# **ACTIVE AND ACTUATED ASSISTIVE DEVICES FOR THE** HANDS AND WRISTS: A REVIEW Angel Galbert<sup>1,2</sup>, Arjan Buis<sup>1</sup>, Xiu T Yan<sup>2</sup> <sup>1</sup>Department of Biomedical Engineering, University of Strathclyde, Glasgow, UK <sup>2</sup>Department of Design, Manufacturing and Engineering Management (DMEM), University of Strathclyde, Glasgow Email: Angel.Galbert@Strath.ac.uk

# **1. INTRODUCTION**

Muscle weakness and impairment in the hands and wrist can result from a variety of conditions, which differ in terms of their permanence, severity, and treatment.

In the UK, individuals experience hand impairment due to different factors, such as stroke (affecting 100,000 people annually [1]), spinal cord injury leading to paralysis (2,500 individuals each year [2]), multiple sclerosis (impacting 100,000 people [1]) and Parkinson's disease (affecting 137,000 people [1]). Furthermore, the natural aging process can cause muscle loss, of which, leads to reduced muscle strength for pinching and gripping, deterioration of hand function, and diminished prehension [3].



## Figure 3: Trends in Publishments

#### **Count of Studies based on Outcome Method**

Robotic Clinical and Robotic Clinical



# 2. METHODS

The scoping review was conducted in accordance with the **PRISMA-ScR guidelines** [4]. Search terms were defined using the **PCC** (Population /Concept/Context) framework.

**Population** was hand and/or wrist impairment, the **concept**/intervention was an actuated device, and **context** was defined as during activities of daily living and outcome measures.

Inclusions, exclusions, and screening process are provided in Figure 1. Data screening was conducted by two researchers with an **agreement level (accuracy) of 87%.** 

The data charting components extracted include Title, Author, Year of Publishment, Country of Study, Study Methodology, Participants Information, Target Population, Device Name, Weight of Device (g), DoF (Degree of Freedom), Mechanical Transmission, User Intent, and Outcome Measures [5].





## 3.2 Intervention and Demographics:

Pulley systems were the least popular actuation method, whereas direct transmission (Bar linkage, Direct and Gears) was most used followed by muscle contraction via stimulation (Figure 4) which is most used in **clinical studies**. An even distribution of hand and/or wrist device design was noted with limited correlation to design or intended patient population.

The distribution of intended population in Figure 5 does not mirror the proportions of those patient populations in our current world. For example, musculoskeletal injury intended devices was 4.3%, but affects **2.41 billion individuals** that would benefit from rehabilitation [6] compared to stroke intended devices which was 52.1% but affects 143 million DALYs [7].

#### Figure 4: Bar chart of Mechanical Transmission

#### Figure 5: Chart of intended target population



participants is **0.867**, this strong correlation (r < 0.7) is noticed in Figure 2. The oldest publishment found was from **1995** (Figure 3) and since then a rapid growth in publications has been seen within the **last 5 years** contributing to almost 50% (64 studies).

# 3.4 Outcomes:

**228 unique outcome measures** were extracted. The most used outcomes were not reflective of clinical settings [8] and outcomes measures in studies which required minimal setting up were favoured (Figure 6). Patient recorded outcomes were often **unused** such as the **DASH outcome**.

#### Table 1: Abstracted User Intent Input

Jser Intent Methods	Count
EEG	10
<ul> <li>Neural activity</li> </ul>	10
EMG	
<ul> <li>EMG single threshold</li> </ul>	37
<ul> <li>EMG adaptive threshold</li> </ul>	
Joint movement	
<ul> <li>Digit movement*</li> </ul>	
<ul> <li>Digit angle*</li> </ul>	77
<ul> <li>Wrist flexion/extension</li> </ul>	37
<ul> <li>Wrist supination/pronation</li> </ul>	
• Tremor	
Joint force (no digital interface)	
<ul> <li>Fingertip tactile force sensor</li> </ul>	20
<ul> <li>Digit torque*</li> </ul>	29
Wrist torque	
Manual Selection	
<ul> <li>Button, Switch, Joystick</li> </ul>	
<ul> <li>User interface (PC, Mobile,</li> </ul>	
Smartwatch)	77
<ul> <li>Tongue position in mouth interface</li> </ul>	24
<ul> <li>Keyword selection from voice</li> </ul>	
control	

## Figure 6: Bar chart of Outcome Measures





The clinical to non-clinical (robotic) study ratio (Figure 3) was 4:6, with experiments being the most popular. Randomised control trials were the most used clinical methodology (18 studies).

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Foot position in insole interface

# **4. CONCLUSIONS**

In this scoping review, we identified 135 primary studies between 1995 and 2023.

\*All, combination, Index, or 5<sup>th</sup>

Muscle stimulation and direct force transmission were the most popular design of the device. The target population of the devices was focused on stroke affected persons. The number of outcome measures was large and **not reflective of clinical settings**.

Efforts should be in assessing clinical outcome measures and reducing cognitive load by changing manual selection devices to more intuitive ones such as EEG, EMG and Joint induced.

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