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Introduction

### Introduction





 $S = S_B \cup S_W$  - B:Body, W:Wake



Aircraft Vortex Wake

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└─ The Problem

### The Problem



### Velocity Potential

$$\mathbf{V}_{t} = \mathbf{v} + \mathbf{V}$$
$$\mathbf{V}_{t} = \left(\frac{\partial \Phi_{t}}{\partial x}, \frac{\partial \Phi_{t}}{\partial y}, \frac{\partial \Phi_{t}}{\partial z}\right)$$
$$\Phi_{t} = \phi + \mathbf{V} \cdot \mathbf{x}$$
$$\nabla^{2} \phi = 0$$

### **Boundary Conditions**

$$\begin{array}{l} \frac{\partial \phi}{\partial n} = -\mathbf{V} \cdot \mathbf{n}, \ S_B \\ p_u - p_l = 0, \ S_W \\ \frac{\partial \phi_u}{\partial n} - \frac{\partial \phi_l}{\partial n} = 0, \ S_W \end{array}$$



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Boundary Integral Equation

### Boundary Integral Equation (BIE)



2<sup>nd</sup> Green's identity & kinematic bc's yield:

$$2\pi\phi(\mathbf{P}) - \int_{S_B} \phi(\mathbf{Q}) \frac{\partial G(\mathbf{P}, \mathbf{Q})}{\partial n} dS - \int_{S_W} \Delta\phi(\mathbf{Q}) \frac{\partial G(\mathbf{P}, \mathbf{Q})}{\partial n} dS$$
$$= \int_{S_B} (\mathbf{V}_{\infty} \cdot \mathbf{n}) G(\mathbf{P}, \mathbf{Q}) dS, \quad \mathbf{P} \in S_H \cup S_B \setminus TE,$$

- **3**D Laplace basic singularity:  $G(\mathbf{P}, \mathbf{Q}) = \frac{1}{4\pi}r^{-1}(\mathbf{P}, \mathbf{Q})$
- r: distance between P and Q
- $\phi(\mathbf{P})$ : potential on boundary surface
- $\Delta \phi = \phi_u \phi_l$ : potential jump on wake
- $TE = S_B \cap S_W$ : wing trailing edge from which wake emanates

#### Kutta condition

$$|\nabla \phi(\mathbf{P})| < \infty, \quad \mathbf{P} \in TE$$

Wake Conditions

### Wake Conditions





#### Potential Jump on Wake

•  $\Delta \phi(\mathbf{Q})|_{S_W} =$   $\Delta \phi(s_1, s_2)|_{S_W} =$   $\Delta \phi(s_1, s_2)|_{S_W \cap TE} :=$   $\widehat{\Delta \phi}(s_2)$ •  $\widehat{\Delta \phi}(s_2) =$  $\Delta \phi(\xi|_{S_B \cap TE}, \eta)$ 

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└─ Isogeometric Boundary Element Method

### Isogeometric Boundary Element Method



Body represented by  $N_P$  bicubic T-spline surfaces (multi-patch):  $S_{B_l} = \bigcup_{e=1}^{n_{B_l}} S_{e,B_l}, \ l = 1, ..., N_P$ 

Wake represented by a single T-spline surface:  $S_W = \bigcup_{e=1}^{n_W} S_{e,W}$ :

$$\widetilde{\mathbf{x}}^{e,m}(\widetilde{\boldsymbol{\xi}}) = \sum_{\alpha=1}^{n_{\alpha}} \mathbf{d}_{\alpha}^{e,m} R_{\alpha}^{e,m}(\widetilde{\boldsymbol{\xi}}) \quad m = B_{l}, W$$

$$\phi(\mathbf{P}^{l}) = \sum_{i=1}^{n_{A,l}} \phi_{i}^{l} \widetilde{R}_{i}^{l}(\mathbf{P}^{l}), \quad \mathbf{P}^{l} \in S_{e,B_{l}}$$

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└─ Isogeometric Boundary Element Method



### Isogeometric Boundary Element Method

The potential jump  $\Delta \phi(\mathbf{Q})$  on the trailing edge of the wing is approximated by using the basis of the trailing edge curve

$$\Delta\phi(\mathbf{Q}) = \Delta\phi(\xi|_{S_B\cap TE}, \eta) = \sum_{i=1}^{n_W} \Delta\phi_i R_i^1(\xi_{TE}, \eta)$$

Isogeometric Boundary Element Method

### Discrete BIE



$$2\pi \sum_{i=1}^{n_{A,i}} \phi_i^l R_i^l(\mathbf{P}_j^l) - \sum_{q=1}^{N_P} \sum_{i=1}^{n_{A,q}} \phi_i^q \sum_{e=1}^{n_{e,q}} \int_{S_e} R_i^q(\mathbf{Q}) \frac{\partial G(\mathbf{P}_j^l, \mathbf{Q})}{\partial n(\mathbf{Q})} dS(\mathbf{Q})$$
$$- \sum_{i=1}^{n_W} \Delta \phi_i \int_{\eta_1}^{\eta_2} R_i^1(\xi_{TE}, \eta) \int_{\xi_{TE,w}}^{\xi_{\infty}} \frac{\partial G(\mathbf{P}_j^l, \mathbf{Q})}{\partial n(\mathbf{Q})} dS(\mathbf{Q})$$
$$= \sum_{q=1}^{N_P} \sum_{e=1}^{n_{e,q}} \int_{S_e} \mathbf{V}_{\infty} \cdot \mathbf{n}(\mathbf{Q}) G(\mathbf{P}_j^l, \mathbf{Q}) dS(\mathbf{Q})$$
$$j = 1, ..., n_{A,l}, \quad l = 1, ..., N_P$$

■ **P**<sub>j</sub>: Collocation points based on the generalisation of Greville abscissae (Scott et al. 2013).

└─ Isogeometric Boundary Element Method

### IGA-Enhanced Kutta Condition



Zero-pressure jump along the trailing edge (Kutta Condition) on  $n_W$  points:

$$\Delta p(\xi_{TE,u}, \xi_{TE,l}, \eta_j) = 0, \quad j = 1, ..., n_W$$

leads to quadratic system:

$$\mathcal{P}_{j(l)}(\Phi) = 0,$$
  

$$j(l) = 1, \dots, n_{A,l} \quad l = 1, \dots, N_P + 1, \quad j(N_P + 1) = 1, \dots, n_W$$
  

$$\Phi = (\phi_1^1, \dots, \phi_{n_{A,1}}, \dots, \phi_1^{N_P}, \dots, \phi_{n_{A,N_P}}^{N_P}, \Delta\phi_1, \dots, \Delta\phi_{n_W})^T$$

solved numerically by applying an iterative Newton-Raphson scheme.

└─ Isogeometric Boundary Element Method



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### Morino Kutta Condition

$$\Delta\phi(\xi_{TE},\eta) = \sum_{i=1}^{n_A} \phi_i^{TE}((\tilde{R}_i(\xi_{u,TE},\eta) - \tilde{R}_i(\xi_{l,TE},\eta))$$

- Potential jump equal to difference between upper and lower potential values on TE
- Essentially a 2D condition
- Used as N-R initial approximation

└─ Isogeometric Boundary Element Method

### Morino Kutta Condition



#### Linear system:



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└─ Isogeometric Boundary Element Method



### Morino Kutta Condition

Then the unknown  $\Delta \phi_i^0$ s can be found by solving the following linear system:

$$\sum_{i=1}^{n_{W}} \Delta \phi_{i}^{0} R_{i}(\xi_{TE}, \eta_{j}) = \sum_{i=1}^{n_{A}} \phi_{i}^{0}(\tilde{R}_{i}(\xi_{u, TE}, \eta_{j}) - \tilde{R}_{i}(\xi_{l, TE}, \eta_{j}))$$
$$j = 1, ..., n_{W}$$

and the zero-th iteration solution vector is given by:

$$\Phi^{0} = (\phi_{1}^{1,0}, \dots, \phi_{n_{A,1}}^{1,0}, \dots, \phi_{1}^{N_{P},0}, \dots, \phi_{n_{A,N_{P}}}^{N_{P},0}, \Delta\phi_{1}^{0}, \dots, \Delta\phi_{n_{W}}^{0})^{T}$$

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LIsogeometric Boundary Element Method

### Evaluation of Singular Integrals



- Far field case: P<sub>j</sub> and Q not on the same element and d(P<sub>j</sub>, x̃<sup>e</sup>) > 2diag(x<sup>e</sup>) → Gauss - Kronrod
- Near field case: P<sub>j</sub> and Q not on the same element and d(P<sub>j</sub>, x̃<sup>e</sup>) < 2diag(x<sup>e</sup>) → Telles transformation
- In field case:  $\mathbf{P}_j$  and  $\mathbf{Q}$  on the same element $\rightarrow \epsilon$  region cut-off



└─ Isogeometric Boundary Element Method





### **Evaluation of Singular Integrals**

Linear transformation of variables:

$$\int_{t_{2A}}^{t_{2B}} \int_{t_{1A}}^{t_{1B}} \mathbf{f}(t_1, t_2) dt_1 dt_2 = \int_{-1}^{1} \int_{-1}^{1} \mathbf{f}_*(\xi_1, \xi_2) d\xi_1 d\xi_2, \quad \mathbf{f}_* = \mid d\mathbf{t}/d\xi \mid \mathbf{f}$$

Non-linear Transformation (Telles and Oliveira 1994):  $\xi_k(s_k) = \alpha_k s_k^3 + b_k s_k^2 + c_k s_k + d_k, \quad k = 1, 2$  leads to:

$$\int_{-1}^{1}\int_{-1}^{1}\mathbf{f}_{*}(\xi_{1}(s_{1}),\xi_{2}(s_{2}))(9\alpha_{1}\alpha_{2}(s_{1}-s_{1}^{P})^{2}(s_{2}-s_{2}^{P})^{2})ds_{1}ds_{2}$$

Application

### Application - Rectangular Wing



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NACA 0012 profile -  $6.75^{\circ}$ 



Wing (308 DoFs), wake (128 DoFs) and cap (86 DoFs) - 6meter span

Application

### Application - Rectangular Wing





Application

### Sectional Pressure Coefficients





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Application

### Sectional Pressure Coefficients





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Application

### Sectional Pressure Coefficients





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Conclusions and Future work

### Conclusions and Future work



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Conclusions:

- Good agreement with experimental results along most of the span
- Significant deviation very close to the tip
- Kutta condtion satisfied all along the span

Future Work:

- Investigation of tip behaviour
- Tests with complex wing geometries (cambered etc.) and/or fuselage

Conclusions and Future work





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Conclusions and Future work

## The End

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