Introduction

Development and validation of a cavitation erosion model

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 \triangleright Absolute values of static pressure and velocity magnitude were compared on the central slice, on a probe line crossing the nozzle joint, for an angle equal to half the overall azimuthal amplitude.

- \triangleright From cavitating solutions, erosion is modelled implementing a new, non-case sensitive methodology.
- \triangleright From grid independence analysis, Mesh 2, θ = 30 °, is chosen to predict cavitation erosion.

 \triangleright Cavitation prediction is realized by using the cavitation model of Singhal et al. [1]. The model equations are proportional to the bubble radius velocity term, computed as a first order approximation of the Rayleigh Plesset equation [4]:

$$
\frac{dr_B}{dt} = \sqrt{\frac{2}{3} \frac{p_{v,\tau}(t) - p_{\infty}(t)}{\rho_l}}
$$

Conclusions and future works

- \triangleright From the grid independence study on domains of azimuthal width equal to 90°, Mesh 2 is chosen as the best compromise computational grid, when static pressure and velocity magnitude curves are tested on the probe line.
- \triangleright Reducing the computational domain azimuthal amplitude from θ = 90° to θ = 30° no relevant differences are detected for Mesh 2. This last condition identifies the chosen grid used to predict cavitation erosion.
- \triangleright Cavitation erosion numerical results show good agreement in the reproduction of the experimental erosion mid-line.
- \triangleright New steady simulations of finer planar meshes, extruded for θ = 30°, are being tested.
- \triangleright New unsteady simulations will be dedicated to assess the effect of the time step sensitivity on the cavitation erosion formation.
- \triangleright The influence of different cavitation models in the prediction of the area affected by erosion will be assessed.

 \triangleright Evaporation and condensation terms, \dot{m}_{ν} and \dot{m}_{l} , respectively, are then enabled according to different pressure conditions:

$$
\text{if } p \leq p_v \Rightarrow \dot{m}_v = C_v \frac{\max\left(1.0; \sqrt{k}\right)}{\sigma} \rho_l \rho_v \sqrt{\frac{2}{3} \frac{p_{v,\tau} - p_{\infty}}{\rho_l}} \left(1 - f_v - \sum_j f_j\right)
$$
\n
$$
\text{if } p \geq p_v \Rightarrow \dot{m}_l = C_l \frac{\max\left(1.0; \sqrt{k}\right)}{\sigma} \rho_l^2 \sqrt{\frac{2}{3} \frac{p_{\infty} - p_{v,\tau}}{\rho_l}} f_v
$$

 \triangleright Numerical simulations are performed adopting the CFD software Ansys Fluent.

- \triangleright The erosion parameters, as for the cavitation model, are based on the bubble dynamics treatment. Bottom plate damage is caused by jets originated by cavitation clouds implosion.
- \triangleright Results show the erosion potential due to jets surface impacts over time. Location of the numerical predicted eroded area is displayed against experimental data produced by J. P. Franc [3]:

Numerical results vs experimental data

Cavitation erosion is a major issue in the working life of hydraulic turbomachines. Vapour formation and bubbles' implosions can lead to the damage of the solid boundaries, provoking performance losses and fatigue failure over time. In this work, cavitation is predicted combining the Full Cavitation Model of Singhal et al. [1] and the modified k-ω SST turbulence model [2]. Simulations, carried out in Ansys Fluent, reproduce a circular sector of the stainless-steel nozzle used in the experiment of J. P. Franc [3]. Results aim at validating a new, non-case sensitive, approach for erosion occurrence.

References

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$$
f_R(\rho) = \rho_v + \frac{(\rho - \rho_v)^n}{(\rho_l - \rho_v)^{n-1}}, \ \ n = 10 \text{ for water} \qquad \qquad \mu_{\tau,R} \propto \frac{k}{\omega} f_R(\rho)
$$

 10.0

