses — for a sufficient DFT size — stationary points that are approximately separated by a modulation [87];
- ▶ cut through cost function  $\xi_p$  for powers of different derivatives  $p$ :



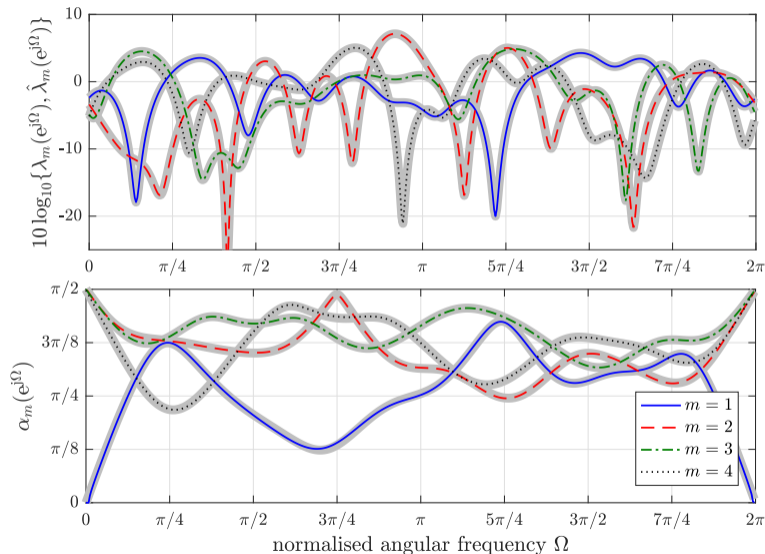
- ▶ an iterative algorithm is proven to converge [87], increasing the DFT length until a reconstruction error is minimised;

## 5.3 Comparison — SMD Algorithm Example



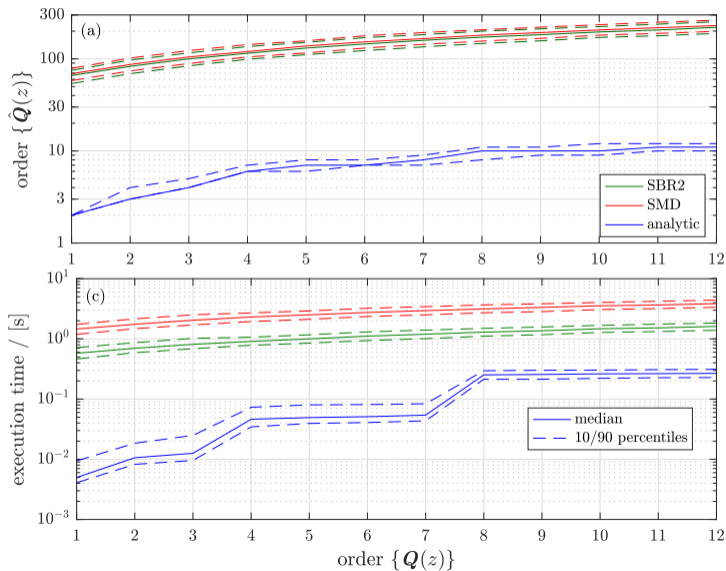
- ▶  $R(z) : \mathbb{C} \rightarrow \mathbb{C}^{4 \times 4}$  of order 47;
- ▶ SMD algorithm [64] yields approximate spectral majorisation [50];
- ▶ Hermitian angles of eigenvectors to a reference vector indicate approximation of piecewise analytic functions.

## Analytic EVD Extraction Example



- ▶ same matrix, but utilising analytic eigen-value [23, 90, 89] and -vector extraction [86, 87, 42];
- ▶ extracted analytic EVD factors are close to ground truth;
- ▶ lower order compared to SMD result.

## Comparison — Ensemble Results



- ▶ ensemble results over matrices with different ground truth, and for various orders;
- ▶ above: application cost — the order of the extracted paraunitary matrices, required e.g. for a subspace projection;
- ▶ below: execution time of the algorithms.

## 6. Summary I

- ▶ An analytic EVD exists in almost all cases — when data is not multiplexed;
- ▶ a polynomial EVD (PEVD) differs if eigenvalues intersect; it targets spectrally majorised eigenvalues;
- ▶ spectral majorisation in the EVD is desirable in coding or communications applications;
- ▶ the PEVD is supported by a number of well-established algorithms [22, 49, 63];
- ▶ analytic EVD algorithms are useful where low-order factors or low-perturbed subspace methods matter;
- ▶ if a space-time covariance matrix is estimated from limited data [25, 26, 27, 28, 39], time- and DFT-domain algorithms target the same factors (within the allpass ambiguity of the eigenvectors) with probability one [46].

## Summary II

- ▶ To calculate an analytic eigenvalue decomposition, a number of efficient implementations have been suggested [22, 45, 40, 41, 43];
- ▶ such algorithms find applications in coding [63, 92], angle of arrival estimation [2, 1, 29, 33, 44, 78], beamforming [3, 4, 54, 65, 80], subspace detection [59, 60, 61, 81], speech enhancement [55, 57, 56, 53], communications [51, 52, 70, 69] and others [62, 82, 93, 95, 94];
- ▶ the idea of an analytic decomposition extends beyond the EVD; similarly the existence has been proven for an analytic SVD [6, 5, 88, 79], and is suspected for the QR decomposition [9];
- ▶ algorithms have been extended to such further decompositions, including the SVD [30, 36, 48, 49, 72, 88, 79, 93, 95, 94] or the QR decomposition [9, 21, 30, 38].

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