

CORRECTION

Correction: Reflex Control of Robotic Gait Using Human Walking Data

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The following information is missing from the Funding section: Funding was provided by the University of Glasgow (<http://www.gla.ac.uk>) LKAS scholarship (<http://www.gla.ac.uk/services/postgraduateresearch/scholarships/kelvinsmith/>). This funding was received by LM.

The complete, correct Funding statement is: Funding was provided by the Engineering and Physical Sciences Research Council (EPSRC) (<http://www.epsrc.ac.uk/Pages/default.aspx>) through the Doctoral Training Centre (DTC) in Medical Devices, University of Strathclyde (<http://www.strath.ac.uk/simd/dtc/>). This funding was received by CAM. Funding was also provided by the University of Glasgow (<http://www.gla.ac.uk>) LKAS scholarship (<http://www.gla.ac.uk/services/postgraduateresearch/scholarships/kelvinsmith/>). This funding was received by LM. The funders had no role in study design, data collection and analysis, decision to publish, or preparation of the manuscript.

Reference

1. Macleod CA, Meng L, Conway BA, Porr B (2014) Reflex Control of Robotic Gait Using Human Walking Data. PLoS ONE 9(10): e109959. doi:[10.1371/journal.pone.0109959](https://doi.org/10.1371/journal.pone.0109959) PMID: [25347544](https://pubmed.ncbi.nlm.nih.gov/25347544/)



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