

# 2 Stochastic Differential Equation Models for the Price 3 of European CO<sub>2</sub> Emissions Allowances

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12 **Abstract:** Understanding the stochastic nature of emissions allowances is crucial for risk  
13 management in emissions trading markets. In this study, we discuss the emissions allowances  
14 spot price within the European Union Emissions Trading Scheme: Powernext and European  
15 Climate Exchange. To compare the fitness of five stochastic differential equations (SDEs) to the  
16 European Union allowances spot price, we apply regression theory to obtain the point and  
17 interval estimations for the parameters of the SDEs. An empirical evaluation demonstrates that the  
18 mean reverting square root process (MRSRP) has the best fitness of five SDEs to forecast the spot  
19 price. To reduce the degree of smog, we develop a new trading scheme in which firms have to  
20 hand many more allowances to the government when they emit 1 unit of air pollution on heavy  
21 pollution days, versus one allowance on clean days. Thus, we set up the SDE MRSRP model with  
22 Markovian switching to analyze the evolution of the spot price in such a scheme. The analysis  
23 shows that the allowances spot price will not jump too much in the new scheme. The findings of  
24 this study could contribute to developing a new type of emissions trading.

25 **Keywords:** CO<sub>2</sub> emissions allowances; Spot price; Stochastic differential equations; Parameter  
26 estimation; Markovian switching

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## 28 1. Introduction

29 In 2005, an emissions trading scheme (ETS) was adopted by the European Union (EU ETS) to  
30 reduce CO<sub>2</sub> emissions by firms. According to the EU ETS, emissions-intensive firms have the right  
31 to release a certain amount of CO<sub>2</sub> into the atmosphere. This amount of permitted CO<sub>2</sub> emissions is  
32 allocated or auctioned to firms in the form of European Union Allowances (EUAs). The firm can  
33 emit 1 ton of CO<sub>2</sub> via one EUA, which is the tradable commodity in the EU ETS.

34 The participating firms are forced to hold adequate emissions allowances for their outputs. The  
35 carbon market provides new business opportunities for market intermediaries, such as emissions-  
36 related firms, brokers, traders, and risk management consultants. For these groups, a valid spot  
37 price model becomes increasingly important.

38 Recently, to bridge the gap between theory and actual price behavior, numerous empirical  
39 studies have investigated the time series of the emissions allowance price. Because the EU ETS is by  
40 far the largest, most developed market, empirical research has mainly focused on it. Paolella and  
41 Taschini [1] advocated using econometric frameworks to explain the heteroscedastic dynamics of  
42 emissions allowance prices under the EU ETS. The authors summarized the poor performance of  
43 previous methods, such as forecasting analysis based on demand/supply fundamentals, and  
44 supported the employment of a well-suited generalized autoregressive conditional  
45 heteroscedasticity (GARCH)-type model, which is suitable for depicting the stylized facts of daily

46 returns [1]. By employing econometric testing procedures and trading strategies, Daskalakis and  
47 Markellos demonstrated that the market for European CO<sub>2</sub> emissions allowances is inefficient [2].  
48 Furthermore, within the framework of a GARCH approach, Oberndorfer claimed that the stock  
49 performance of electricity firms has a positive effect on the EUA price [3]. On the other hand, some  
50 research has used the stochastic method to understand the stochastic properties of spot volatility. In  
51 the study of Daskalakis et al. [4], several different diffusion and jump-diffusion processes were  
52 fitted to the European CO<sub>2</sub> futures and options time series. This study suggested that the  
53 proscription of banking, which implies that emissions allowances cannot be used in the next phase,  
54 plays a significant role in determining the prices of EUA futures. Benz and Trück [5], employing a  
55 Markov switching model and AR-GARCH models, described the price dynamics and changes of  
56 the short-term allowance spot price. Similarly, Seifert et al. [6] built a stochastic equilibrium model  
57 to analyze the dynamics of CO<sub>2</sub> allowances spot prices. The authors proposed that the CO<sub>2</sub>  
58 emissions allowance spot price process should have a time- and price-dependent volatility  
59 structure. Recently, Kim et al. [7] estimated the dynamics of EUA futures prices based on Heston's  
60 stochastic volatility model with or without jumps, and their empirical results revealed three  
61 important features of EUA futures prices: significant stochastic volatility, noticeable leverage effect,  
62 and inclusion of jumps.

63 There is extensive literature concerning the economic and policy aspects of the EU ETS, but  
64 there is little explicit study of the dynamic emissions allowance price in the presence of market  
65 uncertainty. Moreover, rare previous studies have covered the stochastic nature of emissions  
66 allowances in Phase III. There are three periods in the EU-ETS protocol. Previous studies focused on  
67 Phases I and II, of which the main mechanism was free allocation based on past emissions.  
68 However, in Phase III, auctioning is expected to become the dominant allocation mechanism. It is  
69 necessary to examine adequate pricing models for EUA prices in this phase. Motivated by  
70 shortcomings of previous studies on carbon derivatives, we apply a new simple parameter  
71 estimation method for stochastic differential equations (SDEs) and discuss price forecast models  
72 based on different market data. We show that the mean reverting square root process (MRSRP) is  
73 the best of five SDEs to predict the EUA spot price.

74 In addition, the current ETS cannot reduce air pollution congestion (e.g., smog). This study is  
75 the first existing work to develop a new trading scheme to reduce air pollution congestion and  
76 explore the effect of air pollution on the EUA spot price by using the SDE MRSRP model with  
77 Markovian switching. The findings reveal that the spot price will not jump much under the new  
78 trading scheme when firms have to hand in more allowances on heavy pollution days.

79 The remainder of the paper is organized as follows. The following Section 2 presents the  
80 econometric analysis of EUA spot prices. Section 3 introduces a new parameter estimation  
81 methodology for SDEs and use empirical analysis to examine which SDE model is the best for  
82 reflecting the EUA spot price. Section 4 sets up an SDE model with Markovian switching to depict  
83 the EUA spot price considering the effect of air pollution. Finally, Section 5 concludes.

## 84 2. Econometric analysis of EUA spot prices

### 85 2.1 Discovery of the spot market

86 Under the EU ETS, there are two active EUA markets: the French Powernext and European  
87 Climate Exchange (ECX). In 2007, almost 79% of the EUA spot transactions were handled in the  
88 Powernext market, which plays a leading role in EUA price formation [4]. In both markets, spot  
89 contracts involve one EUA and are settled the day after the transaction. In our study, we use the  
90 datasets of daily settlement prices covering the period from 01/11/2012 to 31/10/2014 for Powernext  
91 and ECX, respectively. By comparing price levels from different trading platforms, we are able to  
92 study the potential impact of market conditions. Table 1 presents the descriptive statistics of the  
93 price levels and returns on EUA spot prices in both markets.

94 **Table 1.** Descriptive statistics of EUA price levels (P) and returns (R)

	Powernext		ECX	
	P	R	P	R
# Obs.	503	502	503	502
Mean	5.235	-0.0033	5.229	-0.0034
Median	5.120	0.010	5.120	0.000
Maximum	9.070	0.900	9.060	0.760
Minimum	2.700	-1.650	2.720	-1.590
Std. Dev.	1.053	0.218	1.046	0.216
Skewness	0.306	-1.019	0.320	-1.020
Kurtosis	3.145	11.073	3.155	10.385
Jarque–Bera	8.310*	1450.438**	9.087*	1227.364**
$\rho(1)$	0.992	0.000	0.993	0.000
$\rho(2)$	0.970	0.048	0.969	0.077
$\rho(3)$	0.938	-0.101	0.936	-0.130
$\rho(4)$	0.910	-0.142	0.907	-0.127

95 Note: one star (two stars) denotes (denote) significance at the 5% (1%) level;  $\rho(t)$  are autocorrelation coefficients at lag  $t$ .

96 The second (fourth) column of Table 1 shows the time-series mean, median, maximum,  
 97 minimum, standard deviation (Std. Dev.), skewness, kurtosis, Jarque–Bera test results, and  
 98 autocorrelation coefficients of EUA prices. The third (fifth) column shows the time-series statistics  
 99 of the returns of EUA prices. The coefficients of skewness and kurtosis indicate that  
 100 the distribution of prices is leptokurtic in two markets, which is confirmed by the Jarque–Bera test  
 101 results. The test leads to rejection of the null hypothesis that the spot price levels and returns come  
 102 from normal distribution. Additionally, autocorrelation coefficients decrease slowly in price levels,  
 103 which is consistent with possibly non-stationary, variation. The stationarity of the prices is  
 104 confirmed through three unit root tests (for a detailed description of these, see [8]). The test results  
 105 are presented in Table 2. The results of the augmented Dickey–Fuller (ADF) test and the Philips–  
 106 Peron (PP) test are not statistically significant, which means we cannot reject the null hypothesis  
 107 that the logarithmic EUA prices have a unit root. The results of the Kwiatkowski–Phillips–Schmidt–  
 108 Shin (KPSS) test reveal that we can reject the null hypothesis of stationarity at the 1% level. All test  
 109 results suggest that the logarithmic EUA prices in both markets are not stationary at statistically  
 110 significant levels.

111 **Table 2.** Unit root test on logarithmic EUA price levels

Test	Null Hypothesis	Powernext		ECX	
		C	TC	C	TC
ADF	Unit root	-2.780	-3.129	-2.773	-3.441
PP	Unit root	-2.858	-3.134	-2.870	-3.415
KPSS	Stationarity	0.577**	0.379**	0.748**	0.313**

112 Note: C (TC) refers to a constant (a time trend and constant) in the test equation. One star (two stars) denotes (denote)  
 113 significance at the 5% (1%) level. ADF is the augmented Dickey–Fuller test, PP refers to the Philips–Peron test, and KPSS  
 114 refers to the Kwiatkowski–Phillips–Schmidt–Shin test.

115 In addition, the descriptive analyses find that the EUA spot price behavior in the two trading  
 116 markets is very similar. This is as expected, because any temporal differences between the two  
 117 markets will be wiped out quickly by rational arbitrage. Actually, the EUA spot prices in Powernext  
 118 and ECX moved closely, for the absolute difference of the average mean is tiny. Furthermore, the  
 119 weekly returns between the two markets have a strong correlation coefficient, at almost 95%.

## 120 2.2 Dynamics of emissions allowance spot prices

121 On average, stock prices rise because the investor is rewarded for his or her money's  
 122 time value over a long period. There will be a substantial increase in EUA prices when specific  
 123 changes occur in a short period, such as policy or weather conditions. However, EUA prices tend to  
 124 revert to a normal level in the long run. The properties of spot prices are the result of general mean-  
 125 reversion behavior and the spikes in prices caused by the supply and demand shocks.

126 As discussed previously, the EUA spot prices might fit the validity of the standard Brownian  
 127 motion process. In line with the research of Chan et al. [9] and Dotsis et al. [10], we study the ability  
 128 of different popular diffusion continuous-time models to analyze the dynamics of the EUA spot  
 129 prices. It is necessary for the regulator to explore the dynamics to choose an appropriate pricing  
 130 model and design a new trading scheme.

131 Under historical probability  $P$ , the following SDE represents the underlying stochastic  
 132 properties of the EUA spot prices:

$$133 \quad ds_t = \mu(s_t, t)dt + \sigma(s_t, t)dW_t,$$

134 where  $s_t$  is the EUA spot price in time  $t$ ,  $W_t$  is a standard Wiener process,  $\mu(s_t, t)$  is the drift, and  
 135  $\sigma(s_t, t)$  is the diffusion coefficient. The drift and diffusion are assumed a general function of the  
 136 EUA spot price and time. We can obtain several different models by combining many assumptions  
 137 for the components of  $\mu(s_t, t)$  and  $\sigma(s_t, t)$ . There are five configurations, as follows:

138 Geometric Brownian motion process (GBMP)

$$139 \quad ds_t = \mu s_t dt + \sigma s_t dW_t \quad (2.1)$$

140 Square root process (SRP)

$$141 \quad ds_t = \mu s_t dt + \sigma \sqrt{s_t} dW_t \quad (2.2)$$

142 Mean reverting process (MRP)

$$143 \quad ds_t = k(\theta - s_t)dt + \sigma s_t dW_t \quad (2.3)$$

144 Mean reverting square root process (MRSRP)

$$145 \quad ds_t = k(\theta - s_t)dt + \sigma \sqrt{s_t} dW_t \quad (2.4)$$

146 Mean reverting logarithmic process (MRLP)

$$147 \quad d \ln s_t = k(\theta - \ln(s_t))dt + \sigma dW_t \quad (2.5)$$

148 It is well known that processes (2.1) and (2.2) have been used widely to depict the evolution of  
 149 stock pricing, options, and commodity price indexes (e.g., [11-13]). In processes (2.1) and (2.2),  $\mu$  is  
 150 the expected return of the asset per unit of time and  $\sigma$  is the volatility. However, the other three  
 151 processes have mean reverting drifts. In Equations (2.3)–(2.5),  $k$  is the speed of mean reversion,  $\theta$   
 152 denotes the unconditional mean, and  $\sigma$  measures the asset price volatility. Bierbrauer et al. [14] used  
 153 model (2.3) to test electricity spot prices based on one-factor and two-factor models using data from  
 154 the German EEX market. Models (2.4) and (2.5) have been very popular for describing the interest  
 155 rate and volatility in the literature (e.g., [15-16]).

### 156 3. EUA spot price estimation

#### 157 3.1 Parameter estimation for the SDE

158 In this section, we describe general parameter estimation methodology for the five SDE  
 159 models, (2.1)–(2.5), based on least squares techniques. This method has the same accuracy and  
 160 efficiency as the more complicated maximum likelihood estimation and is easier to apply [17]. We  
 161 start with the general formulas from least squares theory and then, we develop formulas for the  
 162 point and interval estimations for the MRSRP model. The process to develop the estimation for the  
 163 other four models is similar, and thus, is omitted in this section.

164 We recall the MRSRP in the form of an Itô SDE:

$$165 \quad ds_t = k(\theta - s_t)dt + \sigma\sqrt{s_t}dW_t, \quad (3.1)$$

166 where  $k$ ,  $\theta$ , and  $\sigma$  are positive constants and  $W_t$  is a scalar Brownian motion. We assume that the  
 167 initial condition  $S(0) \geq 0$ . To apply a numerical method to SDE (3.1), it needs to be replaced by the  
 168 equivalent problem

$$169 \quad ds_t = k(\theta - s_t)dt + \sigma\sqrt{|s_t|}dW_t. \quad (3.2)$$

170 Since the method could break down if negative values were supplied to the square root  
 171 function, given stepsize  $\Delta t$ , by applying the Euler–Maruyama method to (3.2) and setting  $s_0 = S(0)$ ,  
 172 we obtain approximations  $s_n \approx S(t_n)$ , where  $t_n = n\Delta t$  can be computed by

$$173 \quad s_{n+1} = s_n(1 - k\Delta t) + k\theta\Delta t + \sigma\sqrt{|s_n|}\Delta W_n, \quad (3.3)$$

174 where  $\Delta W_n = W_{n+1} - W_n$ .

175 Equation (3.3) can be rewritten as

$$176 \quad y_{n+1} = \alpha v_{n+1} + ku_{n+1} + \sigma Z_{n+1}, \quad (3.4)$$

177 where  $y_{n+1} = \frac{s_{n+1} - s_n}{\sqrt{\Delta t |s_n|}}$ ,  $\alpha = k\theta$ ,  $v_{n+1} = \sqrt{\frac{\Delta t}{|s_n|}}$ ,  $u_{n+1} = \sqrt{\Delta t |s_n|}$  and  $Z_{n+1} \sim N(0,1)$ .

178 This is a multiple linear regression model and since data points  $s_n$  and stepsize  $\Delta t$  are  
 179 provided, we can use a regression theorem to estimate the parameters  $k$ ,  $\alpha$ , and  $\sigma$ .

180 Rawlings et al. [18] discussed multiple linear regression in general matrix form:

$$181 \quad Y = X\beta + \varepsilon, \quad (3.5)$$

182 where

$$183 \quad Y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}, \quad X = \begin{pmatrix} 1 & x_{11} & x_{12} & \cdots & x_{1p} \\ 1 & x_{21} & x_{22} & \cdots & x_{2p} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n1} & x_{n2} & \cdots & x_{np} \end{pmatrix}, \quad \beta = \begin{pmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_p \end{pmatrix}, \quad \varepsilon = \begin{pmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{pmatrix}.$$

### 184 3.1.1 Point estimations

185 The calculations work equally well for (3.4), which can be written in matrix form (3.5), where  $Y$   
 186 and  $\varepsilon$  remain the same while  $X$  and  $\beta$  become

$$187 \quad X = \begin{pmatrix} v_1 & u_1 \\ v_2 & u_2 \\ \vdots & \vdots \\ v_n & u_n \end{pmatrix}, \quad \beta = \begin{pmatrix} \alpha \\ k \end{pmatrix}.$$

188 Then,

$$189 \quad \begin{pmatrix} \hat{\alpha} \\ \hat{k} \end{pmatrix} = \hat{\beta} = (X^T X)^{-1} (X^T Y) \\
 190 \quad = \frac{1}{\sum v_k^2 \sum u_k^2 - (\sum v_k u_k)^2} \begin{pmatrix} \sum u_k^2 \sum v_k y_k - \sum u_k v_k \sum u_k y_k \\ \sum v_k^2 \sum u_k y_k - \sum u_k v_k \sum v_k y_k \end{pmatrix}. \quad (3.6)$$

191 Then, we can obtain point estimations

$$192 \quad \hat{\theta} = \frac{\hat{\alpha}}{\hat{k}} = \frac{\sum u_k^2 \sum v_k y_k - \sum u_k v_k \sum u_k y_k}{\sum v_k^2 \sum u_k y_k - \sum u_k v_k \sum v_k y_k}, \quad (3.7)$$

$$193 \quad \hat{k} = \frac{\sum v_k^2 \sum u_k y_k - \sum u_k v_k \sum v_k y_k}{\sum v_k^2 \sum u_k^2 - (\sum u_k v_k)^2}. \quad (3.8)$$

194 We obtain  $\hat{\theta}$  by dividing the two point estimations here, which is a sensible thing to do. The  
 195 results are in accordance with the estimations taken from  $\frac{\partial SS}{\partial k} = \frac{\partial SS}{\partial \theta} = 0$ , where

$$196 \quad SS = \sum (y_k - k\theta v_k - ku_k)^2.$$

197 3.1.2 Variance of estimated parameters

198 To obtain the interval estimations for the parameters  $\alpha$  and  $k$ , we need to calculate the variance  
 199 of  $\hat{\beta}$  using the formula

200 
$$var(\hat{\beta}) = (X^T X)^{-1} \sigma^2, \tag{3.9}$$

201 where  $\sigma^2$  can be estimated using

202 
$$\hat{\sigma}^2 = \frac{(Y - X\hat{\beta})^T (Y - X\hat{\beta})}{n - p}, \tag{3.10}$$

203 where  $p$  is the number of parameters, and thus,  $p$  is 2 in the MRSRP model. Equation (3.10) can be  
 204 simplified as

205 
$$\hat{\sigma}^2 = \frac{Y^T Y - Y^T X \hat{\beta}}{n - 2}. \tag{3.11}$$

206 Equation (3.11) can be written as

207 
$$\hat{\sigma}^2 = \frac{1}{n - 2} (\sum y_k^2 - (\sum y_k v_k) \hat{\alpha} - (\sum y_k u_k) \hat{k}).$$

208 Substituting (3.6) in (3.11) yields

209 
$$\hat{\sigma}^2 = \frac{\sum y_k^2 \sum v_k^2 \sum u_k^2 - \sum y_k^2 (\sum v_k u_k)^2 - \sum u_k^2 (\sum v_k y_k)^2 - \sum v_k^2 (\sum u_k y_k)^2 + 2 \sum u_k y_k \sum v_k y_k \sum u_k v_k}{(n - 2)(\sum v_k^2 \sum u_k^2 - (\sum u_k v_k)^2)}$$

210  $\hat{\sigma}^2$  is an asymptotically unbiased estimator to  $\sigma^2$  (i.e.,  $\hat{\sigma}_n^2 \rightarrow \sigma^2$  as  $n \rightarrow \infty$ ).

211 Thus, we obtain

212 
$$var(\hat{\beta}) = var \begin{pmatrix} \hat{\alpha} \\ \hat{k} \end{pmatrix} = \frac{1}{\sum v_k^2 \sum u_k^2 - (\sum u_k v_k)^2} \begin{pmatrix} \sum u_k^2 & -\sum u_k v_k \\ -\sum u_k v_k & \sum v_k^2 \end{pmatrix} \hat{\sigma} \tag{3.12}$$

213 3.1.3 Interval estimation for  $k$

214 The 503 observations in our study is a sufficiently large number for the 95% confident interval  
 215 (CI) for  $k$  to be

216 
$$\hat{k} \pm 1.96 \sqrt{var(k)} = \frac{\sum v_k^2 \sum u_k y_k - \sum u_k v_k \sum v_k y_k}{\sum v_k^2 \sum u_k^2 - (\sum u_k v_k)^2} \pm 1.96 \sqrt{\frac{\sum v_k^2 \hat{\sigma}}{\sum v_k^2 \sum u_k^2 - (\sum u_k v_k)^2}}$$

217 Note that as  $n \rightarrow \infty$ , this 95% CI tends to

218 
$$\frac{\int_0^T \frac{1}{|s_t|} dt (s_T - s_0) - T \int_0^T \frac{1}{|s_t|} ds}{\int_0^T \frac{1}{|s_t|} dt \int_0^T |s_t| dt - T^2} \pm 1.96 \sqrt{\frac{\hat{\sigma}_n^2 \int_0^T \frac{1}{|s_t|} dt}{\int_0^T \frac{1}{|s_t|} dt \int_0^T |s_t| dt - T^2}} \tag{3.13}$$

219 We obtain the daily data of EUA spot prices and can work out the CI for  $k$  using Equation  
 220 (3.13). We use the same methodology to estimate the parameter of other SDE models. Table 3  
 221 displays the estimated parameters, t-statistics results (the latter in brackets) and the Bayesian  
 222 information criterion (BIC) for the five models under scrutiny for the full data of the study.

223 **Table 3.** Estimation results of five SDE models: 01/11/2012–31/10/2014

Para meter	Powernext					ECX				
	GBMP	SRP	MRP	MRSRP	MRLP	GBMP	SRP	MRP	MRSRP	MRLP
$\mu$	0.00058* (0.287)	-0.0006 (-0.361)				0.00056* (0.278)	-0.0006 (-0.349)			
$k$			0.032**	0.029**	0.029**			0.03**	0.029**	0.029**

			(3.287)	(3.126)	(2.952)			(3.372)	(3.148)	(2.940)
$k\theta$			0.163** (3.421)	0.153** (3.122)	0.048** (2.900)			0.165** (3.506)	0.151** (3.141)	0.047** (2.888)
$\sigma$	0.046	0.099	0.045	0.098	0.046	0.045	0.098	0.045	0.097	0.046
BIC	-1666	-881	-1671	-1884	-1647	-1670	-895	-1676	-1899	-1649

224 Note: One star (two stars) denotes (denote) significance at the 5% (1%) level. GBMP is geometric Brownian motion  
 225 process, SRP is square root process, MRP is mean reverting process, MRSRP is mean reverting square root process, and  
 226 MRLP refers to mean reverting logarithmic process.  
 227

228 The results lead to several interesting insights. First, it is obvious that the mean reverting  
 229 model is better than the non-mean reverting model regarding parameter significance and the BIC in  
 230 both markets. The findings indicate that the model's goodness of fit is increased by the addition of  
 231 mean reversion. The results are consistent with the previous descriptive results that the EUA spot  
 232 prices are the non-normality of returns and non-stationarity. Second, for mean-reversion models,  
 233 the BIC of the MRSRP model is smaller than that of the other two mean-reversion models, and thus,  
 234 the MRSRP model is slightly better than the MRP and MRLP models. Third, it should be noted that  
 235 parameter  $\mu$  in SRP is not statistically significant. Therefore, we further investigate the fitness of the  
 236 other four models in the following Subsection 3.2.

### 237 3.2 Spot price estimation

238 To compare the four models further, we perform the following empirical analysis. First, we  
 239 calculate theoretical prices using software R for the EUA spot prices in Powernext and ECX based  
 240 on the four SDE models. The period analyzed is extended from 01/11/2012 to 31/10/2014.  
 241 Subsequently, we assess the accuracy of the price models by calculating the mean absolute percent  
 242 error (MAPE) between theoretical and actual spot prices. The MAPE expressed as a percentage is  
 243 defined as

$$244 \text{MAPE} = \frac{100}{N} \sum_{t=1}^N \frac{F(T)_t^f - F(T)_t^a}{F(T)_t^a},$$

245 where  $N$  is the number of observations,  $F(T)_t^f$  is the theoretical spot price, while  $F(T)_t^a$  is the actual  
 246 spot price. In addition, for comparison purposes, we compute the mean squared pricing error  
 247 (MSE) for the whole period.

248 As shown in Table 4, the results present substantial pricing errors. In particular, the MAPE for  
 249 MRSRP is 0.1798% and 0.188% in Powernext and ECX, respectively, and the MSE is 0.032% and  
 250 0.035%, respectively. These errors for MRSRP are far smaller than are those for other models. The  
 251 results suggest that the pricing errors of MRSRP for the spot prices in the two markets are well  
 252 below those of the other three models. In summary, it is clear that the MRSRP has the best fitness of  
 253 the five models to forecast EUA spot prices.

254 **Table 4.** Comparison of different models for EUA spot prices

	Powernext				ECX			
	GBMP	MRP	MRSRP	MRLP	GBMP	MRP	MRSRP	MRLP
MAPE (%)	0.4433	0.1889	0.1798	0.2517	0.334	0.211	0.188	0.297
MSE (%)	0.1965	0.0356	0.032	0.063	0.116	0.045	0.035	0.088

## 255 4. MRSRP with Markovian switching

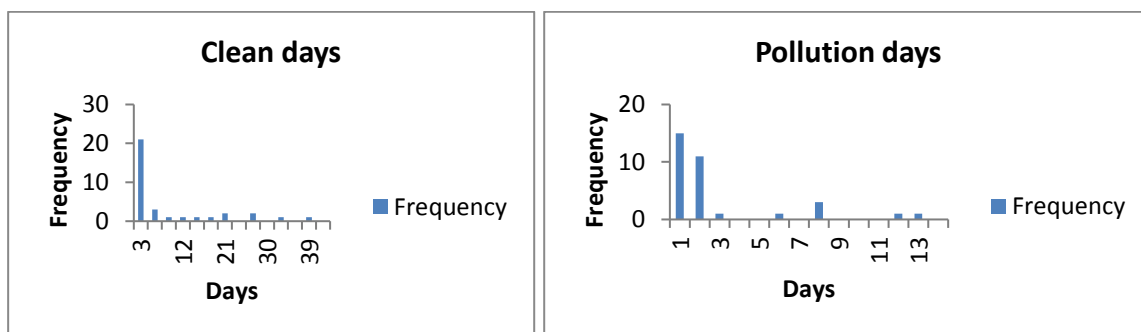
### 256 4.1 Effect of air pollution on the EUA spot price

257 Air pollution is a major environmental and social problem in almost all large cities worldwide  
 258 and “smog” became a serious problem in China in 2013. Smog occurs when emissions reach a  
 259 certain concentration that impairs property, public health, and ecosystems. A recent US study  
 260 found that about 4,000 Chinese people were killed by air pollution per day. Therefore, finding an  
 261 efficient policy instrument is increasingly prominent in the country’s overall development plans.  
 262 The EU ETS is one such attempt to alleviate air pollution from emissions via a financial market  
 263 mechanism. However, the current EU ETS cannot effectively solve the problem of pollution  
 264 congestion (e.g., smog).

265 To reduce the degree of smog, we suggest applying a new scheme to update the current ETS. In  
 266 the current ETS, a firm hands in one allowance to the regulator when the firm emits 1 ton of air  
 267 pollution. Meanwhile, in the new trading scheme, a firm has to hand in two or more emissions  
 268 allowances to the regulator, when the firm emits 1 ton of air pollution on heavy pollution days (e.g.,  
 269 daily mean concentration exceeds  $58 \mu\text{g}/\text{m}^3$ ), compared to only one allowance on clean days. In  
 270 other words, under the new scheme, when pollution congestion (e.g., smog) occurs, the EUA spot  
 271 price is higher than it is on clean days. Rationally, a firm will reduce emissions in pollution days  
 272 and ease the degree of smog in the environment. Then, the spot price changes according to the air  
 273 conditions, which can help to control excessive air pollution from emissions through a self-  
 274 regulating mechanism. Therefore, it is necessary to examine the pricing models for EUA derivatives  
 275 in this new environment. To depict how the EUA spot price evolves under the new trading scheme,  
 276 we apply the SDE MRSRP with Markovian switching.

277 Air conditions affect the EUA spot price under the new scheme. To describe air pollution levels  
 278 simply, based on a regulation of the UK Department for Environment, Food & Rural Affairs, a clean  
 279 day is defined as having a daily mean concentration of less than  $58 \mu\text{g}/\text{m}^3$ , otherwise, it is a  
 280 pollution day. The frequency of “clean days” and “pollution days” in the UK in 2013 is shown in  
 281 the following Figure 1.

282



283

284

Figure 1. UK air condition in 2013

285

Source: <http://www.eea.europa.eu/data-and-maps/data/aireporting#tab-data-by-country>

286 As Figure 1 shows, “1” denotes clean days and “2” denotes pollution days. The probability  
 287 distribution of the duration (in days) from clean to pollution (or from pollution to clean) follows an  
 288 exponential distribution. Thus, we can apply the Markov chain to describe the switching.

289

#### 4.2 Markovian switching

290 The Markovian switching system was first introduced by Krasovskii and Lidskii [19]. This kind  
 291 of stochastic model describes different types of dynamic systems that might experience abrupt  
 292 changes in their parameters and structures. The advantages in modeling have been reported in the  
 293 literature (see Mao [20], Boukas [21], and references therein).

294 We let  $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0}, \mathbb{P})$  be a complete probability space with filtration  $\{\mathcal{F}_t\}_{t \geq 0}$ , which satisfies  
 295 the usual constraints (i.e., it is increasing right-continuous while  $\mathcal{F}_0$  contains all  $\mathbb{P}$  – null sets).  
 296 Let  $r(t), t \geq 0$  be a right continuous Markov chain on the probability space, which takes values in  
 297 finite state space  $\mathfrak{s} = \{\text{clean}, \text{pollution}\}$  with the following generator



$$\Gamma = \begin{pmatrix} -v_{cp} & v_{cp} \\ v_{pc} & -v_{pc} \end{pmatrix}$$

Here,  $v_{cp} > 0$  is the transition rate from the state of “clean” to that of “pollution,” while  $v_{pc} > 0$  is the transition rate from the state of “pollution” to that of “clean,” and thus,

$$\mathbb{P}\{r(t + \delta) = \text{pollution} | r(t) = \text{clean}\} = v_{cp}\delta + o(\delta),$$

and

$$\mathbb{P}\{r(t + \delta) = \text{clean} | r(t) = \text{pollution}\} = v_{pc}\delta + o(\delta),$$

where  $\delta > 0$ .

In our case, the Markov chain  $r(\cdot)$  is independent of Brownian motion  $B(\cdot)$ .

As is well known, almost every sample path of Markov chain  $r(\cdot)$  is a right-continuous step function [22]. More precisely, there is a sequence  $\{\tau_k\}_{k \geq 0}$  of finite-valued and  $\mathcal{F}_t$ -stopping times, such that  $0 = \tau_0 < \tau_1 < \dots < \tau_k \rightarrow \infty$  almost certainly and  $r(t)$  can be expressed as

$$r(t) = \sum_{k=0}^{\infty} r(\tau_k) I_{[\tau_k, \tau_{k+1})}(t).$$

Moreover, given that  $r(\tau_k) = \text{clean}$ , random variable  $\tau_{k+1} - \tau_k$  follows exponential distribution with parameter  $v_{cp}$ , namely,

$$\mathbb{P}(\tau_{k+1} - \tau_k \geq T | r(\tau_k) = \text{clean}) = e^{-v_{cp}T}, \forall T \geq 0,$$

Meanwhile, given that  $r(\tau_k) = \text{pollution}$ , random variable  $\tau_{k+1} - \tau_k$  follows exponential distribution with parameter  $v_{pc}$ , namely,

$$\mathbb{P}(\tau_{k+1} - \tau_k \geq T | r(\tau_k) = \text{pollution}) = e^{-v_{pc}T}, \forall T \geq 0.$$

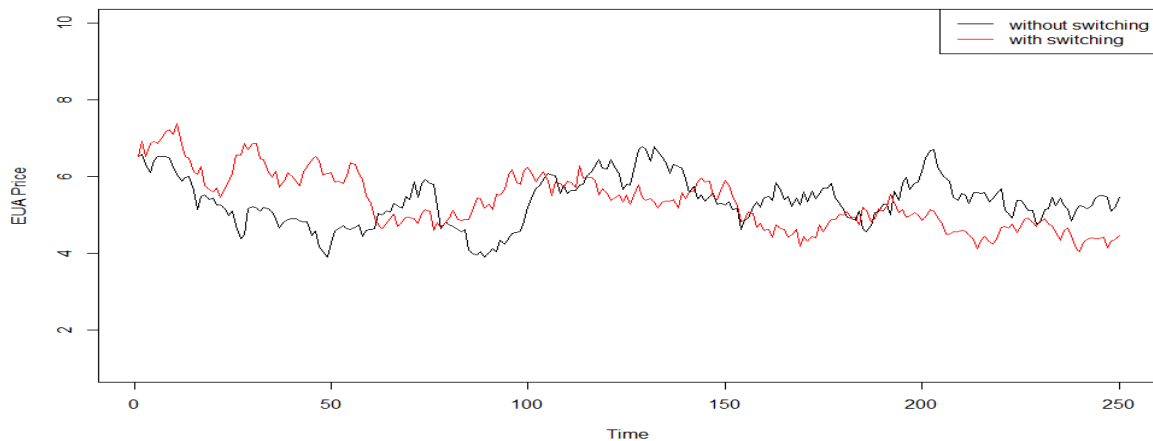
We can easily simulate the sample paths of the Markov chain using the exponential distributions.

#### 4.3 Simulation of the spot price in the new trading scheme

Having reviewed the details of the Markov chain, we now study the SDE MRSRP model with Markov switching. Our aim is to compute the EUA spot prices under the new trading scheme if the firm has to hand many more emissions allowances to the regulator for pollution days. Then, we can compare the spot prices between the current and new trading schemes.

We assume the system parameter  $\sigma$  is constant. Given that, on clean days, the parameter  $k_c = 0.021$ , and on pollution days, the parameter  $k_p = 0.037$ . We estimate the transition rate from clean to pollution using  $v_{cp} = 0.127$  and the transition rate from pollution to clean using  $v_{pc} = 0.347$ .

In 2013, there were 250 business days in the EU ETS. Moreover, the starting level of the spot price on 2 January 2013 was 6.52, and we set it as the starting level for 2013, that is,  $p_1 = 6.52$ . In this study, we design a function in R-software to perform simulations of the spot price for the SDE MRSRP model (2.4) with Markovian switching with step time  $\Delta t = 1$ . Combined with the spot price of the current scheme without considering the effect of air pollution, we obtain Figure 2.



**Figure 2.** Comparison of EUA spot prices under different schemes

331

332

333 Figure 2 depicts the computer simulation of the EUA spot price in 2013. The black line is the  
 334 simulation of the EUA spot price without switching, while the red line is the simulation of the EUA  
 335 spot price with switching. The former is the EUA spot price under the current EU ETS scheme; the  
 336 latter is the EUA spot price under the new trading scheme considering the effect of air pollution. As  
 337 shown in Figure 2, the red line is more stable than the black one. The spot prices do not jump too  
 338 much under the new ETS. Thus, it would help to improve the ETS and achieve the primary goal—  
 339 reduction of air pollution by the government at least possible cost.

## 340 5. Discussions and Conclusions

341 This study examines the stochastic nature of emissions allowances under different schemes  
 342 pertaining to the relevant models that previous studies failed to achieve. First, we analyze the two  
 343 primary markets for CO<sub>2</sub> emissions allowance spot price under the scheme of the EU ETS:  
 344 Powernext and ECX. In line with previous studies focused on the EUA spot prices in Phases I and II  
 345 (e.g., [4]–[6]), the empirical analysis provides evidence that EUA spot prices display non-stationary  
 346 behavior in Phase III. In addition, the EUA spot prices approximately follow geometric Brownian  
 347 motion. An empirical evaluation using actual market data demonstrates that the MRSRP has the  
 348 best fitness of the five SDEs for representing the dynamics of the EUA spot prices.

349 More importantly, to reduce smog, this study develops a new scheme in which a firm has to  
 350 hand many more allowances to the regulator when it emits one unit of air pollution on heavy  
 351 pollution days, compared to only one allowance on clean days. In section 4, we show that under the  
 352 new trading scheme, the air condition can be improved in the pollution days. Using real-life data,  
 353 we find that the time gap between clean days and pollution days follows exponential distribution,  
 354 and therefore we develop a SDE MRSRP model with Markovian switching to predict the spot prices  
 355 in the new trading scheme. The model simulation has shown that the spot prices are expected to not  
 356 jump too much under the new trading system.

357 We contribute to the literature in three ways. First, we explore the fitness of the SDEs mainly  
 358 based on the data of the Phase III of ETS, which has rarely been covered in previous studies.  
 359 Second, this study is one of the earliest works to develop a new trading scheme with two different  
 360 states to reduce pollution congestion. The theoretical conception would serve as the basis for more  
 361 in-depth studies in the future and as a tool for formulating policies aimed at reducing pollution  
 362 disasters. Third, although a lot of research has been done on spot price modeling, none of the  
 363 existing literature used SDE with Markovian switching to study the effect of the air condition, and  
 364 this model is better in our study because there are two different air conditions under our new  
 365 scheme.

366 There are several important implications arising from this study for the regulators and  
 367 managers. First, the current CO<sub>2</sub> emissions market behaves like the MRSRP model. One explanation  
 368 is that the supply of EUA is fixed in ETS, when there is an increase in demand due to policy or  
 369 weather conditions, pushing prices higher. When demand returns to normal levels, prices will fall.

370 Besides the mean reverting characteristic, the spot price is proportion to its variance in the current  
371 CO<sub>2</sub> emission market [7]. This important property improves the assessment of production costs  
372 incorporating CO<sub>2</sub> costs since the introduction of emission trading system, or supports emissions-  
373 related investment decisions. The ability of managers to predict the EUA spot prices helps to  
374 maintain market efficiency and sustain a healthy trading volume. Second, the estimations in this  
375 study showed that the EUA price would not fluctuate too much under the new trading scheme,  
376 which greatly enhances the political acceptability of the scheme. Specifically, it implies that the new  
377 trading scheme does not lead to more complications in the pricing of emission allowances nor to the  
378 adverse effect on market liquidity and efficiency. We suggest the government to apply our scheme  
379 to upgrade the current trading scheme.

380 The study has methodological limitations. Primarily, we compare only five SDEs to the EUA  
381 spot prices, neglecting other SDEs. In addition, for lack of the EUA price, we cannot compare  
382 the theoretical and actual spot price under the new scheme. When future data become available in  
383 years to come, it would be worthwhile to reperform the work in greater detail than the current data  
384 allow. Finally, more advanced econometric techniques to estimate the model parameters, including  
385 the MCMC method, will be widely elaborated on in the future.

386  
387

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