STOCHASTIC BACKGROUND OF GRAVITATIONAL WAVES 919

(The LIGO Scientific Collaboration)

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ABSTRACT

The Laser Interferometer Gravitational-Wave Observatory (LIGO) has performed the fourth science run, S4, with significantly improved interferometer sensitivities with respect to previous runs. Using data acquired during this science run, we place a limit on the amplitude of a stochastic background of gravitational waves. For a frequency independent spectrum, the new Bayesian 90% upper limit is \( \Omega_{GW} \times \left( H_0 / (72 \text{ km s}^{-1} \text{ Mpc}^{-1}) \right)^2 < 6.5 \times 10^{-5} \). This is currently the most sensitive result in the frequency range 51–150 Hz, with a factor of 13 improvement over the previous LIGO result. We discuss the complementarity of the new result with other constraints on a stochastic background of gravitational waves, and we investigate implications of the new result for different models of this background.

Subject heading: gravitational waves

1. INTRODUCTION

A stochastic background of gravitational waves (GWs) is expected to arise as a superposition of a large number of unresolved sources, from different directions in the sky and with different polarizations. It is usually described in terms of the GW spectrum,

\[
\Omega_{GW}(f) = \frac{f}{\rho_c} \frac{d\rho_{GW}}{df},
\]

where \( d\rho_{GW} \) is the energy density of gravitational radiation contained in the frequency range \( f \) to \( f + df \) (Allen & Romano 1999), \( \rho_c \) is the critical energy density of the universe, and \( f \) is frequency (for an alternative and equivalent definition of \( \Omega_{GW}(f) \) see, e.g., Baskaran et al. [2006]; Grishchuk et al. [2006]).

Many possible sources of stochastic GW background have been proposed, and several experiments have searched for it (see Maggiore 2000; Allen 1997 for reviews). Some of the proposed theoretical models are cosmological in nature, such as the amplification of quantum vacuum fluctuations during inflation (Grishchuk 1975, 1997; Starobinsky 1979), pre–big bang models (Gasperini & Veneziano 1993, 2003; Buonanno et al. 1997), phase transitions (Kosowsky et al. 1992; Apreda et al. 2002), and cosmic strings (Caldwell & Allen 1992; Damour & Vilenkin 2000, Damour & Vilenkin 2005). Others are astrophysical in nature, such as rotating neutron stars (Regimbau & de Freitas Pacheco 2001), supernovae (Coward et al. 2002), or low-mass X-ray binaries (Cooray 2004).

While some of these models predict complex GW spectra, most of them can be well approximated with power laws in the
Laser Interferometer Gravitational-Wave Observatory (LIGO) frequency band. Hence, we focus on power-law GW spectra:

$$\Omega_{GW}(f) = \Omega_o \left(\frac{f}{100 \text{ Hz}}\right)^{\alpha},$$  \hspace{1cm} (2)

where $\Omega_o$ is the amplitude corresponding to the spectral index $\alpha$. In particular, $\Omega_o$ denotes the amplitude of the frequency-independent GW spectrum. We consider the range $-3 < \alpha < 3$.

A number of experiments have been used to constrain the spectrum of GW background at different frequencies. Currently, the most stringent constraints arise from large-angle correlations in the cosmic microwave background (CMB; Allen & Koranda 1994; Turner 1997), from the arrival times of millisecond pulsar (Abbott et al. 2005), during LIGO’s first science run (S1) was described in Abbott (2004a). We define the following cross-correlation estimator:

$$Y = \int_0^{+\infty} df \int_{-\infty}^{+\infty} df' \delta_T(f - f') \tilde{\gamma}_1(f) \tilde{\gamma}_2(f'),$$  \hspace{1cm} (3)

where $\delta_T$ is a finite-time approximation to the Dirac delta function, $\tilde{\gamma}_1$ and $\tilde{\gamma}_2$ are the Fourier transforms of the strain time series of two interferometers, and $\tilde{\Omega}$ is a filter function. Assuming that the detector noise is Gaussian, stationary, uncorrelated between the two interferometers, and much larger than the GW signal, the variance of the estimator $Y$ is given by

$$\sigma_Y^2 = \int_0^{+\infty} df \sigma_\gamma^2(f),$$

$$\approx \frac{T}{2} \int_0^{+\infty} df P_1(f) P_2(f) \tilde{\Omega}(f)^2,$$  \hspace{1cm} (4)

where $P(f)$ are the one-sided power spectral densities (PSDs) of both interferometers, and $T$ is the measurement time. Optimization of the signal-to-noise ratio leads to the following form of the optimal filter (Allen & Romano 1999):

$$\tilde{\Omega}(f) = \mathcal{N} \gamma(f) S_{GW}(f) P_1(f) P_2(f),$$  \hspace{1cm} (5)

tween LIGO and other experimental constraints on a stochastic GW background. We conclude with future prospects in § 5.

2. ANALYSIS

2.1. Cross-Correlation Method

The cross-correlation method for searching for a stochastic GW background with pairs of ground-based interferometers is described in Allen & Romano (1999). We define the following cross-correlation estimator:

$$\sigma_Y^2 = \int_0^{+\infty} df \sigma_\gamma^2(f),$$

$$\approx \frac{T}{2} \int_0^{+\infty} df P_1(f) P_2(f) \tilde{\Omega}(f)^2,$$  \hspace{1cm} (4)

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$$\tilde{\Omega}(f) = \mathcal{N} \gamma(f) S_{GW}(f) P_1(f) P_2(f),$$  \hspace{1cm} (5)
where

\[ S_{GW}(f) = \frac{3H_0^2 \Omega_{GW}(f)}{10\pi^2 f^3}, \]

and \( \gamma(f) \) is the overlap reduction function arising from the different locations and orientations of the two interferometers. As shown in Figure 2, the identical antenna patterns of the colocated Hanford interferometers imply \( \gamma(f) = 1 \). For the Hanford-Livingston pair the overlap reduction is significant above 50 Hz. In equations (5) and (6), \( S_{GW}(f) \) is the strain power spectrum of the stochastic GW background to be searched. Assuming a power-law template GW spectrum with index \( \alpha \) (see eq. [2]), the normalization constant \( N \) in equation (5) is chosen such that \( \langle Y \rangle = \Omega_0 T \).

In order to deal with data nonstationarity, and for purposes of computational feasibility, the data for an interferometer pair are divided into many intervals of equal duration, and \( Y_1 \) and \( \sigma_Y \) are calculated for each interval \( I \). The data in each interval are decimated from 16,384 to 1024 Hz and high-pass filtered with a 40 Hz cutoff. As we discuss below, most of the sensitivity of this search lies below 300 Hz, safely below the Nyquist frequency of 512 Hz. The intervals are also Hann windowed to avoid spectral leakage from strong lines present in the data. Since Hann windowing effectively reduces the interval length by 50%, the data intervals are overlapped by 50% to recover the original signal-to-noise ratio. The effects of windowing are taken into account as discussed in Abbott et al. (2004b).

The PSDs for each interval [needed for the calculation of \( Q_1(f) \) and of \( \sigma_Y(f) \)] are calculated using the two neighboring intervals. This approach avoids a bias that would otherwise exist due to a nonzero covariance between the cross-power \( Y(f) \) and the power spectra estimated from the same data (Bendat & Piersol 2000). It also allows for a stationarity cut, which we describe in more detail below.

We consider two interval durations and frequency resolutions:

1. 60 s duration with 1/4 Hz resolution.—The PSDs are calculated by averaging 58 50% overlapping periodograms (based on the two neighboring 60 s intervals) in Welch’s modified periodogram method.

   As we discuss below, the 60 s intervals allow better sensitivity to noise transients and are better suited for data-stationarity cuts. We used this interval duration in the blind analysis. However, after unblinding we discovered a comb of correlated sharp 1 Hz harmonic lines between interferometers. To remove these sharp lines from our analysis without significantly affecting the sensitivity, we performed the second analysis with 192 s intervals. The 192 s intervals allow higher frequency resolution of the power and cross-power spectra and are better suited for removing sharp lines from the analysis.

   The data for a given interval \( I \) are Fourier transformed (with frequency resolution 1/60 or 1/192 Hz) and rebinned to the frequency resolution of the PSDs and of the optimal filter (1/4 or 1/32 Hz, respectively) to complete the calculation of \( Y_1 \) (eq. [3]). Both the PSDs and the Fourier transforms of the data are calibrated using interferometer response functions, determined for every minute of data using a measurement of the interferometer response to a sinusoidal calibration force. To maximize the signal-to-noise ratio, the intervals are combined by performing a weighted average (with weights \( 1/\sigma_Y^2(f) \)), properly accounting for the 50% overlapping as discussed in Lazzarini & Romano (2004).

2.2. Identification of Correlated Instrumental Lines

The results of this paper are based on the Hanford-Livingston interferometer pairs, for which the broadband instrumental correlations are minimized. Nevertheless, it is still necessary to investigate whether there are any remaining periodic instrumental correlations. We do this by calculating the coherence over the whole S4 run. The coherence is defined as

\[ \Gamma(f) = \frac{|P_{12}(f)|^2}{P_1(f)P_2(f)}. \]

The numerator is the square of the cross-spectral density (CSD) between the two interferometers, and the denominator contains the two power spectral densities (PSDs). We average the CSD and the PSDs over the whole run at two different resolutions: 1 and 100 mHz. Figure 3 shows the results of this calculation for the H1-L1 pair and for the H2-L1 pair.

At 1 mHz resolution, a forest of sharp 1 Hz harmonic lines can be observed. These lines were likely caused by the sharp ramp of a one-pulse-per-second signal, injected into the data acquisition system to synchronize it with the Global Positioning System (GPS) time reference. Since the coupling of this signal to the gravitational-wave channel of H1 was much stronger than that of H2, the forest of 1 Hz harmonics is much clearer in the H1-L1 coherence. After the S4 run ended, the sharp ramp signal was replaced by smooth sinusoidal signals, with the goal of significantly reducing the 1 Hz harmonic lines in future LIGO data runs. In addition to the 1 Hz lines, the 1 mHz coherence plots in Figure 3 also include some of the simulated pulsar lines, which were injected into the differential-arm servo of the interferometers by physically moving the mirrors. Both the 1 Hz harmonics and the simulated pulsar lines can be removed in the final analysis, and we discuss this further in § 3. Figure 4 shows that the histogram of the coherence at 1 mHz resolution follows the expected exponential distribution, if one ignores the 1 Hz harmonics and the simulated pulsar lines.

![Fig. 2.—Overlap reduction function for the Hanford-Hanford pair (black solid line) and for the Hanford-Livingston pair (gray dashed line).](image-url)
Data Quality Cuts

In our analysis, we include time periods during which both interferometers are in low-noise, science mode. We exclude:

1. Time periods when digitizer signals saturate.
2. 30 s intervals prior to each “lock loss”; interferometers become increasingly unstable during these intervals, usually due to some external disturbance, until they eventually fail to maintain the fixed distances between mirrors.

We then proceed to calculate $Y_I$ and $\sigma_{Y_I}$ for each interval $I$ and define three data quality cuts. First, we reject intervals known to contain large glitches in one interferometer. These intervals were identified by searching for discontinuities in the PSD trends over the whole S4 run. Second, we reject intervals for which $\sigma_{Y_I}$ is anomalously large. This cut is designed to reject intervals that happen during particularly noisy periods, by rejecting about 2% of the intervals in the high-end tail of the $\sigma_{Y_I}$ distribution. In particular, for the 192 s analysis, we require $\sigma_{Y_I} < 1$ s for the H1-L1 pair, and $\sigma_{Y_I} < 2$ s for the H2-L1 pair (recall that $Y$ is normalized such that $\langle Y \rangle = \Omega_\alpha T$, with $T = 192$ s in this case). The glitch cut and the large $\sigma$ cut largely overlap and are designed to remove particularly noisy time periods from the analysis. Note also that due to the weighting with $1/\sigma_{Y_I}^2$, the contribution of these intervals to the final result would be suppressed, but we reject them from the analysis nevertheless. Third, we reject the intervals for which

$$\frac{|Y_I - \langle Y \rangle|}{\sigma_{Y_I}} > \zeta.$$

Fig. 3.— Coherence calculated for the H1-L1 pair (top) and for the H2-L1 pair (bottom) over all of S4 data for 1 and 100 mHz resolution. The horizontal dashed lines indicate $1/N_{\text{avg}}$, the expected level of coherence after averaging over $N_{\text{avg}}$ time periods with uncorrelated spectra. The line at 376 Hz is one of the simulated pulsar lines.

Fig. 4.— Histogram of the coherence for H1-L1 (top) and H2-L1 (bottom) at 1 mHz resolution. The histogram follows the expected exponential distribution, with exponent coefficient $N_{\text{avg}}$ (the number of time periods over which the average is made), when the 1 Hz harmonics are removed (“after notching”). The gray histograms (“before notching”) show the outliers from the exponential distribution due to the 1 Hz harmonics.
where $<Y>$ is calculated using only the data that pass all the data quality cuts. Also note that the data quality cuts remove outliers from the residual distribution, hence making the data more stationary. After the cuts, the Kolmogorov-Smirnov test indicates that the residual distribution is consistent with a Gaussian, for both H1-L1 and H2-L1 analyses with 192 s intervals, 1/32 Hz resolution, and $\zeta = 0.3$.

3. RESULTS

3.1. New Upper Limit

We performed a “blind” analysis for the H1-L1 and the H2-L1 pairs with 60 s intervals, 1/4 Hz resolution, and $\zeta = 0.2$. To avoid biasing the results, all data quality cuts were defined based on studies done with a 0.1 s time shift between the two interferometers in a pair. Such a time shift removes any GW correlations, without significantly affecting the instrumental noise performance. After the data quality cuts were finalized, we made one last pass through the data, with zero time shift, and obtained the final results of the blind analysis.

The results from the blind analysis for the frequency-independent template spectrum ($\alpha = 0$) are listed in the first row of Table 1 for H1-L1 and in the first row of Table 2 for H2-L1. These results show no evidence of a stochastic GW background. After completing the blind analysis, we discovered that the instrumental 1 Hz harmonic lines, discussed in § 2.2, are correlated between the two sites. We felt compelled on scientific grounds not to ignore these correlations, even though they had been discovered after our initial, blind, analysis was complete.

In order to remove from our results any possible influence of the correlated lines, we repeated our analysis with refined frequency resolution of 1/32 Hz. We increased the interval length from 60 to 192 s, which implies that the PSDs are estimated by averaging 22 50% overlapping periodograms. These changes allowed us to exclude the 1 Hz harmonics from the analysis while losing only $\sim3\%$ of the bandwidth. Besides the low cost in bandwidth, the advantages of this approach are its simplicity and the fact that it does not introduce new systematics effects. The drawback, however, was that the 192 s analysis was less able to identify and exclude the noise transients than the 60 s analysis, as shown in Figure 7. As a result, the $\Delta\sigma$ cut was returned for the 192 s analysis after the 60 s analysis with zero time shift was completed.

We examined several methods of defining the data quality cuts for the 192 s analysis. First, we calculated the $\Delta\sigma$ cut in the 60 s analysis with $\zeta = 0.2$ (along with large $\sigma$ and glitch cuts), and then declared 192 s intervals “bad” if they overlapped with the “bad” 60 s intervals. This approach has the advantage that the 60 s analysis is more sensitive to transients, and the disadvantage that a significant fraction of the data is rejected. The results of this approach are summarized in the second row of Tables 1 and 2. Second, we defined all cuts directly on 192 s intervals. We varied the value of $\zeta (0.2, 0.3, \text{and} 0.4)$ and selected $\zeta = 0.3$ as the optimal parameter choice. This choice represents the best compromise between data loss and data quality; it rejects the least amount of data, while still excluding all residual outliers and preserving the Gaussianity of the data. The last three rows of Tables 1 and 2 summarize the results for the three values of $\zeta$.

The 192 s analysis was not performed blindly. However, it agrees with our blind 60 s analysis very well, because the contribution of the correlated 1 Hz harmonic lines is only about 1.5 $\sigma$. It is also more conservative than the blind analysis, since the value of the theoretical error is larger due to a smaller amount of data available in the form of acceptable 192 s intervals (as compared to the 60 s intervals). It also properly handles the known instrumental correlations at 1 Hz harmonics. Hence, in the remaining part of the paper we focus on the 192 s analysis with $\zeta = 0.3$. For the H1-L1 pair, 12,637 50% overlapping 192 s intervals pass all data quality cuts of this analysis, amounting to 353.9 hr of exposure. For the H2-L1 pair, 11,849 intervals pass all data quality cuts of this analysis, amounting to 332.7 hr of exposure.

Figures 8 and 9 show the results of the 192 s analysis with $\zeta = 0.3$ for H1-L1 and H2-L1, respectively. The top plots in these two figures show the cumulative estimates for the frequency-independent GW template ($\alpha = 0$) as a function of time. They indicate that there is no particular time during the run that dominates the result. Moreover, the ±1.65 $\sigma$ bounds converge as $\sim1/\sqrt{T}$, as expected. The middle plots of the two figures show the cross-correlation spectra (i.e., the integrand of eq. [3]). They indicate that there is no particular frequency that dominates the result.
We perform a weighted average of the H1-L1 and H2-L2 results at each frequency bin (with inverse variances as weights). The resulting cross-correlation spectrum and the theoretical error are shown in Figure 10. The frequency range 51–150 Hz contributes 99% of the full sensitivity, as determined by the inverse combined variance. Integrating over this frequency range, we obtain the final estimate for the frequency-independent spectrum: \( \Omega_0 = (-0.8 \pm 4.3) \times 10^{-2} \).

The dominant systematic uncertainty of this result comes from the amplitude calibration uncertainty of the interferometers. This uncertainty is estimated to be 5% (L1) and 8% (H1 and H2), and it is frequency-independent. The uncertainty in the phase of the interferometer strain response is negligible compared to the magnitude and statistical uncertainties. Similarly, the effect of timing errors, measured to be \( \leq 4 \mu s \), is negligible. Using hardware injections, we estimate that the effect of the timing errors on our point estimate is \( \leq 0.2\% \).

We then construct the Bayesian posterior distribution for \( \Omega_0 \) using the above estimate, following Loredo (1990). We assume a Gaussian distribution for the amplitude calibration uncertainty [with mean 1 and standard deviation (0.05\(^2\) + 0.08\(^2\))\(^{1/2} = 0.093\)], and we marginalize over it. We assume the prior distribution for \( \Omega_0 \) to be the posterior distribution obtained in our previous analysis of the S3 data (Abbott et al. 2005). The 90% upper limit is the value of \( \Omega_0 \) for which 90% of the posterior distribution lies between 0 and the upper limit. This procedure yields the Bayesian 90% upper limit (UL) on \( \Omega_0 \) of \( 6.5 \times 10^{-5} \). This is an improvement by a factor 13 over the previous result in the same frequency band, established based on the science run S3 (Abbott et al. 2005). To investigate robustness of our result under different priors, we repeated the calculation using flat priors for the amplitude calibration uncertainties and using a flat prior for \( \Omega_0 \) between 0 and \( 8.4 \times 10^{-4} \) (previous 90% UL by LIGO; Abbott et al. 2005). We found that these different choices of priors have less than 3% effect on the 90% upper limit.

Once the estimate is made for the frequency-independent spectrum, one can perform appropriate frequency-dependent scalings of \( Y(f) \) and \( \sigma_Y(f) \), re-calculate the posterior distributions, and remarginalize to obtain upper limits for other templates, such as the power-law templates with different spectral indices \( \alpha \) (see eq. [2]). Figure 11 shows the 90% UL as a function of the spectral index \( \alpha \) obtained for this analysis. Similar results for the S3 run of LIGO, as well as the expected sensitivities of H1-L1 and H1-H2 pairs assuming 1 yr of exposure and design interferometer sensitivities, are also shown. The frequency range of interest is defined to include 99% of the full sensitivity, as determined by the inverse variance. For the S4 result, the frequency range varies between 50–107 Hz for \( \alpha = -3 \) and 73–288 Hz for \( \alpha = +3 \), as shown in the bottom plot of Figure 11. Note that the expected sensitivity of the collocated Hanford interferometer pair (H1-H2) is significantly better than that of the H1-L1 pair due to the better antenna pattern overlap (see Fig. 2). However, this

### Table 1: H1-L1 Results

<table>
<thead>
<tr>
<th>Analysis (1)</th>
<th>( \zeta ) (2)</th>
<th>Fraction of Data Excluded (%)</th>
<th>( \Omega_0 \times 10^{-5} ) Before Notching 50–500 Hz (4)</th>
<th>( \Omega_0 \times 10^{-5} ) After Notching 51–150 Hz (5)</th>
<th>90% UL (( \times 10^{-5} )) (6)</th>
</tr>
</thead>
<tbody>
<tr>
<td>60 s (blind)</td>
<td>0.2</td>
<td>4.1</td>
<td>(-8.2 \pm 10.6)</td>
<td>\ldots</td>
<td>13.0</td>
</tr>
<tr>
<td>192 s</td>
<td>conversion</td>
<td>10.7</td>
<td>(-3.9 \pm 11.9)</td>
<td>(-7.2 \pm 12.1)</td>
<td>16.1</td>
</tr>
<tr>
<td>192 s</td>
<td>0.2</td>
<td>6.1</td>
<td>(-1.7 \pm 11.6)</td>
<td>(-4.2 \pm 11.8)</td>
<td>17.1</td>
</tr>
<tr>
<td>192 s</td>
<td>0.3</td>
<td>4.6</td>
<td>(-0.6 \pm 11.5)</td>
<td>(-3.3 \pm 11.7)</td>
<td>17.5</td>
</tr>
<tr>
<td>192 s</td>
<td>0.4</td>
<td>3.8</td>
<td>(-3.1 \pm 11.5)</td>
<td>(-6.1 \pm 11.7)</td>
<td>15.9</td>
</tr>
</tbody>
</table>

**Notes.**—H1-L1 results, for \( H_0 = 72 \text{ km s}^{-1} \text{ Mpc}^{-1} \) and for a frequency-independent template spectrum (\( \alpha = 0 \)). Cols. (1) and (2) define the analysis (interval duration and \( \Delta \sigma \) cut). For the 192 s analysis with \( \zeta \) denoted as “conversion” (second row), the \( \Delta \sigma \) cut was defined using the 60 s analysis listed in the first row; the 192 s segments are declared “bad” if they overlap with a “bad” 60 s segment. Col. (3): Fraction of the data lost to data quality cuts. Col. (4): Estimates of \( \Omega_0 \) for the 50–500 Hz range before notchting the 1 Hz harmonics and the simulated pulsar lines. Col. (5): Estimates of \( \Omega_0 \) for the 51–150 Hz range after notchting the 1 Hz harmonics and the simulated pulsar lines; this frequency range was determined to be optimal for the combined H1-L1+H2-L1 analysis (see text). Col. (6): The 90% upper limit based on the result in col. (5). For all analyses presented here, the distribution of the residual outliers was consistent with a Gaussian distribution (the Kolmogorov-Smirnov test statistic for comparing the two distributions was greater than 52% in all cases).

### Table 2: H2-L2 Results

<table>
<thead>
<tr>
<th>Analysis (1)</th>
<th>( \zeta ) (2)</th>
<th>Fraction of Data Excluded (%)</th>
<th>( \Omega_0 \times 10^{-5} ) Before Notching 50–500 Hz (4)</th>
<th>( \Omega_0 \times 10^{-5} ) After Notching 51–150 Hz (5)</th>
<th>90% UL (( \times 10^{-5} )) (6)</th>
</tr>
</thead>
<tbody>
<tr>
<td>60 s (blind)</td>
<td>0.2</td>
<td>4.1</td>
<td>(-8.2 \pm 10.6)</td>
<td>\ldots</td>
<td>13.0</td>
</tr>
<tr>
<td>192 s</td>
<td>conversion</td>
<td>10.7</td>
<td>(-3.9 \pm 11.9)</td>
<td>(-7.2 \pm 12.1)</td>
<td>16.1</td>
</tr>
<tr>
<td>192 s</td>
<td>0.2</td>
<td>6.1</td>
<td>(-1.7 \pm 11.6)</td>
<td>(-4.2 \pm 11.8)</td>
<td>17.1</td>
</tr>
<tr>
<td>192 s</td>
<td>0.3</td>
<td>4.6</td>
<td>(-0.6 \pm 11.5)</td>
<td>(-3.3 \pm 11.7)</td>
<td>17.5</td>
</tr>
<tr>
<td>192 s</td>
<td>0.4</td>
<td>3.8</td>
<td>(-3.1 \pm 11.5)</td>
<td>(-6.1 \pm 11.7)</td>
<td>15.9</td>
</tr>
</tbody>
</table>

**Notes.**—H2-L2 results, for \( H_0 = 72 \text{ km s}^{-1} \text{ Mpc}^{-1} \) and for a frequency-independent template spectrum (\( \alpha = 0 \)). Cols. (1) and (2) define the analysis (interval duration and \( \Delta \sigma \) cut). For the 192 s analysis with \( \zeta \) denoted as “conversion” (second row), the \( \Delta \sigma \) cut was defined using the 60 s analysis listed in the first row; the 192 s segments are declared “bad” if they overlap with a “bad” 60 s segment. Col. (3): Fraction of the data lost to data quality cuts. Col. (4): Estimates of \( \Omega_0 \) for the 50–500 Hz range before notchting the 1 Hz harmonics and the simulated pulsar lines. Col. (5): Estimates of \( \Omega_0 \) for the 51–150 Hz range after notchting the 1 Hz harmonics and the simulated pulsar lines; this frequency range was determined to be optimal for the combined H1-L1+H2-L1 analysis (see text). Col. (6): The 90% upper limit based on the result in col. (5). For all analyses presented here, the distribution of the residual outliers was consistent with a Gaussian distribution (the Kolmogorov-Smirnov test statistic for comparing the two distributions was greater than 52% in all cases).
pair is also more susceptible to instrumentally correlated noise. New analysis methods are being pursued to estimate and suppress these instrumental correlations (Fotopoulos 2006).

### 3.2. Signal Injections

We exercise the analysis procedure described above using simulated stochastic signals injected into the data both in software and in hardware (see Bose et al. 2003). In particular, we verify that the recovery of the injected signals is not affected by the data quality cuts we impose. The hardware injections are performed by physically moving the mirrors to simulate a stochastic GW signal. Three hardware injections were performed during the S4 run, all using a frequency-independent GW spectrum ($\alpha = 0$). Table 3 summarizes the recovery of all of the hardware injections. Figure 12 shows the cross-correlation spectrum
for injection 3. It also shows the inverse Fourier transform of the spectrum, which is equivalent to the estimate of \( \Omega_0 \) for different values of time lag between two interferometers (for short time lags).

We performed a sequence of software injections, where the injected signal is simply added to the interferometer data in the analysis. We performed 10 trials for 4 injection amplitudes using about 1/3 of the S4 H1-L1 data. Figure 13 shows that the signal is successfully recovered down to \( 1 \times 10^{-4} \) in \( \Omega_0 \). Moreover, the theoretical error bars agree well with the standard deviation over the 10 trials. All injections were performed assuming a frequency-independent GW spectrum (\( \alpha = 0 \)).

### 4. IMPLICATIONS

In this section, we investigate the implications of the new upper limit for some of the models of the stochastic GW background. We also discuss the complementarity of our result with various other experimental constraints on the stochastic GW background.

#### 4.1. Complementarity with Other Measurements and Observations

Figure 14 compares different experiments and some of the theoretical models. We note again our assumption regarding

![Graph](image)

**Fig. 11.** Top: 90\% UL on \( \Omega_0 \) as a function of \( \alpha \) for S3 H1-L1 and S4 H1-L1+H2-L1 combined and expected final sensitivities of LIGO H1-L1 and H1-H2 pairs, assuming LIGO design sensitivity and 1 yr of exposure. Bottom: Frequency band containing 99\% of the full sensitivity (as determined by the inverse variance) is plotted as a function of \( \alpha \) for the S4 result.

**Fig. 12.**—H1-L1 injection 3 (with intended injection amplitude \( \Omega_0 = 1.1 \times 10^{-4} \)). Top: Cross-correlation spectrum \( Y(f) \). Bottom: Inverse Fourier transform of the cross-correlation spectrum indicates the clear signal at zero lag. The inset plot is a zoom-in around zero lag.

TABLE 3

**Summary of the Hardware Injection Amplitudes During S4**

<table>
<thead>
<tr>
<th>Injection (1)</th>
<th>H1-L1 Expected (( \times 10^{-2} )) (2)</th>
<th>H1-L1 Recovered (( \times 10^{-2} )) (3)</th>
<th>H2-L1 Expected (( \times 10^{-2} )) (4)</th>
<th>H2-L1 Recovered (( \times 10^{-2} )) (5)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1..................</td>
<td>9.1</td>
<td>7.9 ± 0.2 ± 0.8</td>
<td>7.9</td>
<td>6.9 ± 0.4 ± 0.6</td>
</tr>
<tr>
<td>2..................</td>
<td>2.5</td>
<td>2.5 ± 0.4 ± 0.2</td>
<td>2.3</td>
<td>1.5 ± 0.6 ± 0.2</td>
</tr>
<tr>
<td>3..................</td>
<td>1.1</td>
<td>0.95 ± 0.04 ± 0.10</td>
<td>...</td>
<td>...</td>
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**Notes.**—Cols. (2) and (4) indicate the expected injection amplitudes for H1-L1 and H2-L1, respectively, based on the signal injected into the differential-arm servo. Cols. (3) and (5) list the recovered values using the H1-L1 and H2-L1 pairs respectively. The recovered values are listed with statistical errors (as defined in eq. [4]) and with systematic errors (estimated using 5\% calibration uncertainty in L1 and 8\% calibration uncertainty in H1 and H2, added in quadrature). For injection 3, the data of H2 interferometer were compromised due to a failure of the interferometer’s laser.
the Hubble parameter, when writing $\Omega_{GW}$ we implicitly mean $\Omega_{GW} \times \left[ H_0 / (72 \text{ km s}^{-1} \text{ Mpc}^{-1}) \right]^2$.

For wavelengths larger than the horizon size at the surface of last scattering (redshifted to today, this corresponds to frequencies below $\sim 10^{-16}$ Hz), the COBE observations of the CMB constrain the stochastic gravitational wave background to $\Omega_{GW}(f) < 7 \times 10^{-11} (3 \times 10^{-18} \text{ Hz}\cdot f)^2$ (see Allen & Koranda 1994; Allen 1997). In the framework of standard inflationary models (Turner 1997), this constraint can be extrapolated to frequencies above $\sim 10^{-16}$ Hz: $\Omega_{GW}(f) \lesssim 10^{-14}$, with some dependence on the inflationary model parameters.

The fluctuations in the arrival times of millisecond pulsar signals can be used to place a 95% detection rate upper bound of $\Omega_{GW}(f) < 10^{-12}$ at $1.2 \times 10^{-6}$ Hz.

If the energy density carried by the gravitational waves at the time of big bang nucleosynthesis (BBN) were large, the amounts of the light nuclei produced in the process could be altered. Hence, the BBN model and observations can be used to constrain the total energy carried by gravitational waves at the time of nucleosynthesis (Kolb & Turner 1990; Maggiore 2000; Allen 1997):

$$\int \Omega_{GW}(f) d(\ln f) < 1.1 \times 10^{-5} (N_{\nu} - 3),$$

where $N_{\nu}$ (the effective number of neutrino species at the time of BBN) captures the uncertainty in the radiation content during BBN. Measurements of the light-element abundances, combined with the Wilkinson Microwave Anisotropy Probe (WMAP) data, give the following 95% upper bound: $N_{\nu} - 3 < 1.4$ (Cyburt et al. 2005). This limit translates into $\int \Omega_{GW}(f) d(\ln f) < 1.5 \times 10^{-5}$. This bound applies down to $\sim 10^{-10}$ Hz, corresponding to the horizon size at the time of BBN.

Gravitational waves are also expected to leave a possible imprint on the CMB and matter spectra, similar to that of massless neutrinos. Smith et al. (2006b) used recent measurements of the CMB anisotropy spectrum, galaxy power spectrum, and Ly$\alpha$ forest to constrain the energy density carried by gravitational waves to $\int \Omega_{GW}(f) d(\ln f) < 1.3 \times 10^{-5}$ for homogeneous initial conditions at 95% confidence level. This bound is competitive with the BBN bound and it extends down to $\sim 10^{-15}$ Hz, corresponding to the horizon size at the time of CMB decoupling. It is also expected to improve as new experiments come online (such as Planck or CMBPol).

The LIGO results apply to the frequency region around 100 Hz. The result discussed in this paper is an improvement by a factor of 3 over the previous LIGO result in the 100 Hz region, for a frequency-independent spectrum of GW background. A 1 yr run at design sensitivity of LIGO (the S5 run, which began in November of 2005) is expected to improve the sensitivity by another factor of 10 – 100, while Advanced LIGO is expected to achieve sensitivities better by yet another factor of 100 – 1000, eventually reaching $10^{-9}$ – $10^{-8}$ for $\Omega_0$. The uncertainty in the final reach of LIGO and Advanced LIGO comes from the potential instrumental correlations that could be present between the colocated Hanford interferometers and from the uncertainty in the final optical configurations of interferometers in Advanced LIGO. The result discussed in this paper is still weaker than the indirect BBN bound (if one assumes that the gravitational-wave spectrum is limited to the LIGO frequency band), but future runs by LIGO and Advanced LIGO are expected to surpass this bound.

The standard inflationary models are most stringently constrained by the CMB bound at lowest frequencies. Although they are most likely out of range of LIGO and Advanced LIGO, they may be accessible to future GW interferometers (Smith et al. 2006a). However, there are models of stochastic GW background that LIGO is beginning to explore. We illustrate this with examples of cosmic string and pre – big bang models.

### 4.2. Implications for Cosmic String Models

Cosmic strings can be formed as linear defects during symmetry-breaking phase transitions in the early universe, as well as in string theory inspired inflation scenarios. In the latter case they have been dubbed cosmic superstrings. CMB data is not consistent
with cosmic strings as the predominant source of density fluctuations in the universe. Their existence, however, is not ruled out below the grand unified theory (GUT) scale, and cosmic strings may still lead to a myriad of detectable astrophysical signatures, such as gravitational radiation, gamma-ray bursts, and ultrahigh energy cosmic rays. For a review, see Vilenkin & Shellard (2000).

Damour & Vilenkin (2005) investigated the stochastic background of gravitational waves produced by cusps on cosmic strings, integrated over all redshifts and all directions. They find that three parameters define the gravitational-wave spectrum due to cosmic strings:

1. String tension $\mu$.—This parameter is usually expressed as a dimensionless quantity $G\mu$ (assuming speed of light $c = 1$), where $G$ is Newton’s constant. String-theory-inspired inflation scenarios prefer the range $10^{-11} \leq G\mu \leq 10^{-6}$.

2. Reconnection probability $p$.—While ordinary, field-theoretic strings reconnect whenever they intersect ($p = 1$), the reconnection probability for superstrings is typically smaller than 1. In particular, the theoretically favored range is $10^{-2} \leq p \leq 1$ (Jackson et al. 2005).

3. $\epsilon$.—This parameter describes the typical size of the closed loops produced in the string network. The value of this parameter is uncertain, and it can span several orders of magnitude. We consider the range $10^{-13} < \epsilon < 1$, which is both theoretically viable and most interesting from the point of view of LIGO.

These parameters determine both the amplitude and the shape of the gravitational-wave spectrum. In particular, parameters $\epsilon$ and $G\mu$ determine the lowest frequency (at a given redshift) at which a string loop could emit gravitational radiation. Since there is a low-frequency cutoff to the predicted gravitational-wave spectrum, it is possible to have a cosmic string model that would avoid the low-frequency bounds due to CMB or pulsar timing measurements, but still be within reach of LIGO (cf. Fig. 14).

Figure 15 shows the region of the parameter space (for $p = 10^{-2}$) excluded by the result discussed in this paper and by the S3 result (Abbott et al. 2005), as well as the expected reach of LIGO and Advanced LIGO in future runs. As shown in this figure, LIGO is most sensitive to the regions of large $G\mu$ and small $\epsilon$. Moreover, LIGO results are complementary to the pulsar timing limit, which is most sensitive to models with large $G\mu$ and large $\epsilon$, and to the indirect BBN limit. In particular, the population of models with $p = 10^{-3}$, $\epsilon \lesssim 5 \times 10^{-11}$, and $5 \times 10^{-9} \leq G\mu \leq 7 \times 10^{-8}$ are excluded by the result discussed in this paper, but are not accessible to other current experimental bounds. To produce this figure, we used equations (4.1)–(4.7) from Damour & Vilenkin (2005).

We note that as $p$ increases toward 1, the bounds/reach of all experiments in the $G\mu-\epsilon$ plane weaken because the amplitude of the gravitational-wave spectrum scales with $1/p$. We also note that there are significant uncertainties in the calculation discussed by Damour & Vilenkin (2005), mostly due to incomplete understanding of the string network behavior. Recent numerical simulations of cosmic string networks (Martins & Shellard 2006; Vanchurin et al. 2006; Ringeval et al. 2005) suggest that loop sizes are related to the large-scale dynamics of the network. In this case, the expected stochastic background at the frequencies of pulsar timing experiments could be substantially larger (Hogan 2006). In addition, the treatment of Damour & Vilenkin (2005) did not account for the effects of late-time acceleration. Thus, a more detailed analysis of the stochastic background produced by cosmic strings is necessary.

4.3. Implications for Pre–Big Bang Models

Pre–big bang models are cosmology models motivated by string theory (Gasperini & Veneziano 1993, 2003). In these models, the universe evolves through several phases: “dilation” phase in which the universe is large and shrinking; “stringy” phase in which the curvature of the universe is high; and standard radiation- and matter-dominated phases. The GW spectrum is generated by amplification of vacuum fluctuations as the universe transitions from one phase to another. The shape and amplitude of the spectrum are determined by the states of the universe in the different phases. Although the “stringy phase” of the model and the transition to the radiation phase are not well understood, some models have been proposed in the literature that may partially describe it. In the formalism developed by Buonanno et al. (1997), the GW spectrum produced by the model can be described as

1. $\Omega_{GW}(f) \sim \mu^3$ for $f < f_1$, where $f_1$ is essentially unconstrained.

2. $\Omega_{GW}(f) \sim f^{3-2\mu}$ for $f_1 < f < f_2$, where $\mu < 1.5$ defines the evolution of the universe in the “stringy” phase. The cutoff frequency $f_1$ is determined by string-related parameters and its most natural value is expected to be $4.3 \times 10^{10}$ Hz.

Following the analysis in Mandic & Buonanno (2006), we can scan the parameter space $(f_1, \mu, f_2)$. For each set of values of these parameters, we calculate the GW spectrum following Buonanno et al. (1997) and check whether the model is accessible to the current (and past) LIGO results. We also project the sensitivity of initial and Advanced LIGO to these models. Figure 16 shows the $f_1-\mu$ plane for $f_2 = 30$ Hz. Note that the LIGO S3 and S4 results are beginning to explore the parameter space of these models, although the indirect BBN bound is still a stronger constraint. Future runs of LIGO and of Advanced

![Image](318x559 to 564x747)

**Fig. 15.**—The $\epsilon$-$G\mu$ plane for the cosmic string models with $p = 10^{-3}$. The shaded regions are excluded by the LIGO S3 limit (dark grey) and by the LIGO S4 limit presented here (light grey). The hatched regions are accessible to future LIGO runs: expected LIGO sensitivity for the H1-L1 pair, assuming design interferometer strain sensitivity and 1 yr of exposure (horizontal hatching); expected LIGO sensitivity for the H1-H2 pair, assuming design interferometer strain sensitivity and 1 yr of exposure (solid hatching); expected Advanced LIGO sensitivity for the H1-H2 pair, assuming interferometer strain sensitivity tuned for the binary neutron star inspiral search and 1 yr of exposure (/// hatching). The dash-dotted black curve is the exclusion curve based on the pulsar limit (Jenet et al. 2006; the excluded region is above the curve). The solid black curve is the exclusion curve based on the indirect big bang–nucleosynthesis bound (the excluded region is to the right of the curve).
LIGO are expected to explore significantly larger parts of the parameter space, eventually surpassing the BBN bound (in some parts of the parameter space) and even reaching the most natural value of $f_1 = 4.3 \times 10^{10}$ Hz.

5. CONCLUSIONS

LIGO data acquired during the science run S4 yield a new Bayesian 90% upper limit on the amplitude of the stochastic GW background: $\Omega_0 < 6.5 \times 10^{-5}$ for the frequency-independent GW spectrum ($\alpha = 0$) in the frequency band 51–150 Hz. Similar limits are obtained for other values of $\alpha$, as shown in Figure 11. This result is an improvement by a factor of 13 over the previous upper limit in the same frequency range, obtained by LIGO in the science run S3.

This result is obtained using 192 s long intervals of data with 1/32 Hz frequency resolution of the spectra, and it properly excludes the known instrumental correlations at 1 Hz harmonics. It is fully consistent with the blind result that uses 60 s long intervals of data with 1/4 Hz frequency resolution, which is slightly contaminated by the instrumental 1 Hz harmonics. It is also more conservative than the blind result, as the theoretical error is larger due to the smaller amount of data available in the form of acceptable 192 s intervals (as compared to the 60 s intervals).

This result is complementary to the constraints on the gravitational-wave spectrum, based on the measurements of the CMB spectrum and pulsar timing. It is still weaker than the indirect BBN bound for models where the stochastic gravitational-wave background is limited to the LIGO frequency band. The ongoing 1 yr long run of LIGO at the design sensitivity, and the future runs of Advanced LIGO, are expected to surpass the BBN bound for such models. Furthermore, this result is already exploring the parameter space of some models of the stochastic GW background, such as cosmic strings models and pre–big bang models.

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