

1 **USING ARTIFICIAL NEURAL NETWORK TO PREDICT THE FRACTURE PROPERTIES**
2 **OF THE INTERFACIAL TRANSITION ZONE OF CONCRETE AT THE MESOSCALE**

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9
10 **Abstract**

11 Concrete is a multi-phase heterogeneous material in which the interfacial transition zone (ITZ) between
12 aggregates and mortar significantly affects the cracking behaviour of concrete, especially under tensile
13 load. In this paper, the artificial neural network (ANN) method is applied in predicting the fracture
14 properties of ITZ in concrete. To form the data pool for the training of the ANN, a large number of two-
15 dimensional (2D) meso-scale fracture simulation of concrete under direct tensile load is conducted.
16 Cohesive crack elements are used in simulating arbitrary cracking in the ITZ and mortar. After the
17 verification of the trained ANN model, the tensile strength and fracture energy of the concrete ITZ are
18 predicted by using the RILEM direct tensile test results, i.e., stress–displacement curve, as the input for
19 the ANN. It has been found that, the trained ANN performs well in predicting the ITZ properties and
20 the computed stress–displacement curve together with the optimized ITZ fracture parameters has a good
21 agreement with that from the RILEM test results. The randomness of aggregates has little effect on the
22 predicted ITZ tensile strength while it becomes slightly bigger on the predicted ITZ fracture energy.
23 The tensile strength ratio of ITZ to mortar are calculated 0.38-0.47 and the fracture energy ratio of ITZ
24 to mortar are 0.18-0.58. These inversely predicted fracture properties of concrete ITZ can be useful
25 complementation to the existing dataset and 2D fracture simulation of concrete structures.

26
27 **Keywords:** interfacial transition zone (ITZ); cohesive elements; fracture energy; inverse analysis;
28 artificial neural network.

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30 1. Introduction

31 As the most widely used construction material worldwide, concrete has attracted considerable
32 research interest in the past few decades particularly for improved sustainability, enhanced
33 strength and prolonged service life. To better understand the concrete properties and develop
34 new concretes [1-4] to satisfy the pressing demands from the changing environment, the meso-
35 scale structure of concrete and their relationship with the exhibited engineering properties
36 becomes a key. At the meso-scale, concrete is made of multi-phase material components and
37 the interfacial transition zone (ITZ) between the aggregates and the (mortar) matrix is normally
38 the weakest part in such a composite [5-7]. Therefore, the mechanical behaviour, especially the
39 fracture properties, of the ITZ in concrete is important in predicting the concrete performance.

40

41 The size of fracture process zone (FPZ) during concrete cracking is not small enough for
42 negligible so concrete is normally considered as a quasi-brittle material. Hillerborg et al. [8]
43 proposed the cohesive crack model to characterize the behaviour of a finite-size FPZ, which
44 has developed to become one of the most robust fracture models for concrete. There are two
45 independent parameters in the cohesive law: the tensile strength and fracture energy. So far,
46 lots of researches have been carried out to measure the strength and fracture energy of concrete
47 by experiments [9, 10]. In particular, several methods including three-point bending test [11],
48 compact tension test [12], wedge splitting test [13] and uniaxial tensile test [14], have been
49 proposed to determine the strength and fracture energy for concrete. Amongst the proposed
50 methods, the uniaxial tensile test is the direct and most accurate method for obtaining the
51 stress–displacement (of notch) relation which represents the true uniaxial mechanical
52 behaviour compared to others [9]. However, it should also be mentioned that, most
53 experimental and theoretical work were focused on Mode I fracture while studies on Mode II
54 fracture properties have not been very clearly understood yet. It is even questionable that Mode

55 II fracture energy obtained from the test is the real material property [15]. The argument is
56 related to the fact that creating a pure Mode II fracture for quasi-brittle materials in experiment
57 is extremely challenging [10].

58

59 Compared with other the aggregates and cement mortar, the fracture properties of ITZ are much
60 more difficult to be tested. Rao and Prasad [16] designed notched rock-mortar specimens by
61 casting fresh mortar on the rock surface and found that the tensile strength of interface between
62 the rock and mortar was 1/16 – 1/3.5 times of that of mortar. Gu et al. [17, 18] tested the
63 bonding strength of the ITZ and found the bonding strength was about 50% of the tensile
64 strength of the mortar. Dong et al. [19] carried out the three-point bending test for a concrete-
65 rock beam with the interface located at the geometric centre; they obtained the tensile strength
66 and fracture energy of ITZ which were 1.37 MPa and 19.3 N/m, respectively. Meanwhile, the
67 ITZ properties are closely related to the processing and manufacturing of concrete including
68 mixing, transportation, compaction, etc. Moreover, by nano-indentation test, Xiao et al. [5]
69 obtained the elastic modulus and hardness of ITZ in concrete and found that the hardness value
70 for ITZ were about 80% - 85% of that for mortar. However, it should also be noted that the
71 nano-indentation results on ITZ properties are at different length scale to above mentioned
72 meso-scale ITZ tests and they may not be directly comparable.

73

74 In the past decade, some researchers proposed to model concrete arbitrary cracking by inserting
75 zero-thickness cohesive elements into the mesh of multi-phase concrete [6, 7, 20-26]. The
76 meso-scale modelling based on cohesive elements provides an effective approach to investigate
77 the toughening fracture mechanism of concrete cracking, such as aggregate bridging, void
78 formation, or microcrack shielding. Yang et al. [6, 21, 22] modelled concrete fracture under
79 the uniaxial tensile test in 2D as a heterogeneous material by inserting cohesive elements and

80 the heterogeneity was achieved by random aggregates distribution [6, 22] or random elements
81 properties [21]. Further, Ren et al. [7] obtained more realistic concrete meso-structures through
82 X-ray computed tomography scanning and carried out 2D uniaxial tensile simulations by the
83 imaged based mesh with cohesive elements. They found that the micro cracks were always
84 initiated at the ITZ before connected to form the macro cracks and the overall stress-
85 displacement relationship of concrete was mainly determined by ITZ fracture properties.
86 Recently, Ren et al. [27] and Trawiński et al. [26] established 3D numerical model using
87 cohesive elements based on X-CT scanning results of concrete specimen and modelled the
88 concrete cracking under direct uniaxial loading. Their researches revealed that 3D modelling
89 would be a very powerful tool to unveil the damage and failure mechanisms in a more realistic
90 way. However, 3D simulations for concrete fracture at meso-scale level, due to the highly
91 nonlinear equation system and the softening-induced instabilities, are very time-consuming
92 [26]. The limitation on computing efficiency brings great challenges in the widespread
93 application of 3D meso-scale fracture models especially when a large number of simulations
94 are necessary.

95

96 Trial and error is usually used to estimate the ITZ properties for application in the meso-scale
97 simulation of concrete cracking. However, this method cannot always yield accurate and
98 reliable results. Instead, inverse analysis method has been widely employed to determine the
99 mechanical parameters of materials and structures, such as rock creep parameter [28], residual
100 stress by wilding [29] and overall fracture properties of composites [28, 30, 31]. Recently the
101 application of artificial intelligence in civil engineering has proved powerful and has potential
102 to solve new problems. In light of the fracture properties of the concrete ITZ, given the
103 difficulties in the experimentation, an inverse method based on artificial neural network would
104 be a promising solution.

105

106 This paper aims to use the artificial neural network (ANN) in the prediction of the fracture
107 properties of ITZ in concrete. Concrete is considered as a heterogeneous material at the meso-
108 scale, consisting of polygonal aggregates, mortar and ITZ. A multi-phase fracture model
109 involving cohesive elements is established and the uniaxial direct tensile test from RILEM is
110 employed and reproduced in the finite element simulation. A large number of simulations are
111 conducted with prior known values of ITZ tensile strength and fracture energy to form the data
112 pool to train the ANN. After the training and validation of the ANN, the real ITZ tensile
113 strength and fracture energy are inversely attained, against the RILEM test results. A
114 parametric study focusing on some underlying factors that may influence the accuracy of the
115 ANN prediction on the fracture properties of ITZ in concrete is carried out.

116

117 **2. Meso-scale fracture model for concrete**

118 A meso-scale structure for concrete is firstly developed by randomly generating and packing
119 aggregates. Although realistically aggregates should have rough edges, it is almost impossible
120 to mesh the aggregates with extremely irregular edges in finite element modelling [7, 17]. We
121 simplified the aggregate shape as the polygon with a random size and 4 to 13 sides. An
122 aggregate in a regular polygon (Figure 1a) is generated with random sides in 4 - 13 and a
123 random size in a specified grading range. To change the regular polygon to irregular one, the
124 vertex of the regular polygon will be randomly moved to/away from the centre and then rotated
125 between the adjacent vertices (Figure 1b and 1c).

126

127 Once the meso-structure of concrete is generated and meshed, cohesive elements are embedded
128 into the boundaries of the mesh. The ITZ and mortar matrix have cohesive elements inserted
129 to approximately simulate arbitrary cracking but the material properties of the cohesive

130 elements are defined separately for these two phases. The mechanical properties of aggregates
131 are considerably stronger than mortar and the ITZ excluding the ultra-high performance
132 concrete (UHPC). In this study, the fracture of aggregates is not simulated and the ITZ is
133 assumed as zero thickness interface. More details on the insertion process of cohesive elements
134 has been introduced in the authors' previous study [32]. Figure 2 shows the concrete model
135 consisting of solid elements for the aggregates and mortar, and cohesive elements in the mortar
136 and the interfaces. The mesh size is 1 mm for the worked example and we will discuss the mesh
137 dependency later.

138

139 Normally, a traction–separation law is used as the constitutive model for the zero-thickness
140 cohesive elements [7]. The calculation thickness for the cohesive elements is 1 so the element
141 strain is replaced by the relatively displacement of the crack face. The traction stress of
142 cohesive elements is a function of the corresponding relative displacements of the crack surface.
143 In general, the traction–separation laws for the cracks can be expressed as follows:

$$144 \quad \sigma_n = f(\delta_n) \quad (1)$$

$$145 \quad \sigma_s = f(\delta_s) \quad (2)$$

146 where σ_n and σ_s are the normal and shear traction stress, respectively. δ_n and δ_s are the
147 corresponding opening displacement and slipping displacement, respectively; f is the function
148 describing the traction and separation relationship.

149

150 For a cohesive crack, the traction stresses will linearly increase to the peak strength by a penalty
151 stiffness and then gradually decrease to zero. The traction–separation relationship for the
152 opening and shearing in the linearly elasticity stage can be expressed as follows:

$$153 \quad \sigma_n = K_n \langle \delta_n \rangle \quad (3)$$

$$154 \quad \sigma_s = K_s \delta_s \quad (4)$$

155 where $\langle \rangle$ is the Macaulay bracket which equals zero if the value of normal displacement is
156 smaller than zero (i.e., compression). The K_n and K_s are the penalty stiffness at the normal and
157 shear directions, respectively. Penalty stiffness is a numerical parameter to control the
158 deformation of the zero-thickness cohesive element.

159

160 Figure 3 illustrates the constitutive relationship for the cohesive crack with an exponential post-
161 peak softening behaviour. The area under the traction-separation curve is the corresponding
162 fracture energy. It should be mentioned that, the softening behaviour can be in a linear, bilinear
163 even any pre-defined shape. The damage initiation will occur when the critical displacement
164 satisfies the following equation:

$$165 \quad \left(\frac{\sigma_n}{\sigma_n^0}\right)^2 + \left(\frac{\sigma_s}{\sigma_s^0}\right)^2 = 1 \quad (5)$$

166

167 where σ_n^0 and σ_s^0 are the tensile strength and shear strength of the cohesive crack, respectively.
168 It should be mentioned that the experimental data on the shear fracture properties are very
169 limited [7]. Although some researches considered the shear strength was larger than tensile
170 strength and proposed to use the ratio of shear strength to tensile strength to model concrete
171 cracking, the ratio was randomly assumed and not verified by experiments [20, 34]. Moreover,
172 there is even a doubt whether shear fracture energy is a material property [15, 20]. For uniaxial
173 direct tensile test, tensile fracture is the main failure type. As such, Mode I fracture properties
174 are considered as most significant parameters in the simulations and the parameters for Mode
175 II fracture are assumed to be the same as those for Mode I fracture according to existing studies
176 on tensile fracture modelling of meso-scale concrete [21, 24, 26, 35].

177

178 An effective displacement coupling normal and shear separation is proposed to calculate the
179 damage evolution:

180
$$\delta = \sqrt{\langle \delta_n \rangle^2 + (\delta_s)^2} \quad (6)$$

181 where δ is the effective displacement.

182

183 Further, the damage value under the exponential damage curve can be calculated as follows

184 [24]:

185
$$D = 1 - \left(\frac{\delta_0}{\delta_m}\right) \left\{ 1 - \frac{1 - \exp\left(-\alpha\left(\frac{\delta_m - \delta_0}{\delta_f - \delta_0}\right)\right)}{1 - \exp(-\alpha)} \right\} \quad (7)$$

186 where δ_0 is the critical displacement when the stress reaches the peak strength (i.e., $D=0$); Due

187 to the same value of tensile and shear strength, the critical displacements for the pure tensile,

188 pure shear and mixed-mode cracking become the same (the inner circle in Figure 3). δ_m is the

189 maximum effective displacement during the loading history; δ_f is the completely failure

190 displacement which is the same for the pure tensile, pure shear and mixed-mode cracking (i.e.,

191 the outer circle in Figure 3). α is a softening parameter representing the damage evolution rate.

192

193 Thus, the post-peak traction stresses can be expressed as follows:

194
$$\sigma_n = (1 - D)K_n \langle \delta_n \rangle \quad (8)$$

195
$$\sigma_s = (1 - D)K_s \delta_s \quad (9)$$

196 It should be mentioned that, D is the stiffness damage value while not the strength damage

197 value. Once the cohesive strength σ_0 , failure displacement δ_f and the softening parameter α

198 are determined, the fracture energy (i.e., the area under the softening curve) can be obtained as

199 follows:

200
$$G_f = \int_0^{\delta_f} f(\delta) \delta \quad (10)$$

201 For quasi-static simulations by implicit analysis programs, a small value of viscosity can be

202 introduced to help convergence, making the stiffness matrix positive definite. The viscosity

203 regularizes the constitutive relationship of the cohesive element by modifying the damage
204 value D to D_v as follows:

$$205 \quad \dot{D}_v = (D - D_v)/\mu \quad (11)$$

206 where D_v is the viscous damage variable for regularization of the constitutive equations. \dot{D}_v is
207 the derivative of viscous stiffness degradation variable with respect to time; μ is the viscosity
208 parameter which should be sufficiently small to improve the rate of convergence without
209 compromising results. When viscosity is introduced to the model, D is not applicable any more
210 while D_v becomes effective. The material stiffness matrix is then modified.

211

212 **3. Direct tensile test on fracture properties of concrete**

213 RILEM [11, 14] recommended a closed-loop uniaxial tensile test method to obtain the stress–
214 displacement relationship which describes the overall fracture behaviour for concrete. The
215 experimental data on RILEM round-robin tests [11, 14] is used to validate the developed
216 numerical method and the starting point for the inverse analysis. In the round-robin tests, the
217 mix proportion by weight for concrete was 1:2:2.5:0.56 in terms of cement, fine aggregate,
218 coarse aggregate and water respectively. In addition, 10 mm single-sized coarse aggregates
219 were used. The coarse aggregates were defined as aggregates with size larger than 2.36 mm
220 according to British Standard 882 [36]. To reduce the complexity of the mesh, only coarse
221 aggregates larger than 2.36 mm are modelled in this study, while fine aggregates and cement
222 are treated as mortar phase [22]. The total area fraction of coarse aggregates can be calculated
223 by the weight mix proportion and materials densities as follows:

$$224 \quad P_a = \frac{P_w/\rho_{agg}}{\rho_{con}} \quad (12)$$

225 where P_a is the area/mass percentage of the coarse aggregates in the total. P_w is the percentage
226 by weight of the coarse aggregates in the total, which is about 0.41 according to the mix

227 proportion by weight in their experiments [11, 14]. ρ_{agg} and ρ_{con} are the density of the coarse
228 aggregate (limestone) and the normal concrete, respectively. The values of density for
229 limestone and normal concrete are about 2400 kg/m³ and 2700 kg/m³, respectively [37]. The
230 calculated area fraction of the coarse aggregates is about 36.7% by Equation (12). More details
231 on the experiments can be found in the references [11, 14].

232

233 A 2D concrete model with the same size of the experimental sample is developed. The model
234 dimensions are 100 mm×150 mm and two notches are created with width 2 mm and depth 10
235 mm in the middle of the model. Figure 2 shows the typical mesh with element size 1 mm. Table
236 2 lists the values for the geometric and mechanical parameters and their sources. Yang et al.
237 [7] have found that the interfacial cohesive strength and fracture energy are the dominant
238 factors governing the fracture process of concrete. Rao et al. [38] investigated the relationship
239 between the mortar splitting tensile strength and the water/cement ratio and generalized the
240 Abrams' law for predicting the tensile strength of mortar. In Rao's experiments, the mortar
241 tensile strength changes from 1.76 to 2.66 MPa when the water/cement ratio decreases from
242 0.65 to 0.3. According to Abrams' generalization law, the mortar strength for the water/cement
243 ratio 0.56 was estimated as 2.2 MPa [38]. Further, the fracture energy of the mortar was
244 predicted as 72N/m according to Rao's experimental data on mortar fracture energy [16].
245 Moreover, a parametric study of a realistic range of tensile strength and fracture energy of
246 mortar on the fracture behaviour of the concrete sample in this research will be carried out. The
247 damage evolution rate parameter α is obtained by fitting the Equations (7) and (8) with RILEM
248 data [11, 14]. The tensile strength and fracture energy of ITZ are regarded as targets which will
249 be inversely determined. The effects of mortar strength and fracture energy on the inverse
250 analysis will be investigated by parametric studies later.

251

252 The top and bottom surfaces of the specimen for experiments were tied to the loading plates
253 by stiff glue [11]. For the direct uniaxial tension modelling, the frictional and rotational effects
254 were considered minor and the tensile displacements (y direction) were directly applied to top
255 and bottom nodes. The average stress of the model is obtained by dividing the reaction forces
256 by the net cross section area. The crack width w is obtained from the average value of the
257 separating displacements of the two notches.

258

259 **4. Establishing the artificial neural network and the inverse analysis**

260 The artificial neural network (ANN) has been widely employed for learning, predictions and
261 making decisions based on data. There are three basic datasets for the ANN model: training,
262 testing and validation datasets. First, training dataset is used to fit the model. Then testing
263 dataset is used to provide an unbiased evaluation of a final model fit on the training dataset.
264 The validation is to evaluate a given model by a dataset [39]. The inverse analysis method
265 based on ANN for determining the ITZ fracture properties of concrete is as follows: First, a
266 known solution for the overall fracture behaviour (i.e., the whole stress-crack width
267 relationship) should be obtained with a high reliability and accuracy. Then, a meso-scale
268 concrete model consisting of aggregates, mortar and ITZ should be developed. This model is
269 able to obtain the overall structural performance and the whole stress-crack width curve of the
270 concrete by assigning different material properties to different phases. We select the tensile
271 strength and fracture energy of ITZ as the target variables and the other material parameters
272 are treated as constants. Numerical simulations with a number of initial values for the tensile
273 strength and fracture properties of ITZ are conducted. Accordingly, the stress-crack width
274 curves from the simulations can be obtained. For establish the ANN, the initial values for the
275 tensile strength and fracture energy of ITZ are used as input data and the stress-crack width
276 curves from the corresponding simulations are output data. These input and output data are

277 randomly divided into training, testing and validation dataset. Then an objective function for
278 calculating the error between the computed outputs and experimental stress-crack width curve
279 is created in the ANN. For a given output value (i.e., the overall stress-crack width curve), an
280 optimization algorithm is used to find optimized ITZ values which make the objective function
281 minimum. Further, the computed stress-crack width curve with optimized values will be
282 compared with experimental results. Then, the error between the numerical and experimental
283 results are calculated. If the error falls below a threshold value, i.e., negligibly small, the ITZ
284 values are determined and the inverse analysis processes are accomplished. If the error is over
285 the threshold value, the current numerical results will be added to re-train the network and
286 inverse the targeted ITZ fracture properties. However, it is likely that the errors cannot be
287 reduced even after lots of iterations. In this case, the retraining and inverse analysis will be
288 forced to quit and the ITZ properties will be determined by the final inverse analysis with the
289 corresponding error. The maximum iterations for retraining is set as 10 in this study.

290

291 RILEM uniaxial direct tensile test [14] obtained the whole stress-crack width curve of concrete
292 which is chosen as the known solution. The developed meso-scale fracture model for concrete
293 is used to generate the input and output data for establishing the ANN. The uniform design
294 which uniformly scatters the design points in the domain range is employed for choosing the
295 initial values for the ITZ tensile strength and failure displacement. Figure 4 illustrates the 20
296 sets of input values for ITZ fracture properties according to the previous studies on ITZ
297 properties [5, 16-19]. The initial ITZ values and their corresponding stress-crack width curves
298 from simulations are then used as the ANN training, testing and validation input and output
299 data, respectively. The ANN is established in Matlab and the output for the stress-crack width
300 curve is read by a Matlab open-source application [40]. It should be mentioned that, the stress-
301 crack width curves from simulations and experiments are represented by 40 discrete points

302 which are linearly spaced to train the ANN. Figure 5 shows the computed stress-crack width
303 curves. An objective function considering both the errors of peak point and all the 40 points at
304 the stress-crack width curve is designed as follows:

$$305 \quad \text{Fit} = \min \sum_{i=1}^{40} \left\{ \frac{[\max(y_i) - \max(x_i)]^2}{[\max(x_i)]^2} + \frac{(y_i - x_i)^2}{[\text{sum}(x_i)]^2} \right\} \quad (13)$$

306 where y_i and x_i are the stresses for the i^{th} point from the network and the experiment,
307 respectively; The $\max(y_i)$ and $\max(x_i)$ are the maximum stresses (i.e., tensile strength) from the
308 network and the experiment, respectively.

309

310 Back-propagation (BP) algorithm is used to train the network. In this method, the error
311 calculated at the output of the network is propagated back through the layers of neurons to
312 update the weights [39]. The network contains 8 hidden layers and the account for training,
313 validation and testing dataset 80%, 10% and 10%, respectively. Figure 6(a)-(d) show the linear
314 regression of network outputs with respect to targets for training, validation, testing and all sets.
315 The targets are the values of simulated stress at the 40 points from simulations while the outputs
316 are the values of stress at the 40 points predicted from the network. The R values for all the
317 datasets are larger than 0.99, which means the fit is very good and the output tracks the targets
318 very well for all datasets. Figure 7 shows the variations of Mean Squared Error of the outputs
319 for the learning and testing sets plotted against different number of epochs. The error quickly
320 decreases to smaller than 0.001 with epochs increasing and the errors of testing and validation
321 sets have similar characteristics. Moreover, overfitting does not occur because neither testing
322 nor validation error increased before epoch 32. Therefore, the established ANN can well predict
323 the target variables.

324

325 The optimized tensile strength and fracture energy for concrete ITZ are 1.02 MPa and 28.9
326 N/m, respectively. Figure 8 shows the stress-crack width curves from both the numerical model

327 with the optimized ITZ fracture properties and the RILEM experiment [14]. The computed
328 stress-crack width curve has a good agreement with that from RILEM experiment. The error
329 between the two curves by Equation (13) is 1.8%. Therefore, the ITZ tensile strength and
330 fracture energy can be well predicted by the ANN. The ratio of ITZ tensile strength to mortar
331 tensile strength is about 0.46 time and the fracture energy of ITZ is about 0.4 time of the fracture
332 energy of the mortar.

333

334 **5. Parametric study and discussion**

335 The aggregates in the heterogeneous concrete model are randomly generated and packed.
336 Therefore, the heterogeneity of concrete will affect the concrete cracking. Figure 9 illustrates
337 the effect of concrete heterogeneity on the stress-displacement curves by 10 random
338 heterogeneous models which use the same materials mechanical parameters including the
339 optimized ITZ fracture properties. It can be seen that, the stress-displacement curves are very
340 close at the linear increase stage before the peak-stress and have slight differences at the
341 softening stage. Although the stress-displacement curve has a reasonable repeatability, the
342 variabilities may affect the values of optimized ITZ fracture properties. Further, based on the
343 same 20 sets of initial values for simulations and the inverse method, the ITZ fracture properties
344 for each heterogeneous model are determined. Table 2 shows the values of the optimized ITZ
345 tensile strength, fracture energy, iteration number and error. It can be found that, the tensile
346 strength varies from 0.96-1.03 MPa and the fracture energy varies from 13.1-28.9 N/m for
347 different heterogeneous models. Figure 10 illustrates the stress-displacement curves from
348 RILEM experiment and the numerical simulations with optimized ITZ fracture properties. The
349 error between the stress-displacement curves from the experiment and numerical simulation
350 varies from 0.6% to 3.1%, which proves the numerical model and inverse analysis method are
351 reliable. The mean value and coefficient of variation for the ITZ tensile strength are 1.00 MPa

352 and 2.8%, respectively. Therefore, the determined ITZ tensile strength is about 0.46 time of
353 the mortar strength. The mean value and coefficient of variation for the fracture energy of ITZ
354 are 20.9 N/m and 27%, respectively. The ratio of the ITZ fracture energy to mortar fracture
355 energy is about 0.18-0.40 with a relatively high degree of variability. The values obtained for
356 ITZ will be useful in the meso-scale modelling of concrete fracture; however, it may be noted
357 that more cases should be included in the inverse analysis by considering a variety of material
358 composition and geometric configuration. It will then give a range of values for ITZ properties
359 and the possible correlation to some underlying parameters. Figure 11 shows the typical crack
360 patterns for three heterogeneous models. It can be found that, the macro cracks are formed at
361 the middle of the specimen and the interfaces dominate the crack path. It is interesting to find
362 that, two macro cracks occur for model 9 where the cracks propagate from two notches. Due
363 to the distributions of aggregates and driving effects of ITZ, the left crack propagates to the top
364 of the right notch. Although the post-peak stress has decreased to about zero, the two macro
365 cracks have not completely connected.

366

367 As introduced in Equation (11), the viscosity is a numerical parameter to overcome the
368 convergence problem. Parametric studies are carried out to investigate the effect of viscosity
369 on the stress-displacement curve and crack pattern. Figure 12 illustrates the stress-displacement
370 curves for the heterogeneous model 1 with the viscosity values 1.0×10^{-5} , 5.0×10^{-5} and 1.0×10^{-4}
371 ⁴. It can be seen that, the smaller the viscosity is, the smaller the peak strength of concrete is.
372 A very small value of viscosity has little effect on the stress-displacement curve. However, the
373 increment steps for the simulations with the viscosity values 1.0×10^{-5} , 5.0×10^{-5} and 1.0×10^{-4}
374 are 1640, 624 and 432, respectively. The convergence can be significantly improved by a
375 relatively larger viscosity. Figure 13 shows the crack patterns of the heterogeneous model 1 for
376 different values of viscosity. It can be seen that, there is no difference in the crack patterns of

377 heterogeneous model 1 with the viscosity 1.0×10^{-5} , 5.0×10^{-5} and 1.0×10^{-4} . Therefore, the
378 viscosity in this study is determined as 5.0×10^{-5} for improving the convergence without
379 compromising results.

380

381 Although the mesh dependency has been reduced through replacing the strain by separation
382 displacement in the constitutive model of cohesive element, the crack patterns and overall
383 stress-displacement may also be mesh-dependent if the size ratio of fracture process zone to
384 cohesive element is not large enough. Figure 14 illustrates the stress-displacement curves for
385 the heterogeneous model 1 with element size 0.5 mm, 1 mm and 2 mm. It can be found that,
386 the stress-displacement curves are almost the same for the meshes with the three chosen
387 element sizes. The increment steps for the simulations with element size 0.5 mm, 1 mm and 2
388 mm are 3079, 624 and 764, respectively. Figure 15 shows the crack patterns for the
389 heterogeneous model 1 with the three element sizes. It can be seen that, the element size has
390 little effects on the crack patterns while the crack paths are slightly different for the three
391 element sizes. In consideration of calculation efficiency, the smaller the element size is, the
392 larger the degree of freedom of the mesh is and more CPUs time will be required for each
393 increment step. Therefore, the element size is set as 1 mm in this study.

394

395 It has been found that the ITZ fracture properties dominate the overall fracture of concrete for
396 uniaxial tensile tests [23, 27, 42]. However, it should be mentioned that the tensile strength and
397 fracture energy of the mortar in this study are estimated according to previous experiments [16,
398 38]. Therefore, the effects of mortar tensile strength and fracture energy on the inversed results
399 are investigated. The optimized values of tensile strength and fracture energy from the inverse
400 analysis of heterogeneous model 8 are listed in Table 3. It can be seen that, for the mortar
401 tensile strength varying from 1.9 to 2.5 MPa, the optimized ITZ tensile strength and fracture

402 energy change from 1.10-0.94 MPa and 31.9-22.5 N/m, respectively. The larger the mortar
403 strength is, the smaller the optimized ITZ tensile strength and fracture energy are. The mean
404 values of the optimized ITZ tensile strength and fracture energy are 1.05 MPa and 29.6 N/m,
405 respectively. In addition, the values for coefficient of variation of the optimized ITZ tensile
406 strength and fracture energy are 7.1% and 15.8%, respectively. Figure 16 shows the stress-
407 displacement curves from the inversed results with different mortar strengths and fracture
408 energies. It can be found that, the stress-displacement curves from the simulations have a good
409 agreement with that from experimental results. Figure 17 illustrates the crack pattern for the
410 heterogeneous model 8 with different mortar strengths and fracture energies. It can be seen that,
411 the crack patterns from the inversed results are almost the same.

412

413 **6. Conclusions**

414 This paper proposed a method to inversely determine the ITZ fracture properties of concrete
415 based on meso-scale concrete fracture model and artificial neural network. A three-phase
416 concrete model containing aggregate, mortar and ITZ was developed and zero-thickness
417 cohesive elements were used to simulate the cracking in the mortar and ITZ. RILEM direct
418 uniaxial tensile test was employed as the worked example to demonstrate the inverse method
419 and the benchmark to inversely determine the ITZ properties. A number of simulations with
420 initial ITZ fracture properties were carried out to obtain the stress-displacement curves which
421 was used for training the artificial neural network. Various factors have been considered in the
422 parametric study in confirming the robustness of the developed method. Specific conclusions
423 can be obtained as follows:

424 (1) The developed fracture model can reproduce the cracking phenomena (i.e.,
425 micro cracks initiation, crack deflection, bridging etc.) of concrete at meso-scale. The

426 established artificial neural network showed a good performance in optimizing the fracture
427 properties of ITZ by minimizing the objective function. The computed stress-crack width curve
428 with the optimized tensile strength and fracture energy of ITZ has a good agreement with that
429 from the RILEM experiment. The proposed method is robust and reliable on determining the
430 tensile strength and fracture energy of ITZ once the mortar and aggregate properties are
431 obtained.

432 (2) For 10 different heterogeneous models, the mean values and coefficients of
433 variance for ITZ tensile strength and fracture energy are 1.0 MPa and 2.8%, 20.9 N/m and 27%,
434 respectively. The randomness of aggregates has little effect on the optimized ITZ tensile
435 strength but slightly bigger effect on the optimized ITZ fracture energy.

436 (3) The larger the tensile strength of mortar is, the smaller the optimized ITZ
437 strength and fracture energy are. However, in the ranges of mortar strength (1.9-2.5 MPa) and
438 fracture energy (60-92 N/m), the values for coefficient of variation of the optimized ITZ tensile
439 strength and fracture energy are 7.1% and 15.8%, respectively. The optimized ITZ results
440 would be reliable according to the estimations of mortar fracture properties.

441 (4) The tensile strength ratio of ITZ to mortar are 0.38-0.47 and the fracture energy
442 ratio of ITZ to mortar are 0.18-0.58 according to the parametric study on aggregate randomness
443 and variety of mortar fracture properties. These ratios can well be used for meso-scale fracture
444 modelling of concrete. It should be noted, however, that these values were derived without the
445 consideration of more complex 3D mechanisms including aggregate distribution and the
446 heterogeneity out of the plane. Therefore, the accuracy of directly using these data in 3D meso-
447 scale fracture simulation of concrete is not verified.

448

449

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568 3. Optimized ITZ fracture properties for different values of mortar strength and fracture energy

569

Table 1 Mechanical parameters for different material phases of concrete

Description	Symbol	Values
Young's modulus of aggregate	E_{Agg}	80 GPa [24]
Young's modulus of mortar	E_{Mor}	23 GPa [24]
Poisson's ratio of aggregate	ν_{Agg}	0.16 [43]
Poisson's ratio of mortar	ν_{Mor}	0.22 [24]
Tensile strength of mortar	σ_{Mor}	2.2 MPa [16, 38]
Fracture energy of mortar	G_{Mor}	72 N/m [16, 38]
Failure displacement of mortar	$\delta_{f,\text{Mor}}$	0.23 mm
Evolution rate parameter	α	7 [11]
Tensile strength of ITZ	σ_{ITZ}	0.55 MPa
Fracture energy of ITZ	G_{ITZ}	11 N/m
Failure displacement of ITZ	$\delta_{f,\text{ITZ}}$	0.14 mm

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Table 2 Optimized ITZ fracture properties for different heterogeneous models

Random heterogeneous model	Tensile strength (MPa)	Fracture energy (N/m)	Strength ratio of ITZ to mortar	Fracture energy ratio of ITZ to mortar	Error
1	1.02	28.9	0.46	0.40	1.8%
2	0.98	18.7	0.45	0.26	0.8%
3	0.96	17.1	0.44	0.24	2.9%
4	1.01	21.2	0.46	0.29	1.8%
5	1.01	15.9	0.46	0.22	3.1%
6	1.03	24.1	0.47	0.33	2.6%
7	1.01	26.3	0.46	0.37	1.2%
8	1.03	28.1	0.47	0.39	0.6%
9	0.96	13.1	0.44	0.18	0.7%
10	0.97	15.7	0.44	0.22	1.9%
Mean	1.00	20.9			
CoV	2.8%	27%			

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575

576 Table 3 Optimized ITZ fracture properties for different values of mortar strength and fracture
 577 energy

Mortar Strength	Mortar fracture energy	ITZ Tensile strength	ITZ fracture energy	Strength ratio of ITZ to mortar	Fracture energy ratio of ITZ to mortar	Error
1.9 MPa	72 N/m	1.11 MPa	31.9 N/m	0.58	0.44	1.3%
2.2 MPa	72 N/m	1.03 MPa	28.1 N/m	0.47	0.39	0.6%
2.5 MPa	72 N/m	0.94 MPa	22.5 N/m	0.38	0.31	0.6%
2.2 MPa	60 N/m	1.06 MPa	35.0 N/m	0.48	0.58	3.6%
2.2 MPa	94 N/m	1.13 MPa	30.3 N/m	0.51	0.32	0.6%

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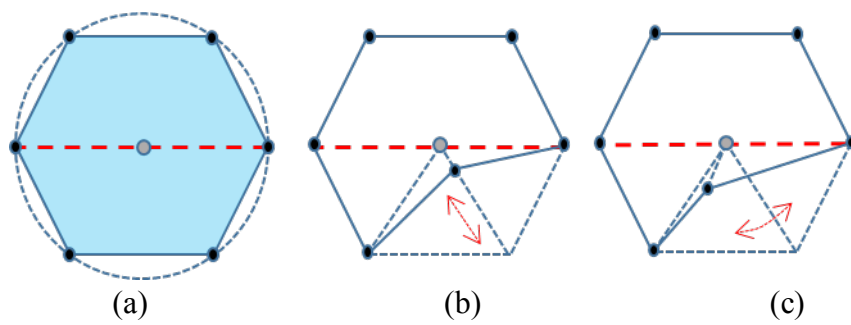
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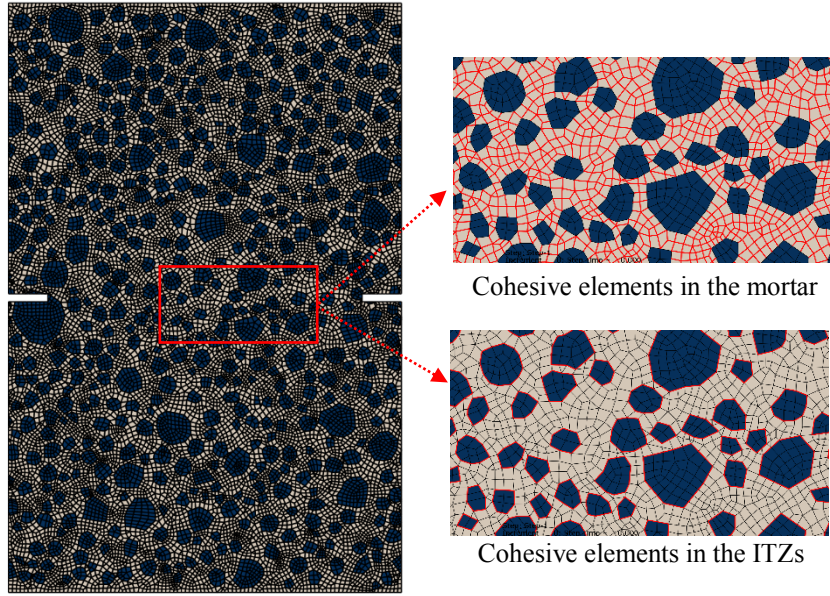
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606 Figure 1 Generation of the irregular polygon: (a) regular polygon; (b) moving vertex; (c)
607 rotating vertex
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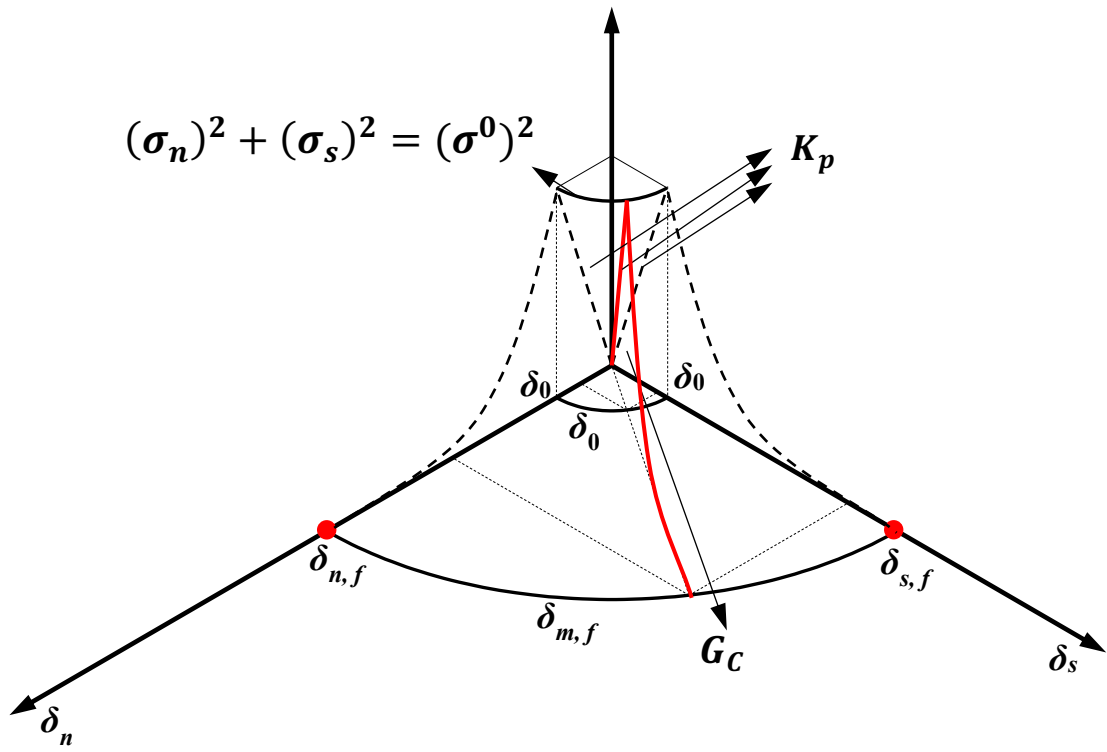


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Figure 2 Meso-scale concrete model with cohesive elements

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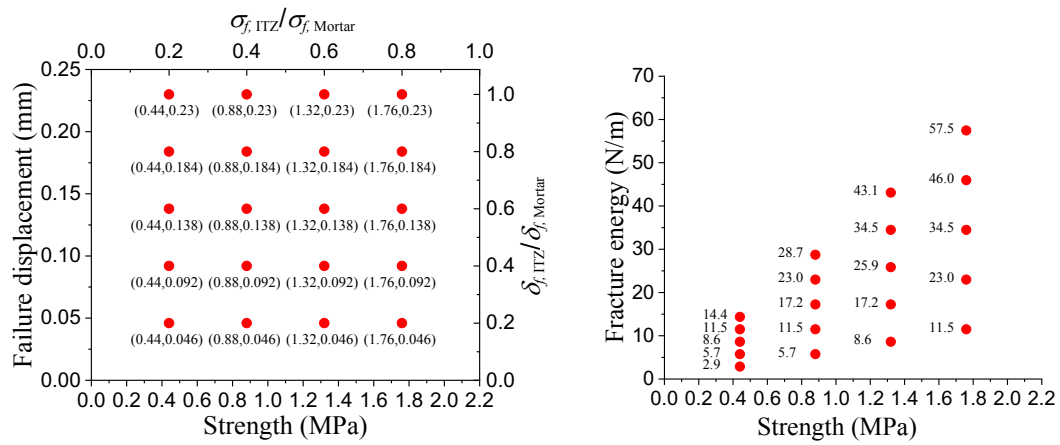
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Figure 3 Stress-displacement relationship for the cohesive element

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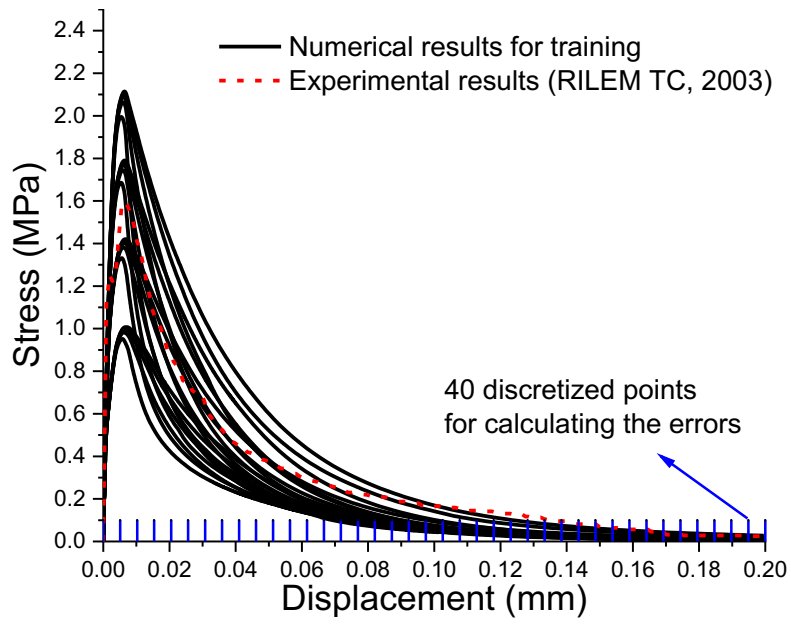
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618 Figure 4 The initial values for ITZ fracture properties in the simulations for training (a) the
619 strength and failure displacement; (b) the corresponding values of fracture energy

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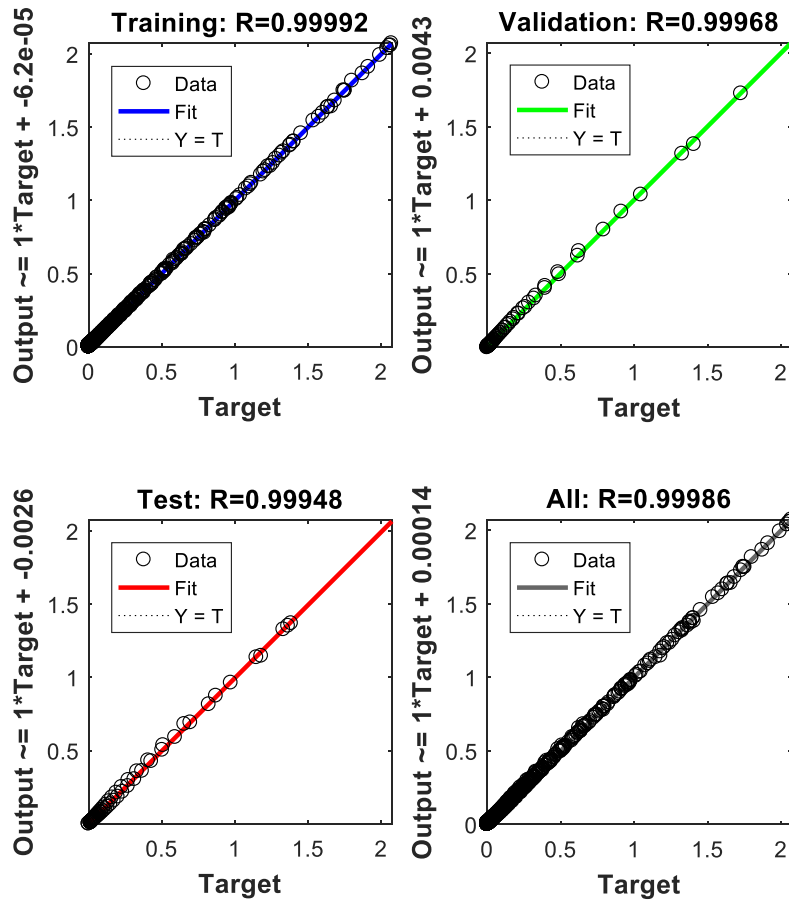


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Figure 5 Stress-displacement curves for training neural network

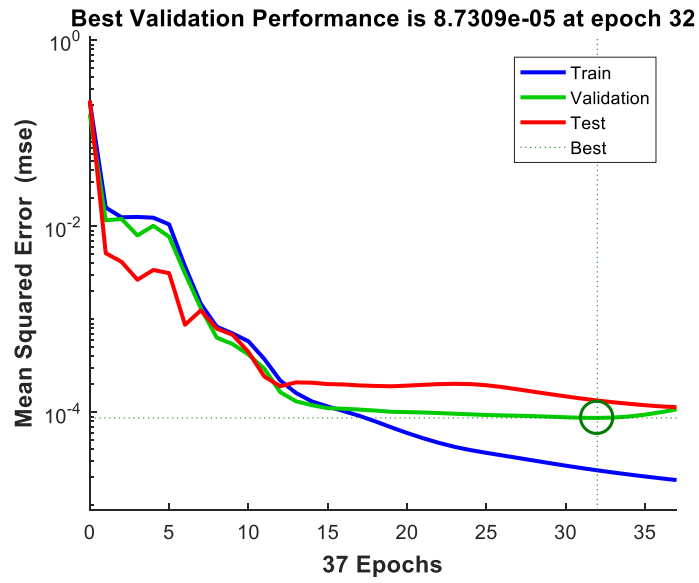
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625 Figure 6 The regressions of network outputs with respect to targets for (a) training set; (b)
 626 validation set; (c) test set; (d) all data

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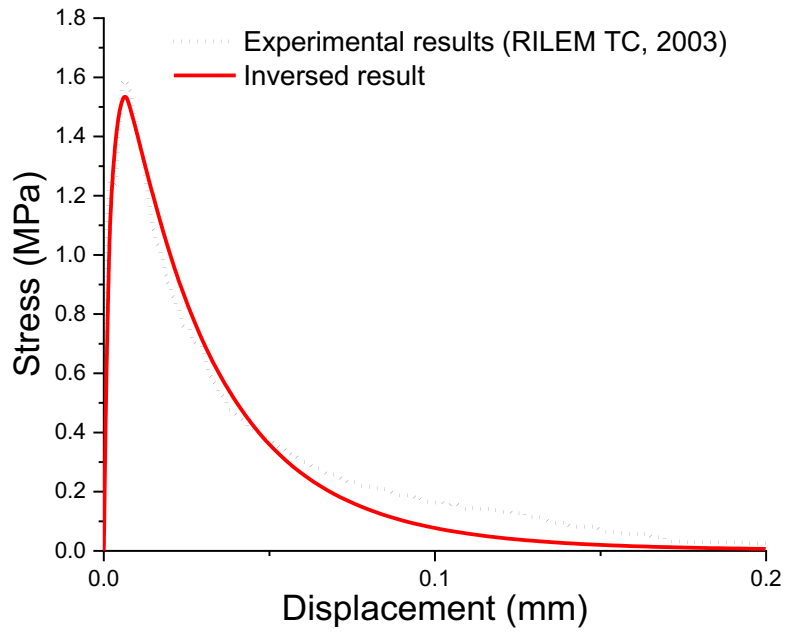
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Figure 7 Mean squared errors of the network data with the epoch increasing

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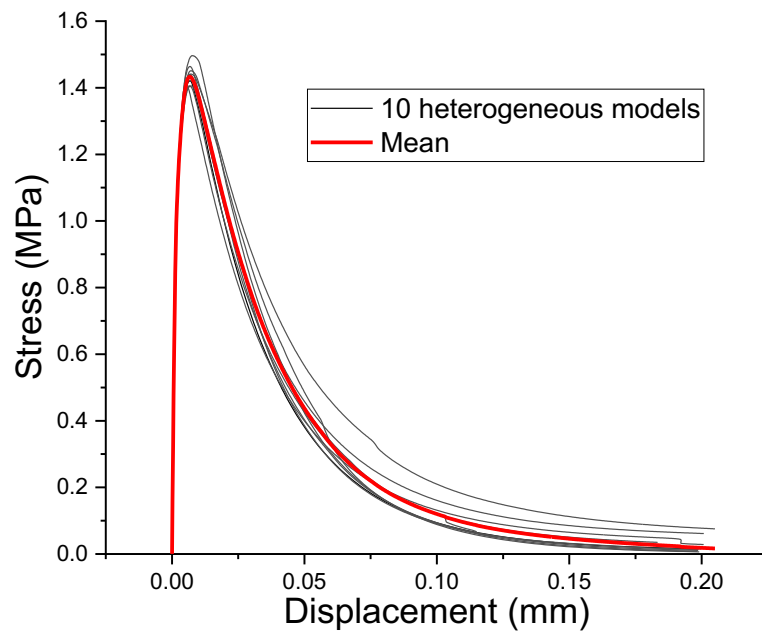


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634 Figure 8 Stress-displacement curves from the experiment and numerical result with inversed
635 ITZ fracture properties

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Figure 9 Effect of aggregate randomness on the stress-displacement curve

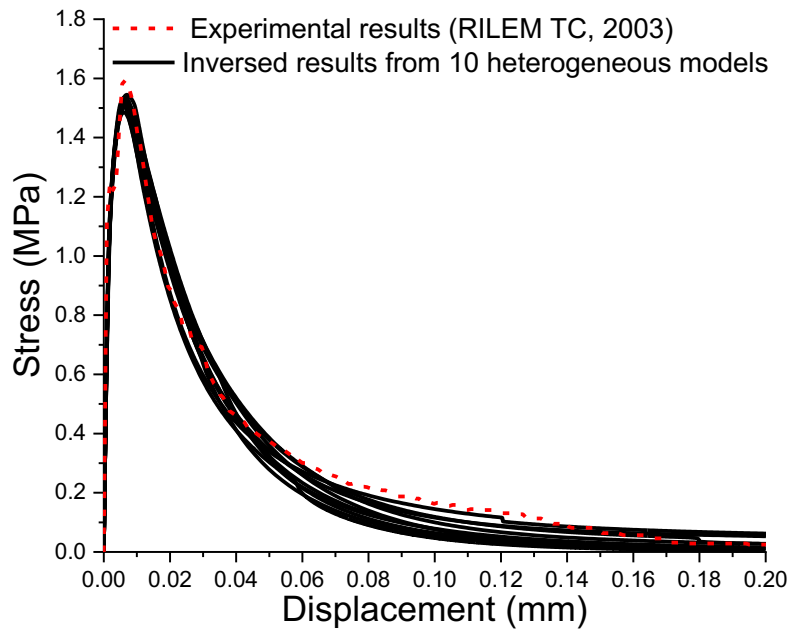
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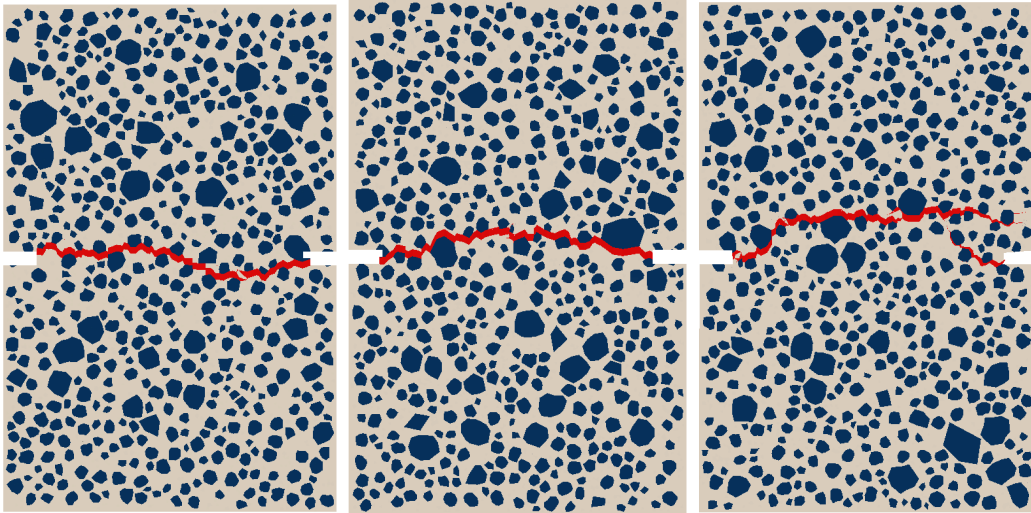
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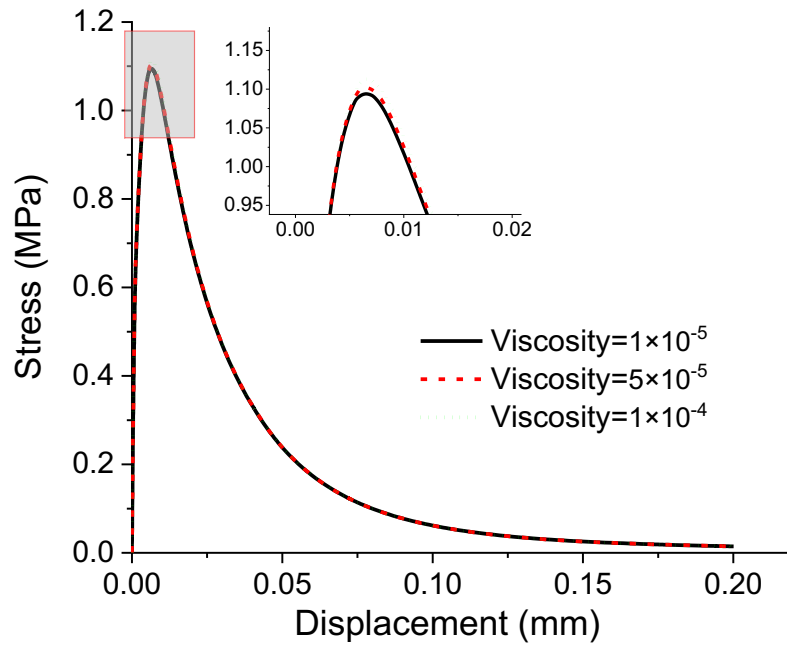
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Figure 10 Stress-displacement curves from the experiment and inversed results for 10 heterogeneous models



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Figure 11 Typical crack patterns from the inversed results

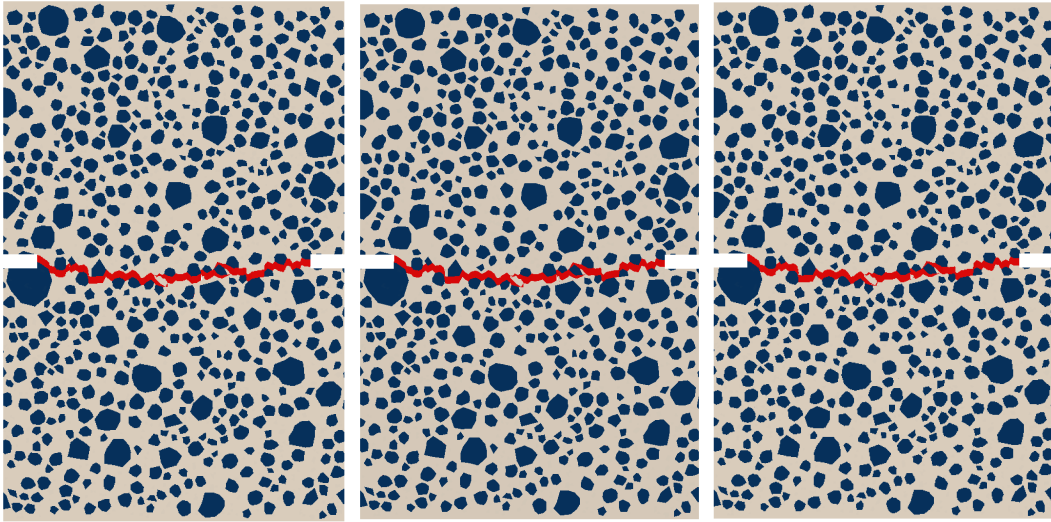


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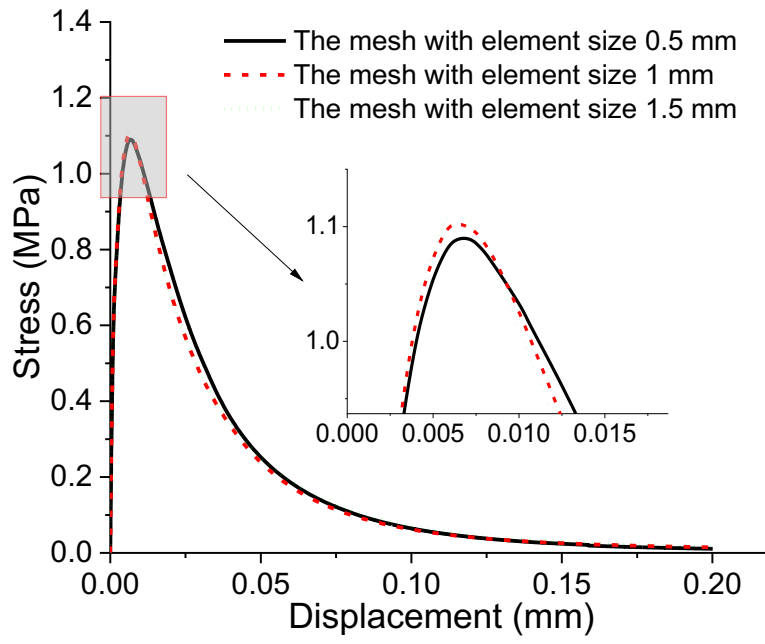
Figure 12 Effect of the viscosity on the stress-displacement curve of concrete

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(a) viscosity= 1.0×10^{-5} (b) viscosity= 5.0×10^{-5} (c) viscosity= 1.0×10^{-4}
Figure 13 Effect of the viscosity on the crack patterns of concrete

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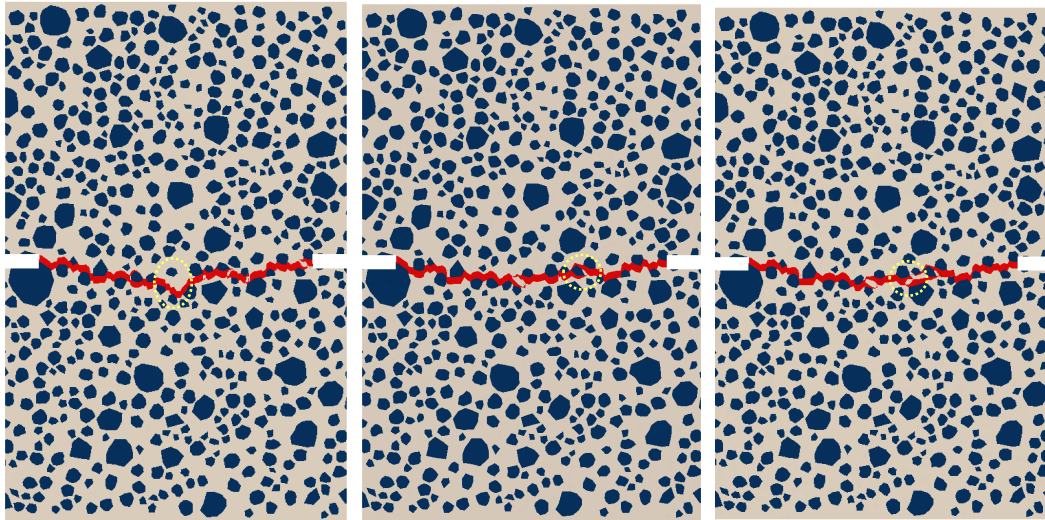
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Figure 14 Effect of element size on the stress-displacement curve of concrete

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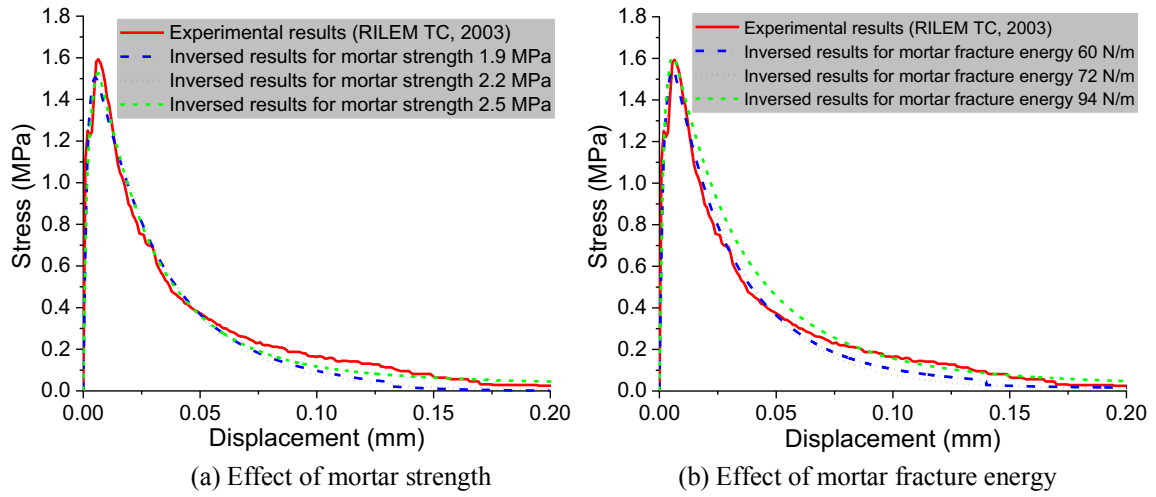
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(a) element size 0.5 mm (b) element size 1 mm (c) element size 1.5 mm

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Figure 15 Effect of element size on the crack patterns of concrete



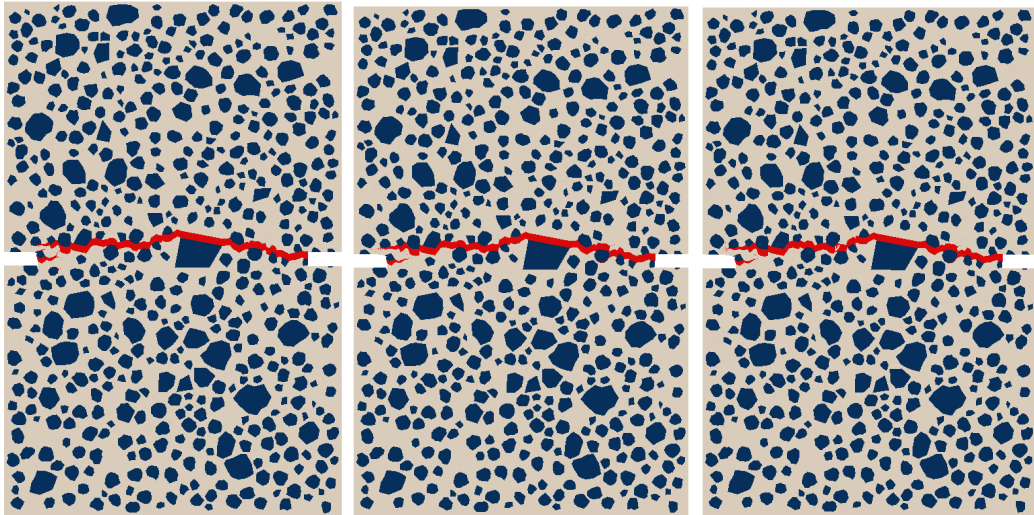
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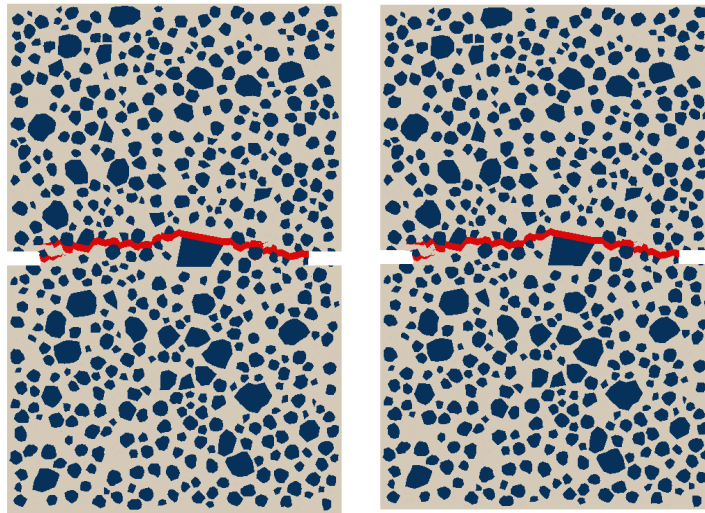
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Figure 16 Stress-displacement curves from inversed results for different values of mortar fracture properties

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(a) $\sigma_{\text{Mor}}=1.9$ MPa, $G_{\text{Mor}}=72$ N/m (b) $\sigma_{\text{Mor}}=2.2$ MPa, $G_{\text{Mor}}=72$ N/m (c) $\sigma_{\text{Mor}}=2.5$ MPa, $G_{\text{Mor}}=72$ N/m



(d) $\sigma_{\text{Mor}}=2.2$ MPa, $G_{\text{Mor}}=60$ N/m (e) $\sigma_{\text{Mor}}=2.2$ MPa, $G_{\text{Mor}}=94$ N/m

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Figure 17 Crack patterns of the inversed results for different values of mortar fracture properties

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