



Vertical Axis Wind Turbine Case Study: Costs and Losses associated with Variable Torque and Speed Strategies

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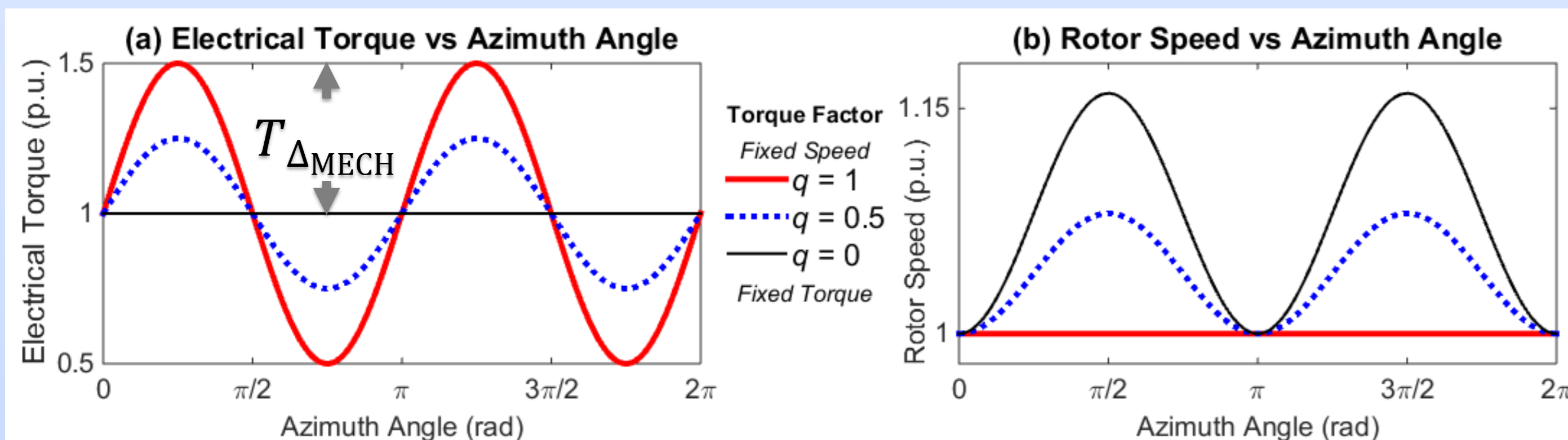
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1) OVERVIEW

- Generator Case Study for Large Offshore VAWT
- Directly Driven Permanent Magnet Generator (DD PMG)
- Modelling effect on costs & losses of inherent cyclic torque loading caused by periodic variation in aerodynamic load from rotor blades
- Strategies to control magnitude of electrical torque variation q ratio
- Equations for Copper and Iron Losses based on these strategies
- Relationship between cost and electrical torque variation allowed
- **Work presented is part of 3 year PhD into VAWT Drivetrains**

2) CYCLIC TORQUE

- Mechanical torque is modelled using a sinusoidal variation
 $T_{MECH} = \bar{T} + T_{\Delta} \sin(2\theta)$ [2 bladed rotor]
- Electrical torque control is parameterised by $q = \frac{T_{\Delta ELEC}}{T_{\Delta MECH}}$
- Torque control strategies can vary between two extremes: $q = 0$ (fixed T_{ELEC}) and $q = 1$ (fixed rotor speed)



- Depending on the strategy, there can be a torque imbalance between T_{MECH} and T_{ELEC} resulting in a changing rotor speed:
 $T_{MECH} - T_{ELEC} = J\alpha$
- The variance in electrical torque and/or rotor speed will effect the copper and iron losses experienced by the generator

Varying T_{ELEC} ($q > 0$)

Varying Current I

Copper Losses: $\int I^2 R$

$$P_{Cu} = R \left(\bar{I}^2 + \frac{1}{2} (q I_{\Delta})^2 \right)$$

Copper Losses $\propto q^2$

Varying Rotor Speed ($q < 1$)

=> Varying Electrical Frequency

Iron Losses depend on f_e

$$P_{Fe} = \sum (A_h \bar{f}_e + A_e \bar{f}_e^2) \hat{B}_{Fe_i}^2 m_i$$

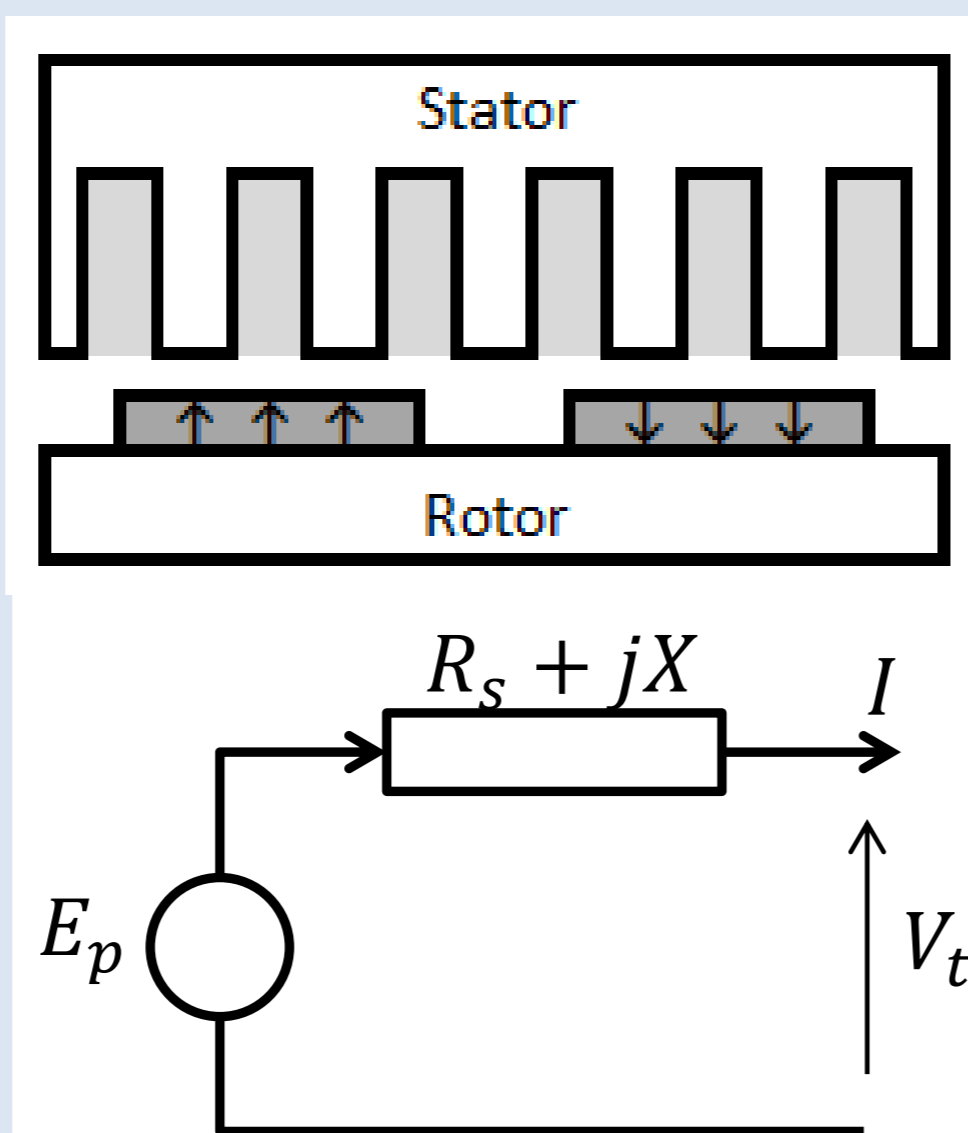
Both \bar{f}_e & \bar{f}_e^2 proportional to $(1 - q)$

Iron Losses $\propto (1 - q)$

- Generator cost depends on peak electrical torque loading

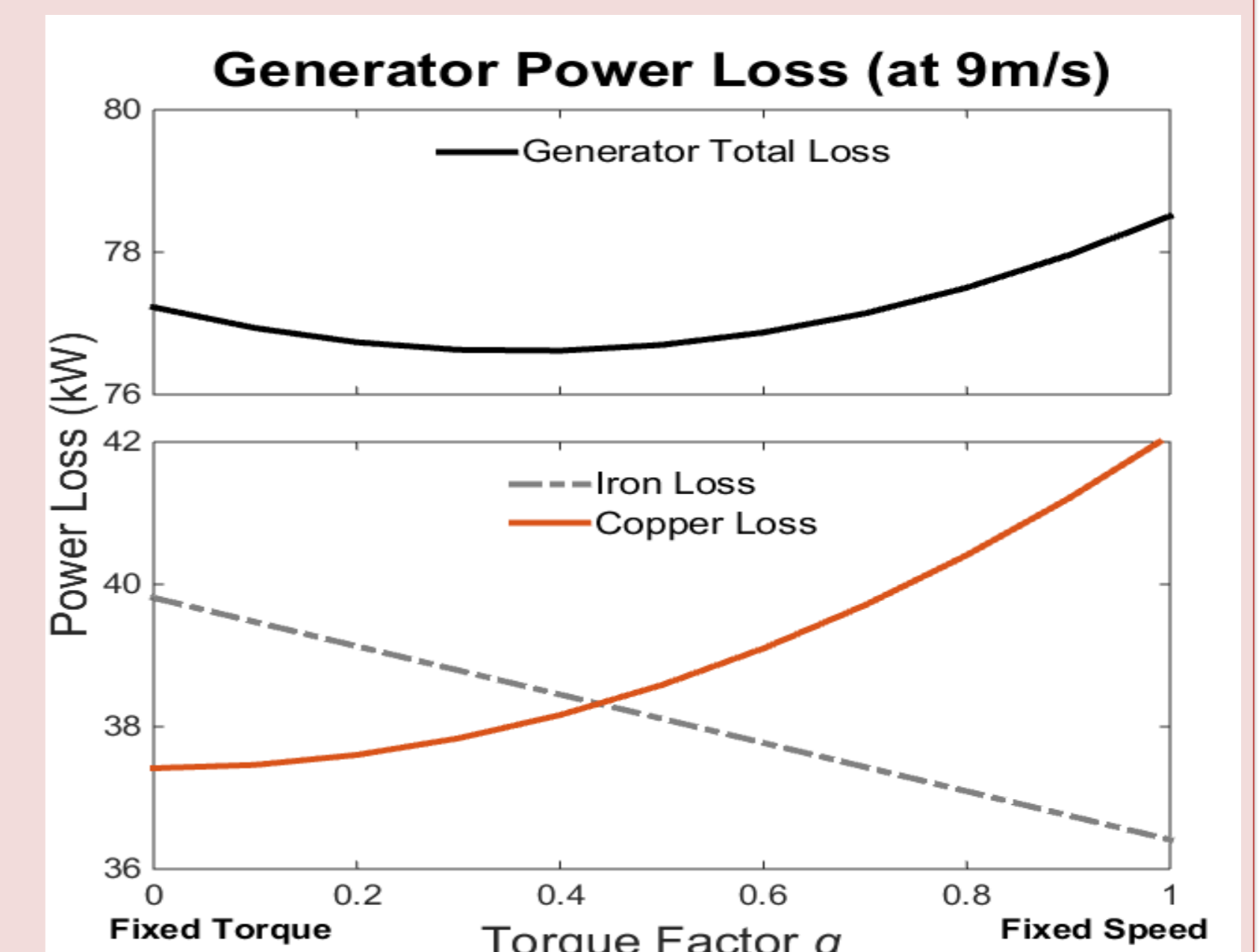
3) GENERATOR MODELLING

- Single pole pair of generator modelled
 - Electrical equivalent circuit in MATLAB
 - Magnetic Circuit Model in Finite Element Analysis package FEMM
- Programming Procedure:
 - MATLAB calculates generator sizings
 - FEMM calculates airgap flux density
 - MATLAB calculates equivalent circuit and resulting power output & losses
- Generator is 5MW DD PMG for use in offshore H-rotor VAWT, see paper for specs



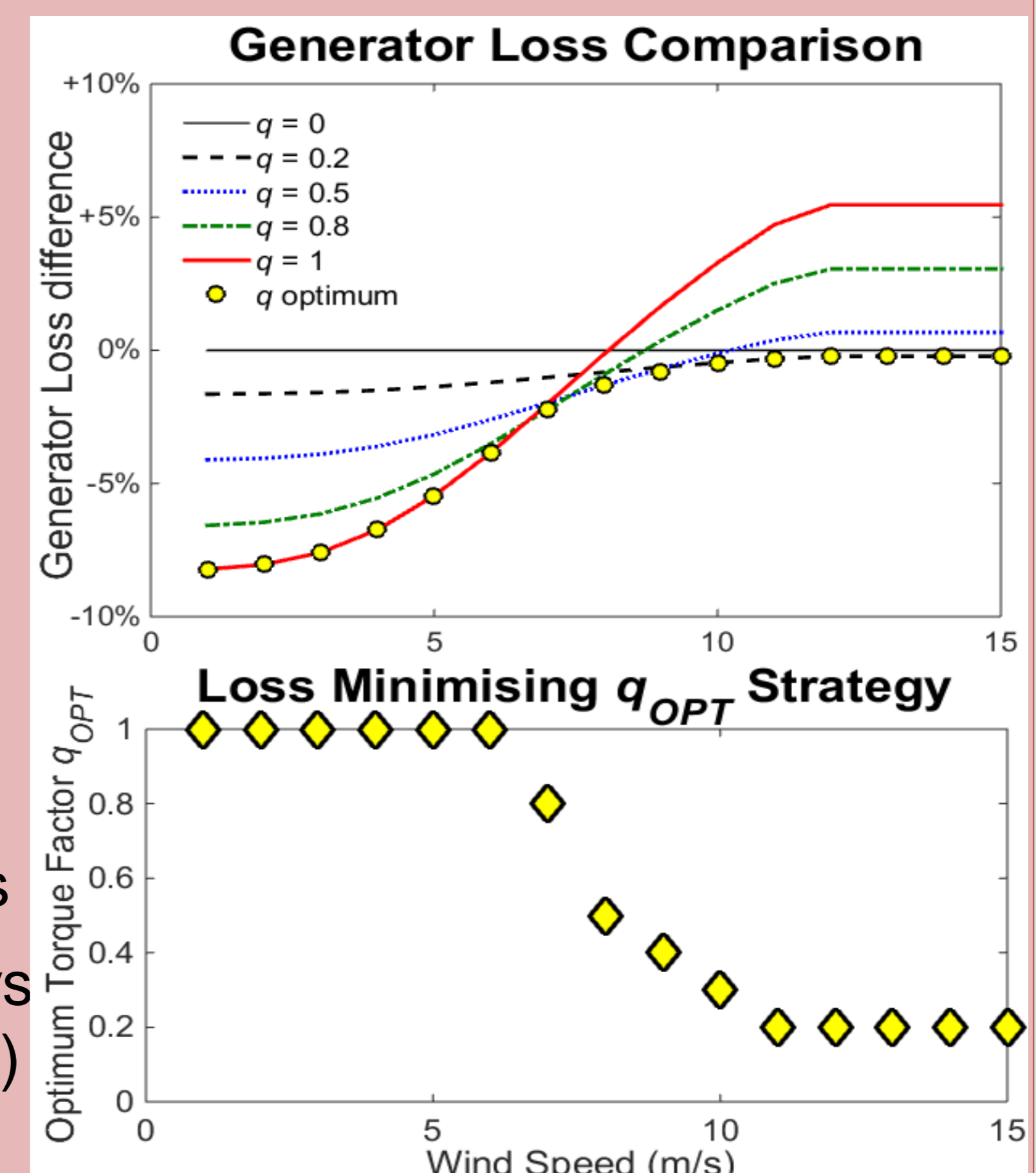
4) LOSSES FOR A FIXED WIND SPEED

- Comparing how losses vary for different torque factor q settings.
- Copper losses increase with q^2
- Iron losses decrease linearly with q
- At this speed losses are of similar magnitude
 - For 9m/s Losses minimised at $q=0.4$



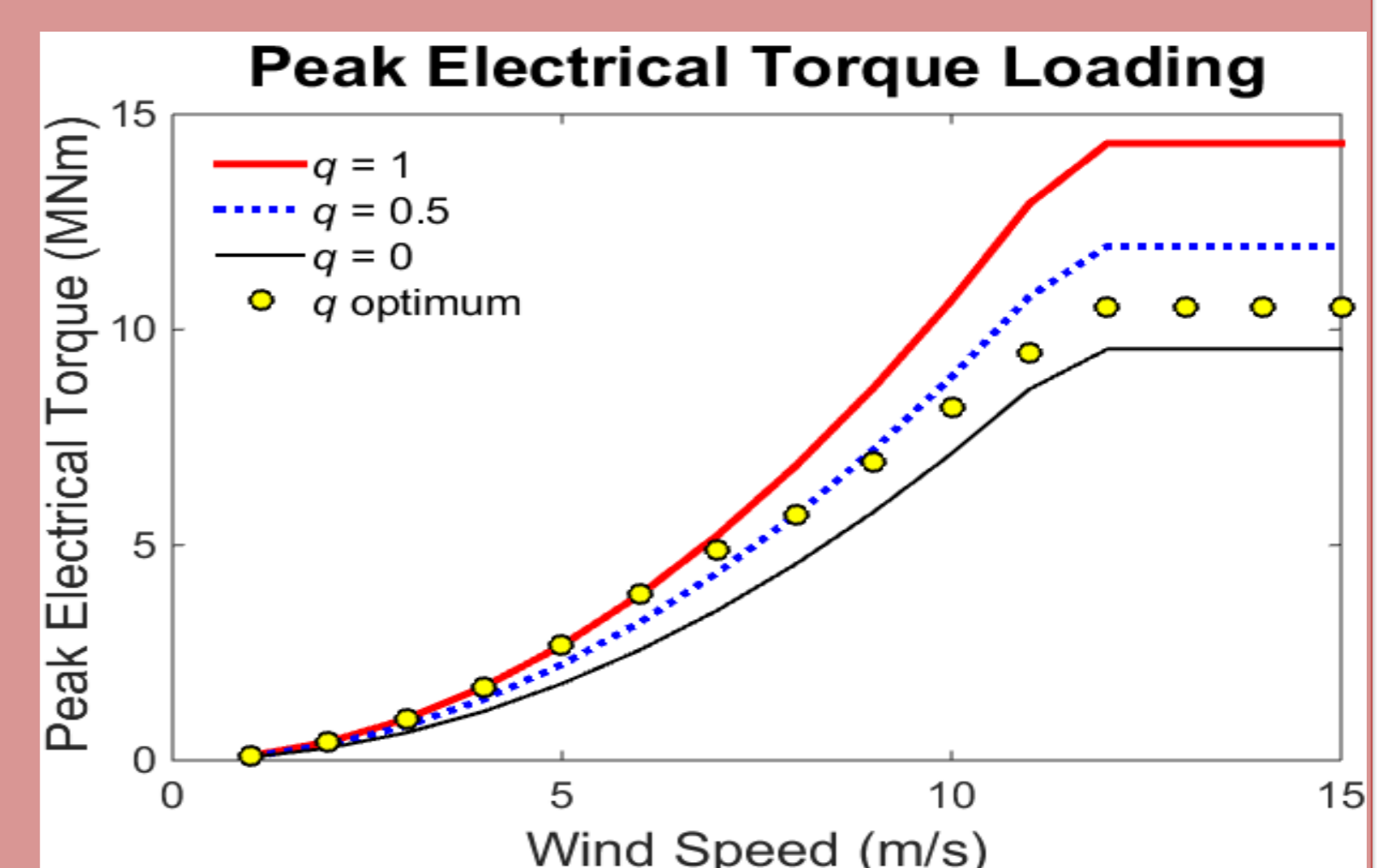
5) LOSS MINIMISATION STRATEGIES

- Calculate losses for each q strategy for whole range of wind speeds (% change vs fixed torque setting $q=0$)
- Losses minimised when:
 - $q = 1$ at low wind speeds
 - q near 0 at high speeds
 - $0 < q < 1$ medium speeds
- A loss minimisation strategy q_{OPT} can be setup which varies q with wind speed to minimise generator losses
- q_{OPT} 0.8% loss reduction vs best single q strategy ($q=0.4$) (1.5% vs $q=0$ fixed torque)



6) PEAK TORQUE AND COSTS

- Peak $T_{ELEC} \propto q$ (larger peak torque for fixed speed than fixed torque requires larger generator)
- q_{OPT} strategy: lower torque at rated => lower cost
- Restricting q at rated can lead to cost saving



7) CONCLUSIONS

- Adjusting torque control strategy can lead to loss reductions
- Biggest reductions allowing generator to adapt to wind speed
- Loss reduction: fixed speed at low wind speeds
low torque variation at higher speeds
- Future research: aerodynamic efficiency from speed variation (potential loss at low q , limited effect due to large rotor inertia); rescaling the generator (smaller generator with limit on q at rated)
- **PhD Overall Aim: optimise the VAWT powertrain design to minimise Cost of Energy & compare with commercial HAWTs**