

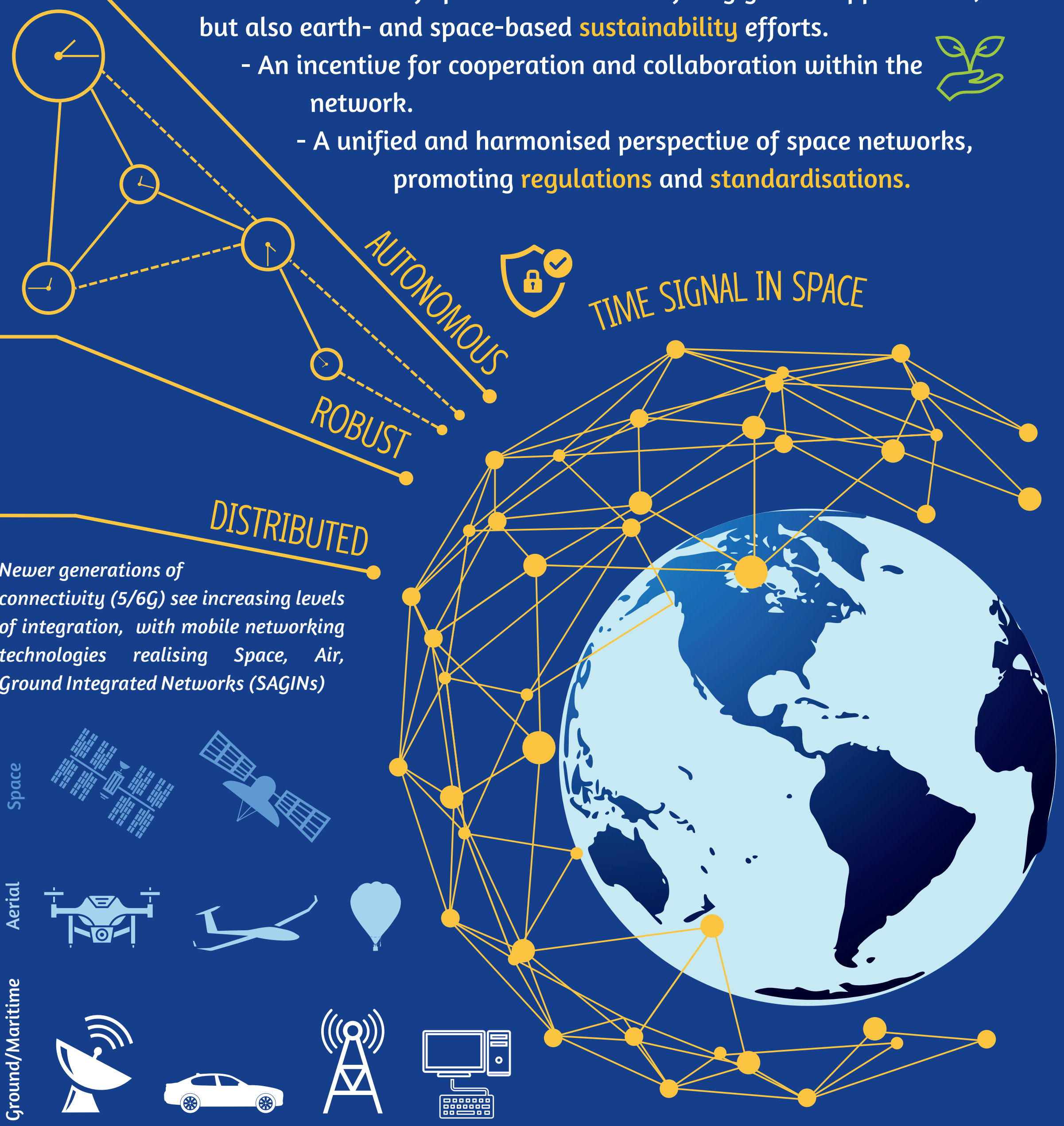
Abstract

As space becomes increasingly contested, the terrestrial vulnerabilities of GPS will extend into orbit. The resulting inability to rely on GPS for time synchronisation on ground and in space will cause a fundamental shift in the approach to space networks. This project aims to design an **autonomous, distributed, robust timing signal in space** as an alternative method to GPS time synchronisation. Building upon prior work in consensus algorithms, this project has developed a Disruption-Tolerant Social-Dynamics inspired approach to consensus. This work is being adapted for time synchronisation and space networks which involve dynamic effects, time delays, and relativity effects.

Space IoTs

This Project will slot itself in the current framework of satellite network communications and offer an **alternative to GPS** time synchronisation and position. This will enable a **higher level of integration** of satellite and constellations, resulting in an augmented architecture allowing for:

- Improved **service coverage, reliability, performance, and efficiency.**
- A more cohesive use of space resources benefiting ground applications, but also earth- and space-based **sustainability** efforts.
- An incentive for cooperation and collaboration within the network.
- A unified and harmonised perspective of space networks, promoting **regulations and standardisations.**



Motivation

GPS signals are used for Earth- and Space-based positioning, and time synchronisation. Many applications rely on these signals to **function** and **coordinate** their actions. To be of use, these GPS signals must be time synchronised, with all GPS atomic clocks showing the same time.

However, this reliance faces two issues:

- GPS's **centralised** approach ("server-client") makes it vulnerable to **single point failures** (incorrect or spoofed signals), causing all downstream applications to suffer.
- GPS atomic clocks still suffer from **drift** and **error**. As such, GPS clocks must still be corrected from ground.

GPS are **vulnerable** and **expensive**: an alternative must be proposed.

A Social Dynamics Approach to Consensus

Love, Hate, and Propaganda, or how opinion dynamics can engineer consensus for synchronisation

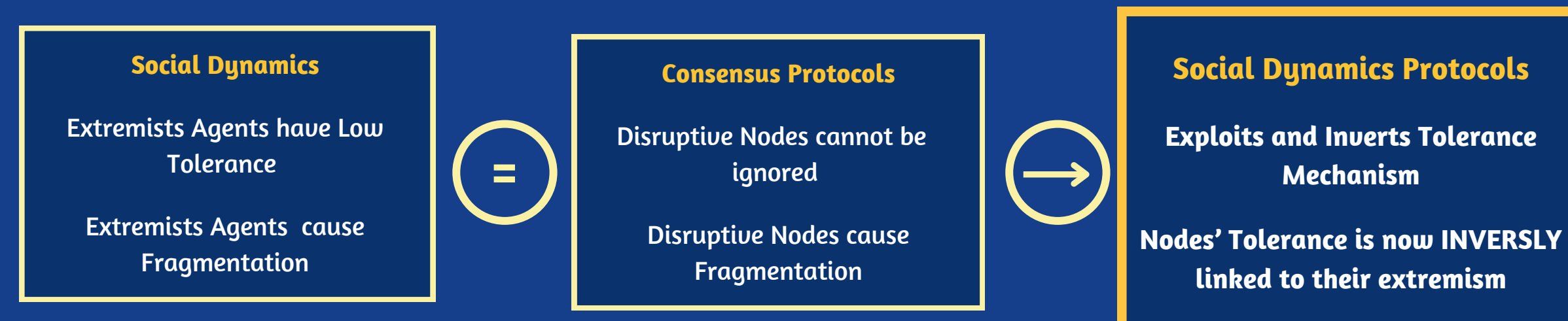
Opinion dynamics models aim to characterise the outcomes of collective behaviours within social networks as a result of opinion sharing. Notably, models are interested in representing how minority opinions can dominate social groups, and cause **polarisation** and **fragmentation**.

The most common Social Dynamics model is the Deffuant Model which defines Agents with a tolerance - a parameter representing agents' willingness to consider other's opinions. Mathematically, tolerance is the maximum allowable difference between two agents' opinions for an agent to account for that of its neighbour when "updating" its own internal state.



Typically, **extremist** agents have a **low tolerance** compared to their more moderate peers, thus swaying them to more extreme opinions (see above).

Based on the similarities in mechanics between Social Dynamics and Consensus Protocols, a **SOCIAL DYNAMICS-INSPIRED PROTOCOL** has been designed, tested, and concluded to be **DISRUPTION-TOLERANT**.



ACKNOWLEDGEMENTS:

This project is funded by the Air Force Office of Scientific Research (AFOSR), Contract Award Number: FA8655-22-1-7033

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I would like to extend my appreciation and thanks to the entire ApSTL team at Strathclyde, including Joshua Gribben, Dr Astrid Werkmeister, Dr Ruaridh Clark, Dr Chris Lowe, and Professor Malcolm Macdonald.