

NPL



University of  
**Strathclyde**  
Engineering



EMRP

European Metrology Research Programme  
• Programme of EURAMET  
The EMRP is jointly funded by the EMRP participating countries  
within EURAMET and the European Union



# *Sensitivity Analysis of Sensor Networks for Distribution Grids*

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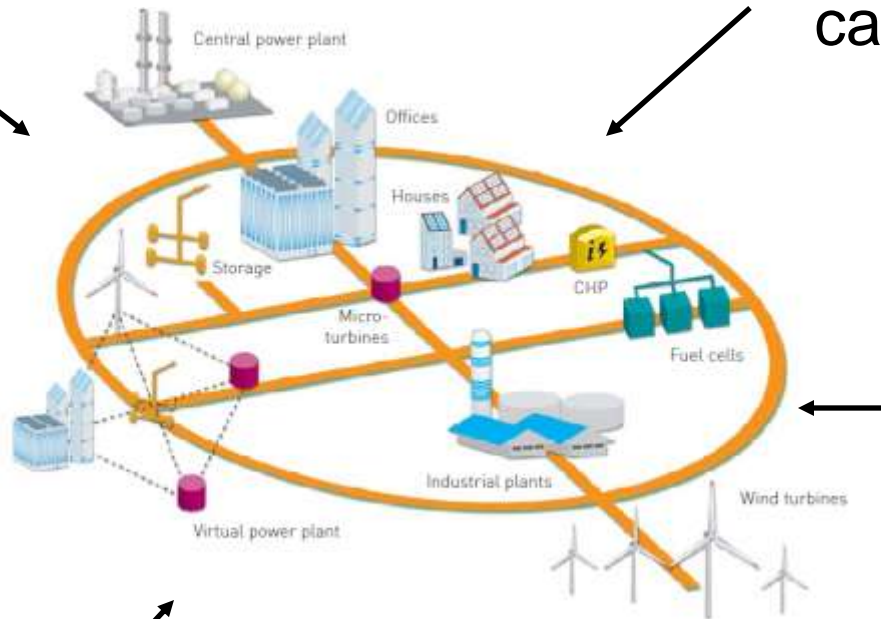
26 June, 2013

# Sensor Coverage in Electricity Networks

How to handle  
Too much data ?

Which sensors  
can be removed ?

How many  
Sensors are  
Needed ?



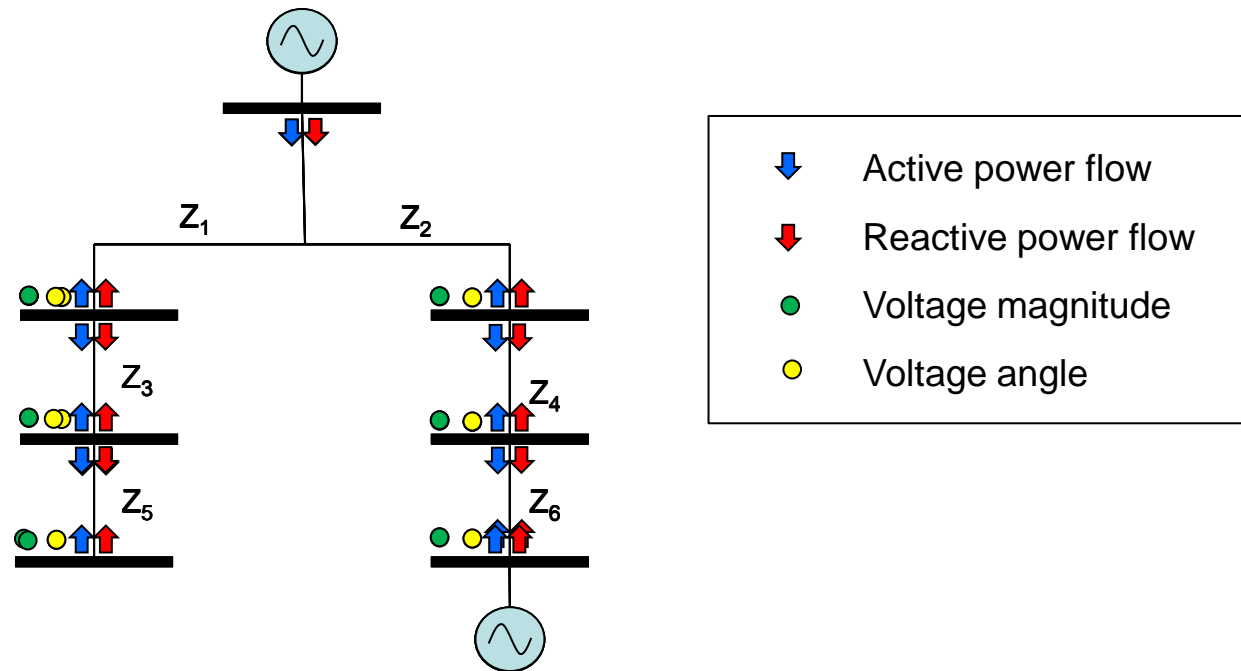
What  
happens  
when a given  
sensor fails ?

Estimate unknown  
Cable impedances

How accurate  
Should a given  
Sensor be ?

# State estimation

- From limited power flow and voltage measurements derive voltage magnitudes and angles at each bus
- Derive power flow at every node in the network from estimated impedances and calculated voltages.



# Sensitivity Analysis



Suppose the state estimation problem is given as

$$\min_{\mathbf{x}} (\mathbf{z} - H\mathbf{x})^T (\mathbf{z} - H\mathbf{x}) \quad \text{Subject to: } E\mathbf{x} = \mathbf{y}$$

Where:

$\mathbf{x}$  are the parameters to be estimated

$H$  is a (linearized) observation matrix

$E$  is a constraint matrix

$\mathbf{z}$  and  $\mathbf{y}$  are vectors storing measured data values

The solution depends linearly on  $\mathbf{y}$  and  $\mathbf{z}$ :  $\mathbf{x} = S_z \mathbf{z} + S_y \mathbf{y}$

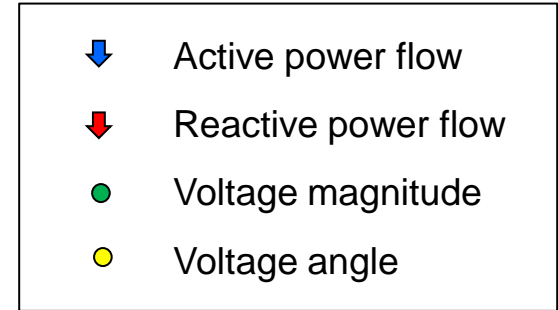
And the variance matrix is:

$$V_{\mathbf{x}} = S_z V_z S_z^T + S_y V_y S_y^T$$

( $\mathbf{z}$  and  $\mathbf{y}$  supposed uncorrelated)

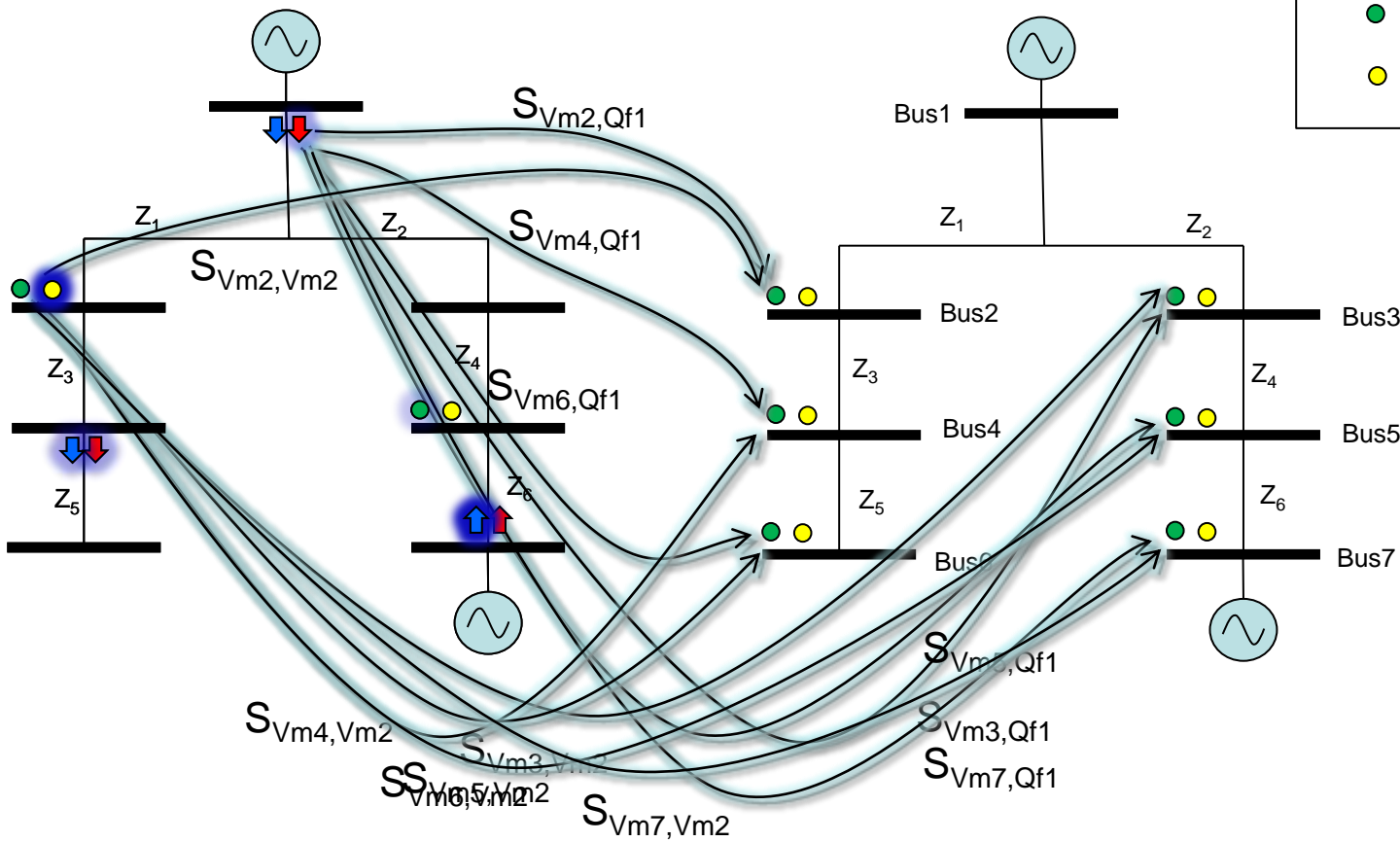
The matrices  $S_z$  and  $S_y$  show precisely how the uncertainties associated with the data vectors  $\mathbf{z}$  and  $\mathbf{y}$  contribute to the uncertainties associated with the parameter estimates  $\mathbf{x}$ .

# Sensitivity analysis



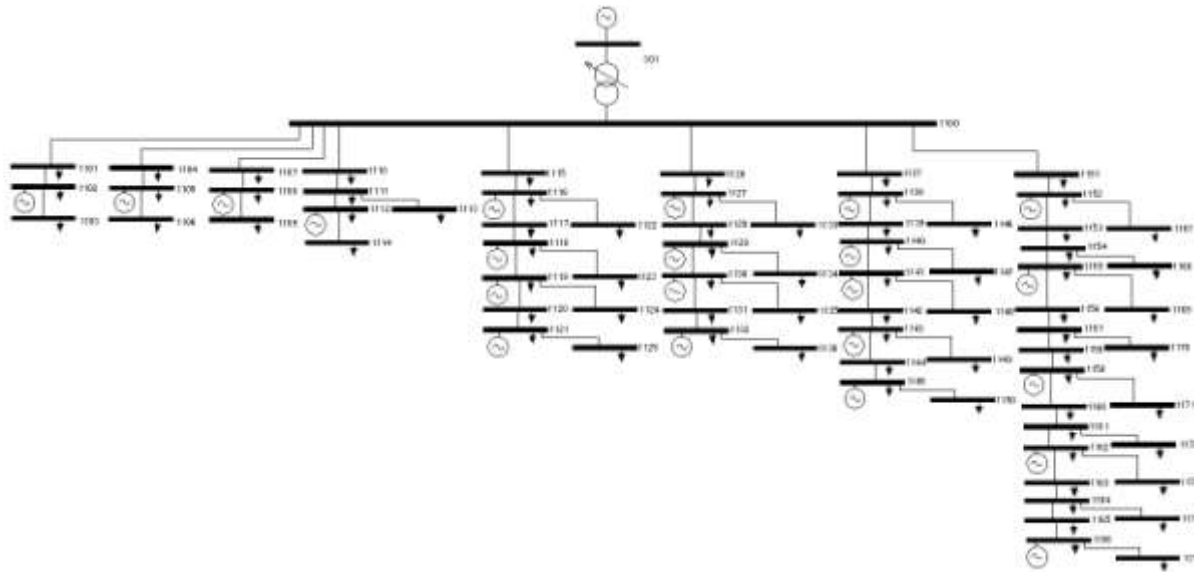
## Measurements

## Estimates

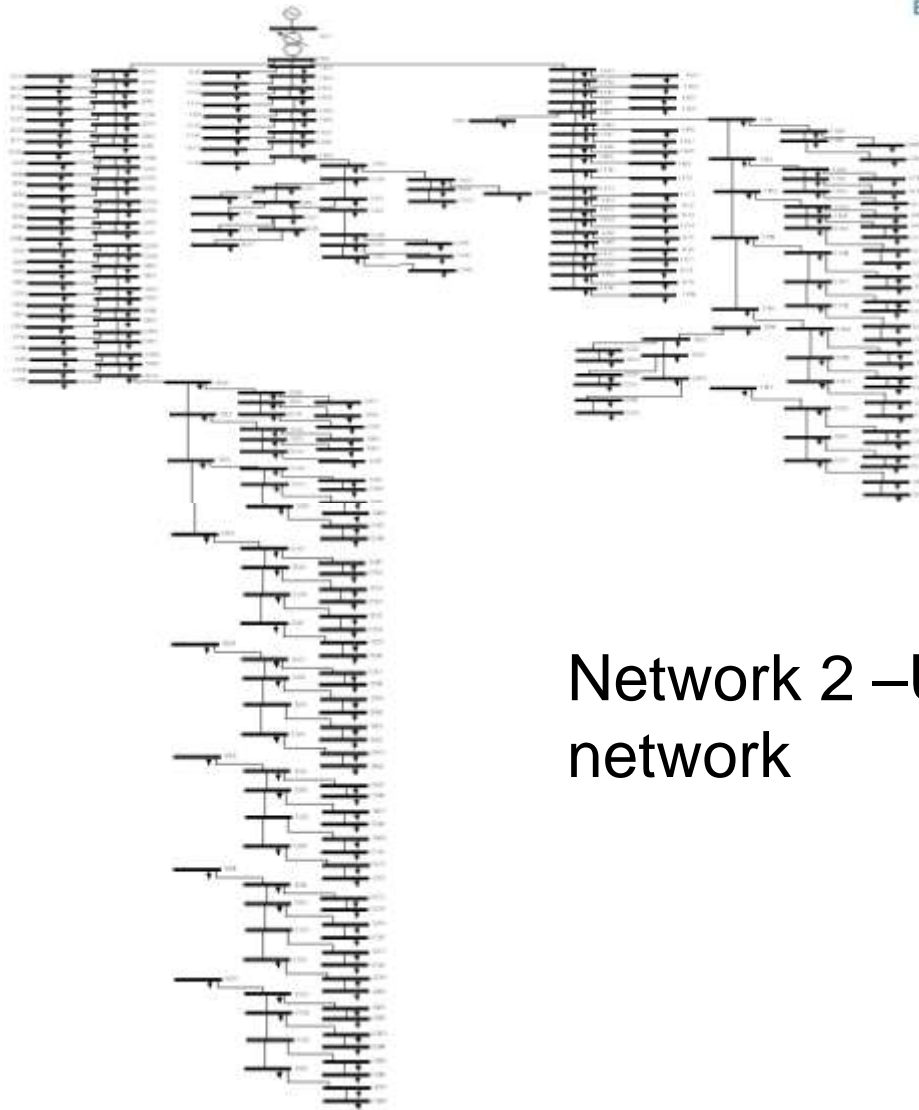


# Example simulated networks

Network 1 – United Kingdom Generic Distribution System (UKGDS) 77 bus network



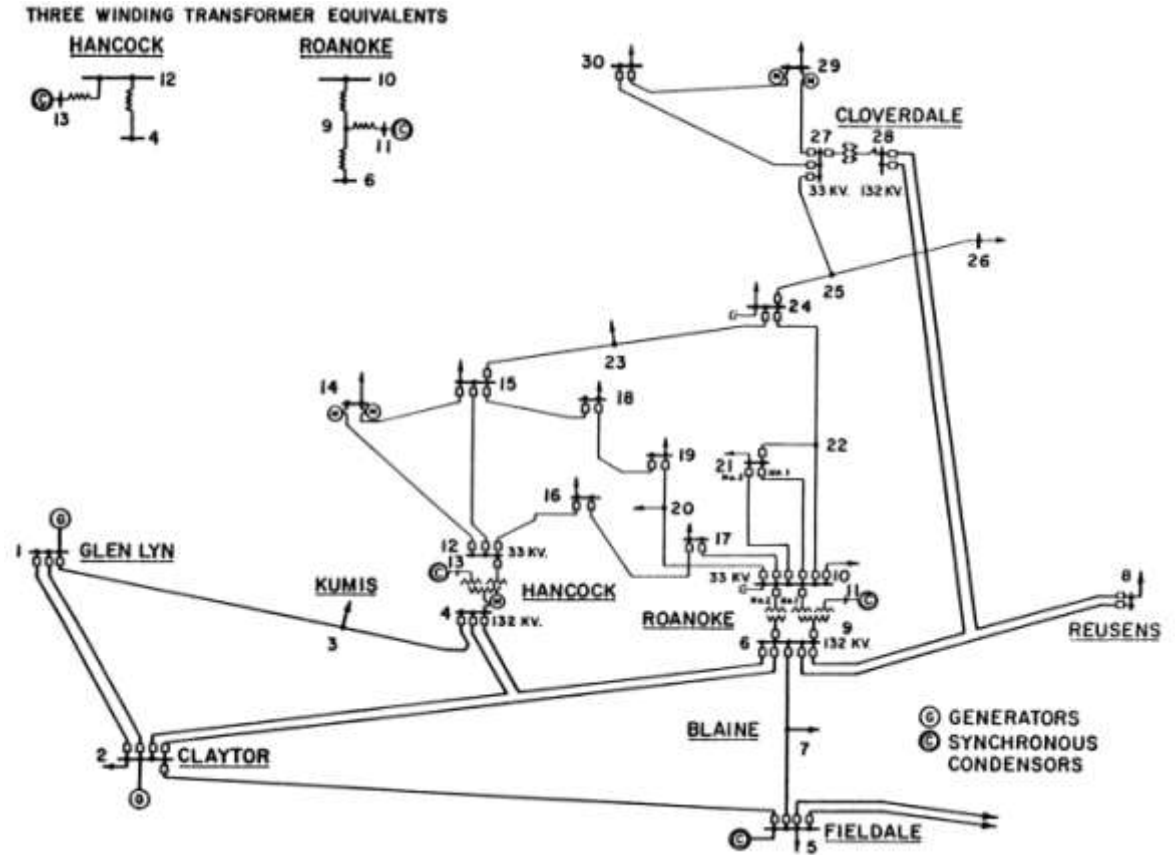
# Example simulated networks



Network 2 –UKGDS 290 bus network

# Example simulated networks

Network 3 – IEEE  
30 bus system





# Example simulated networks

## Network 4 – IEEE 300 bus system

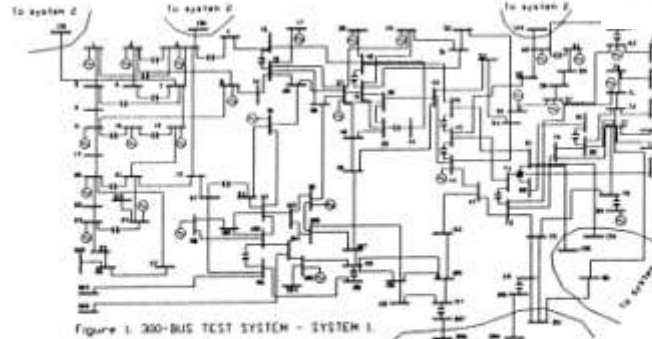


Figure 1. 300-BUS TEST SYSTEM - SYSTEM 1.

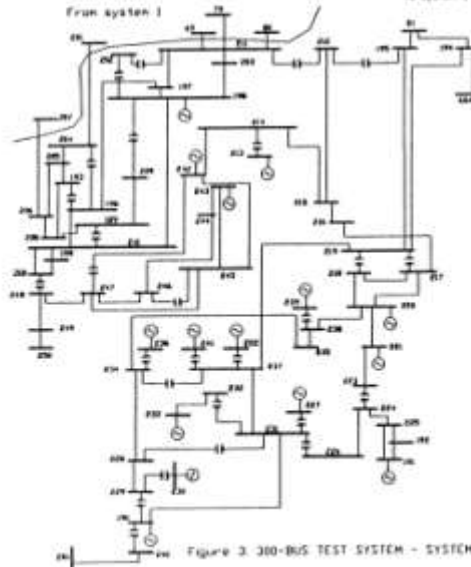


Figure 3. 300-BUS TEST SYSTEM - SYSTEM 3.

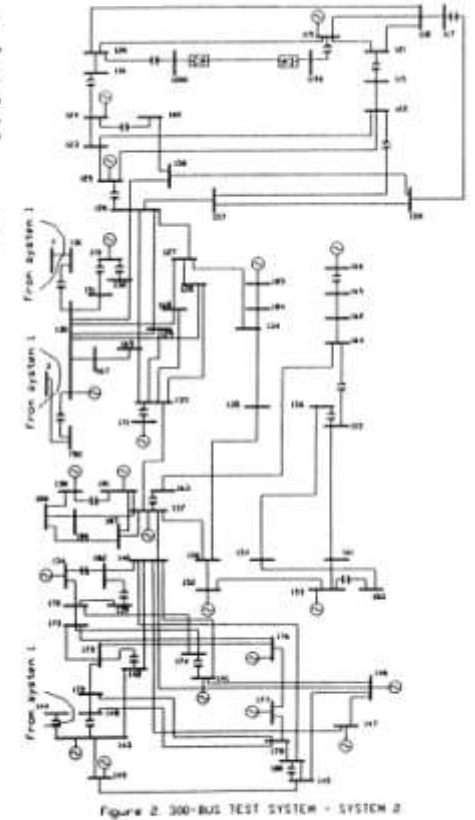
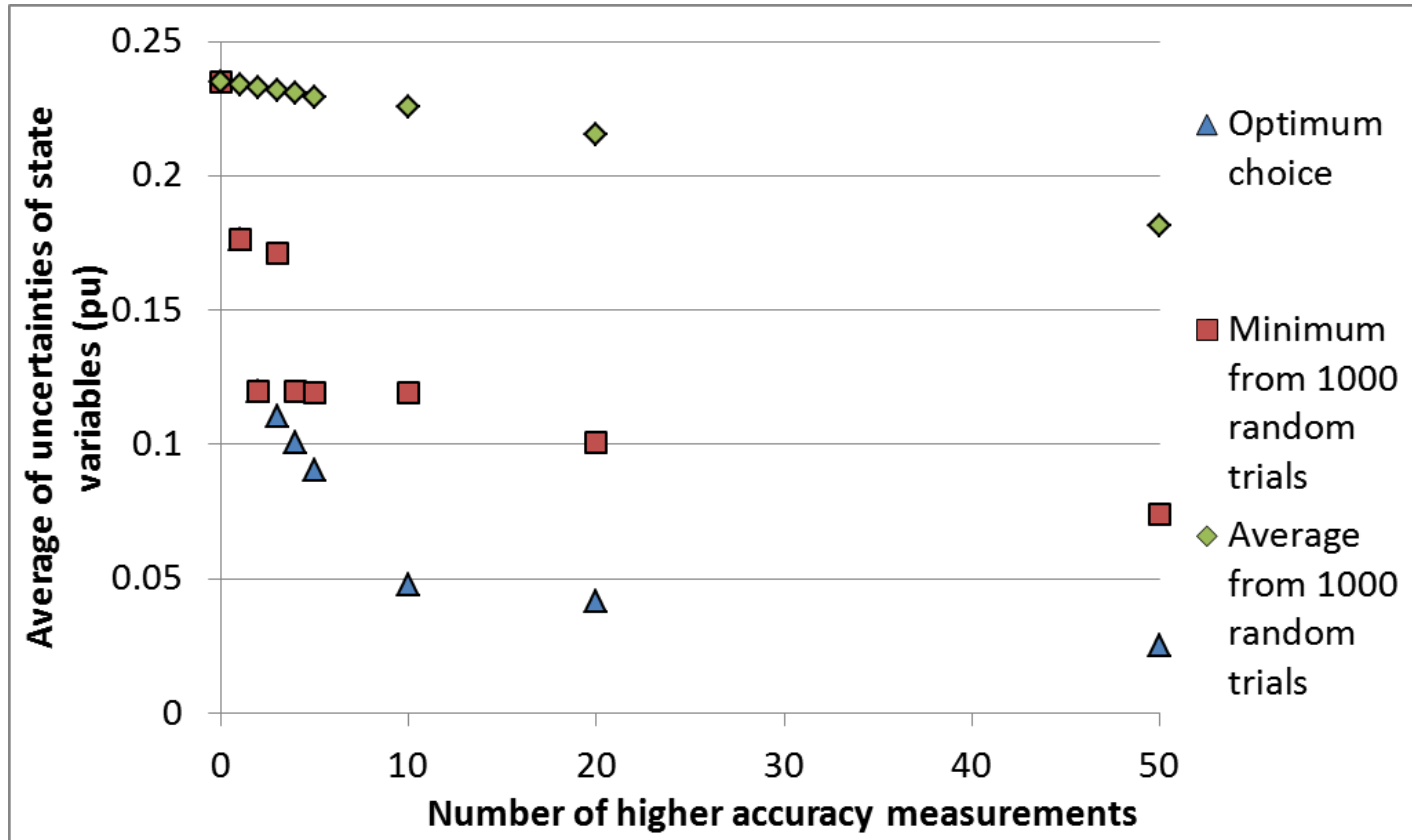


Figure 2. 300-BUS TEST SYSTEM - SYSTEM 2.

# Choosing optimum measurement locations using sensitivity analysis

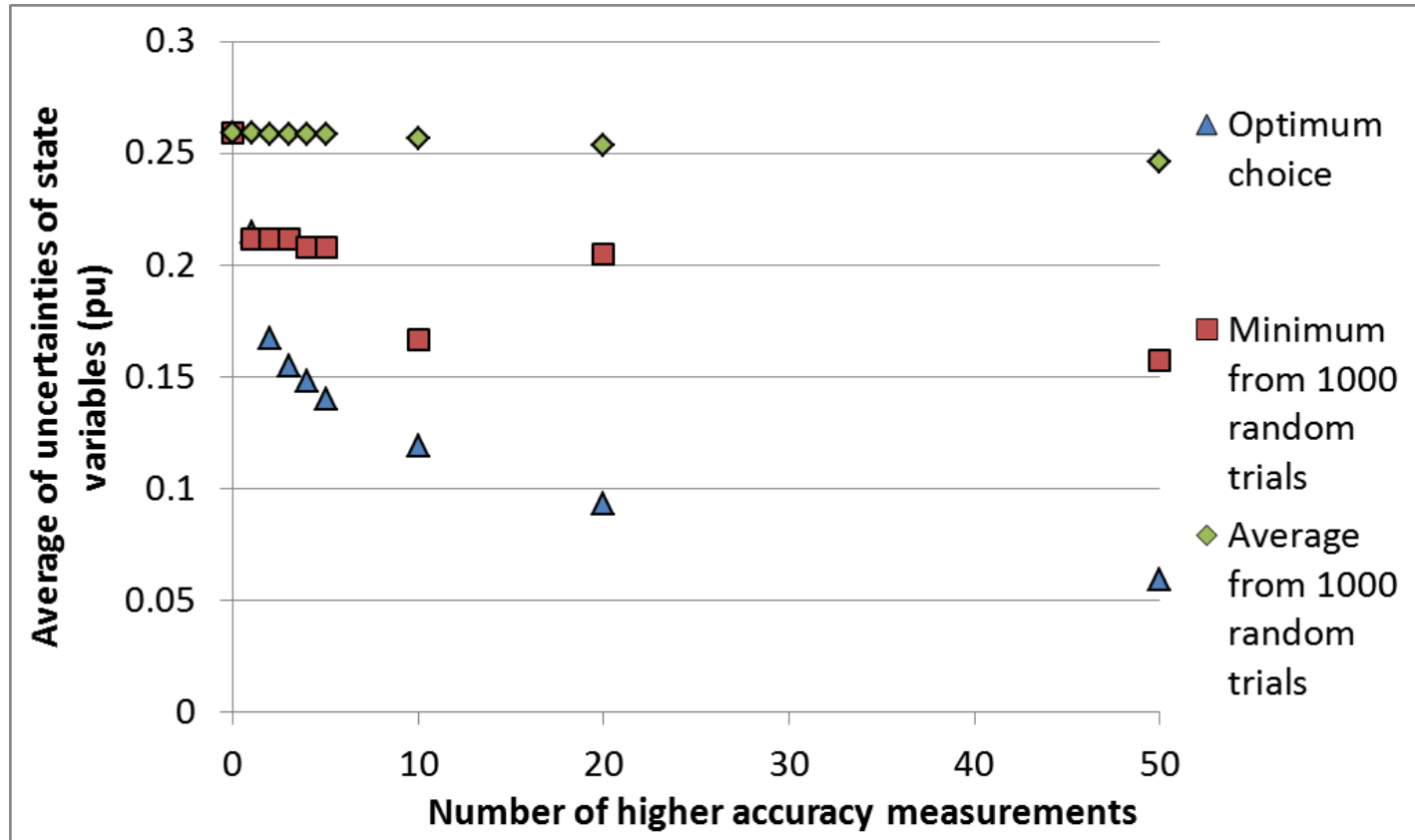
## Network 1



Choose positions of high accuracy “real” measurements and low accuracy “pseudo” measurements

# Choosing optimum measurement locations using sensitivity analysis

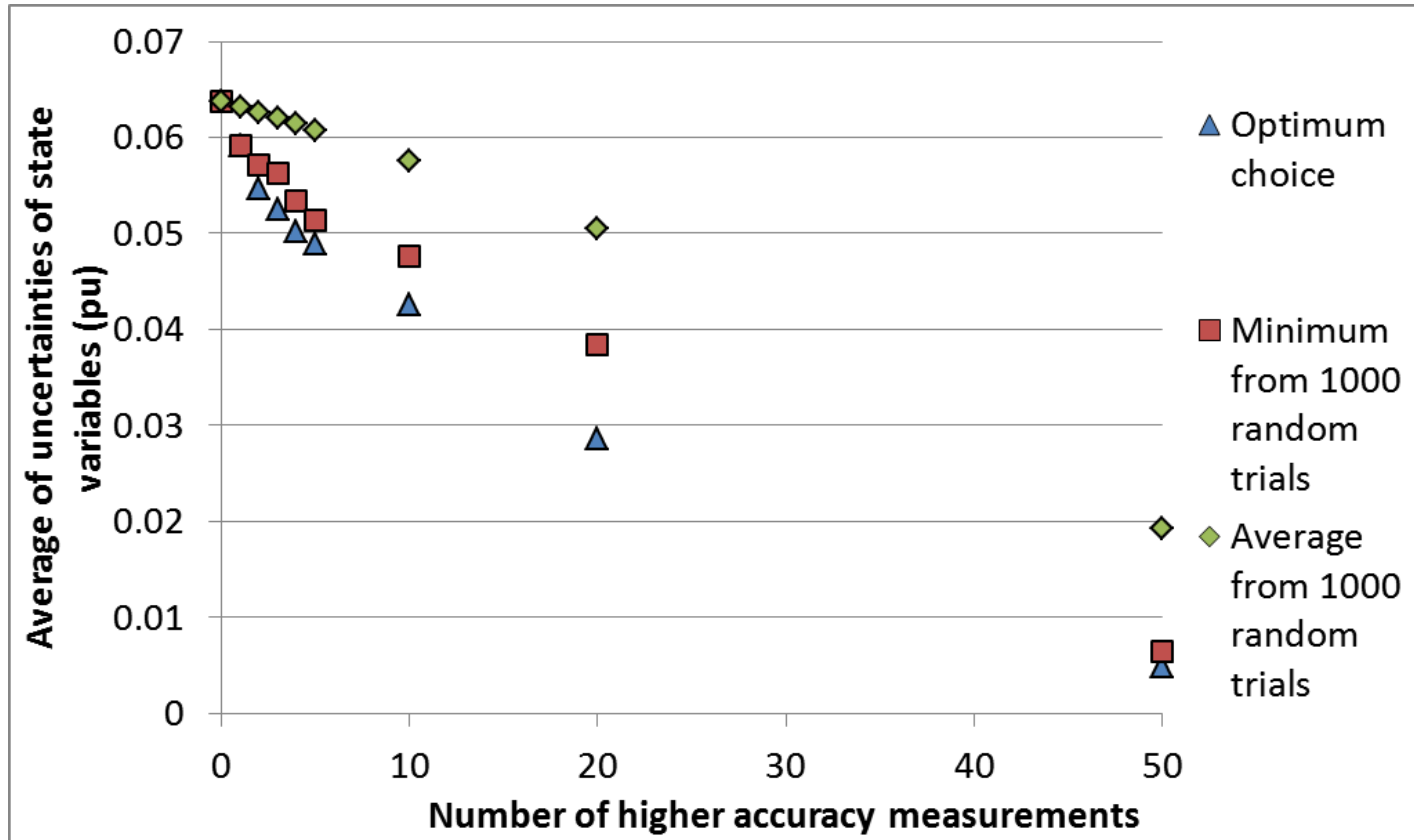
## Network 2



Choose positions of high accuracy “real” measurements and low accuracy “pseudo” measurements

# Choosing optimum measurement locations using sensitivity analysis

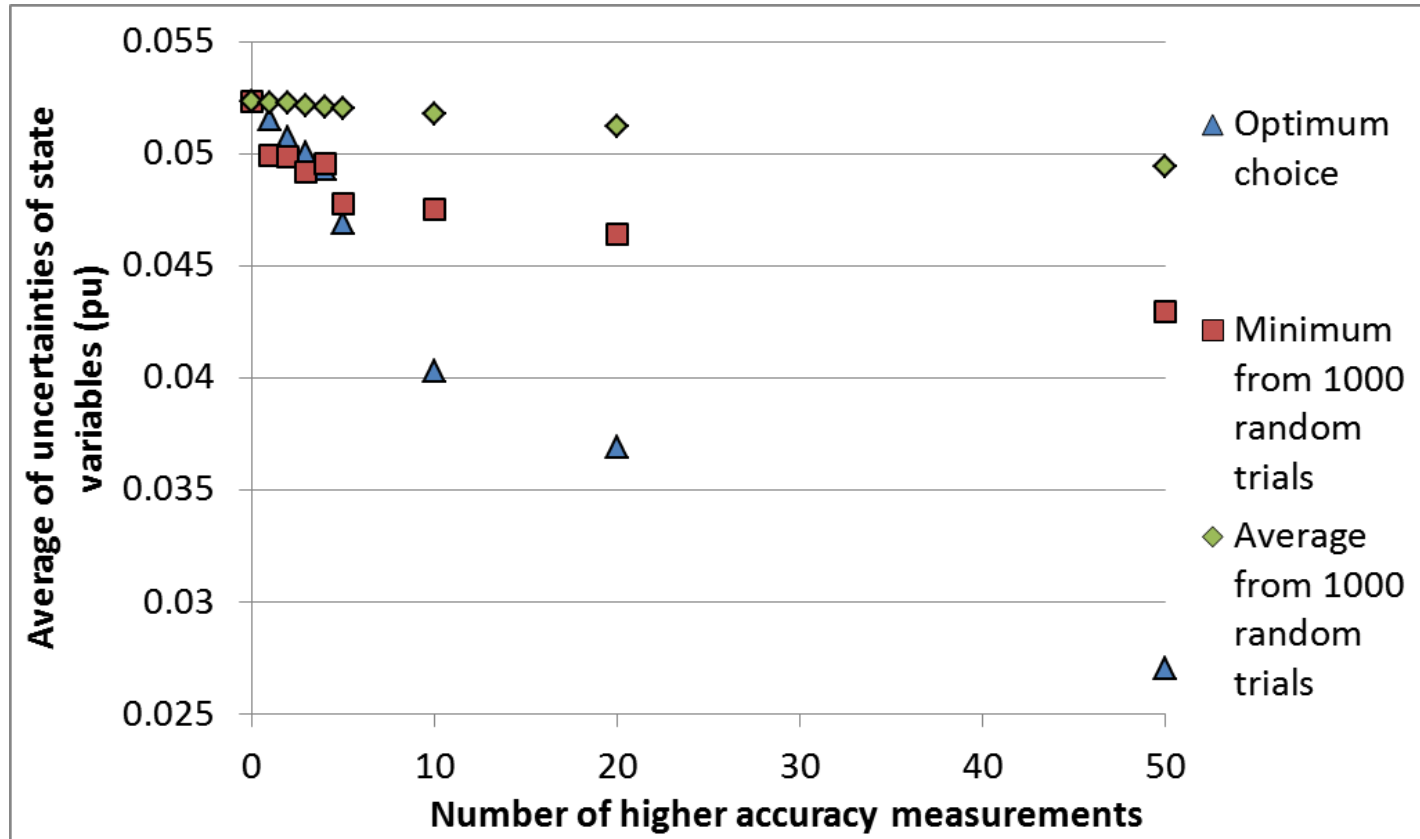
## Network 3



Choose positions of high accuracy “real” measurements and low accuracy “pseudo” measurements

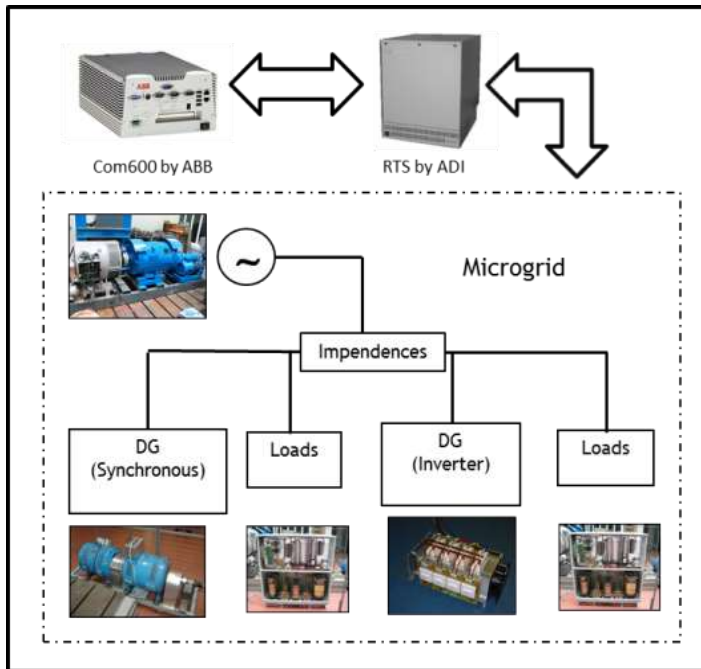
# Choosing optimum measurement locations using sensitivity analysis

## Network 4

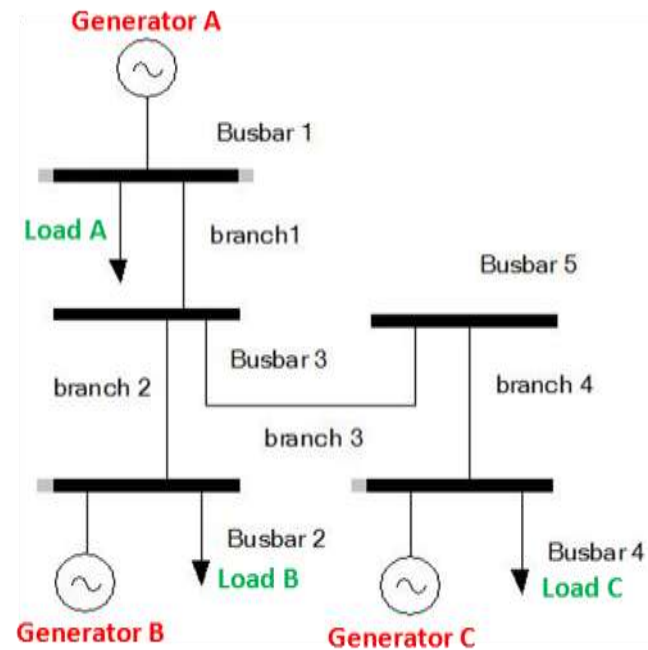


Choose positions of high accuracy “real” measurements and low accuracy “pseudo” measurements

# University of Strathclyde experimental smart-grid

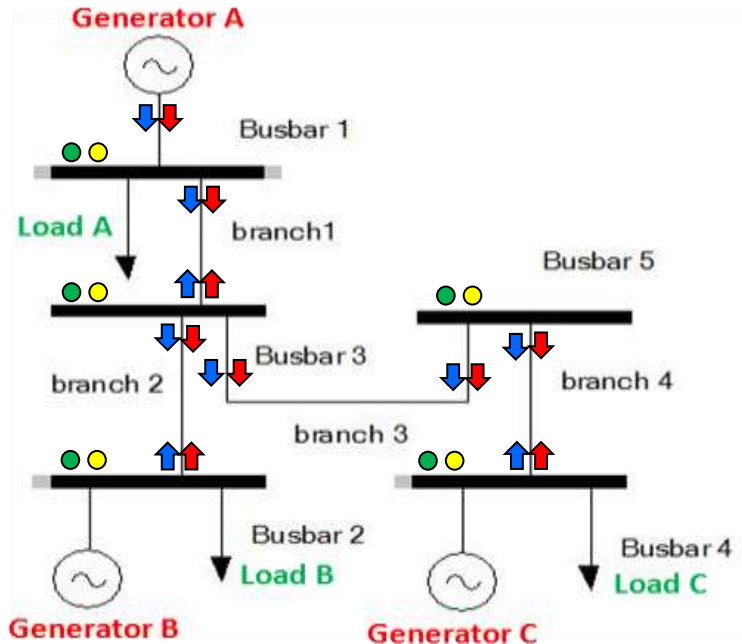


Control system



Network model

# Testing on microgrid



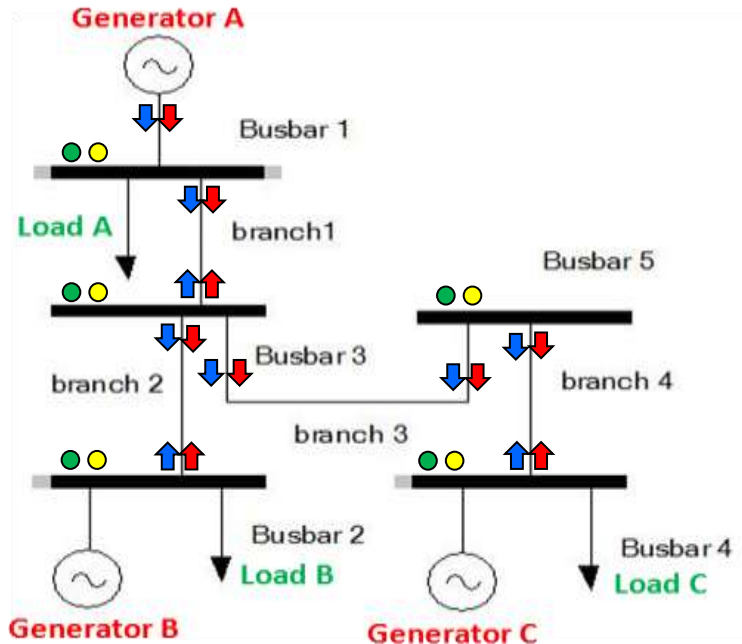
Start with fully instrumented grid

- ↓ Active power flow
- ↓ Reactive power flow
- Voltage magnitude
- Voltage angle

Apply state estimation → Measurement error

Apply sensitivity analysis → Measurement uncertainty

# Testing on microgrid



Start with fully instrumented grid

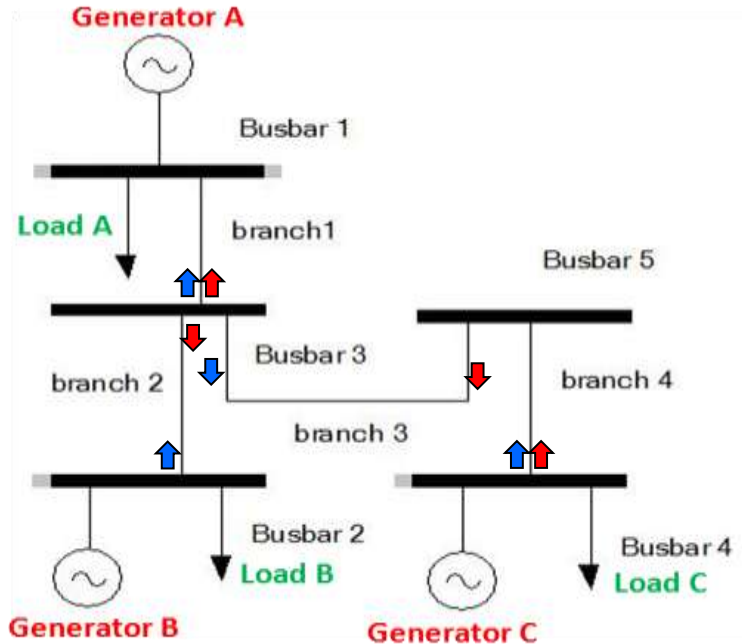
- ↓ Active power flow
- ↓ Reactive power flow
- Voltage magnitude
- Voltage angle

Average measurement error of 1.7 %

Average state variable uncertainty of 0.4 %



# Testing on microgrid



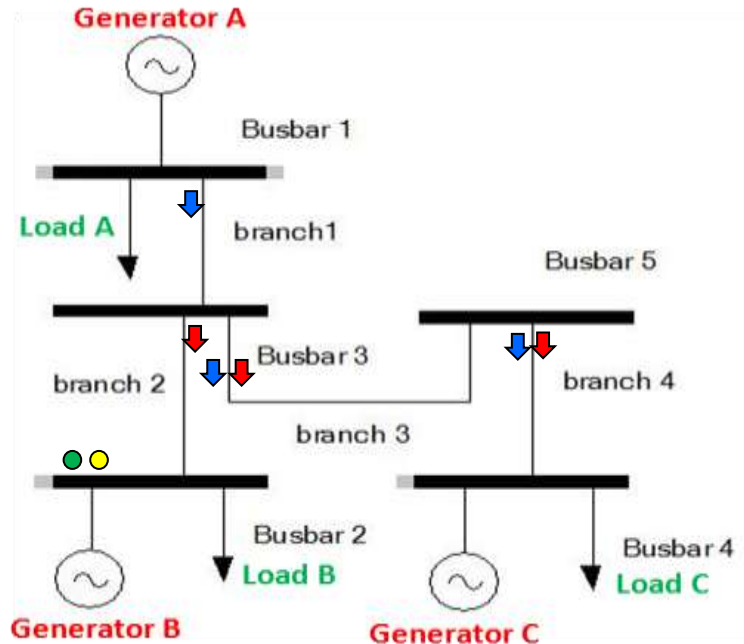
Apply algorithm to find optimum minimum measurement set

- ↓ Active power flow
- ↓ Reactive power flow
- Voltage magnitude
- Voltage angle

Average measurement error of 1.0 %

Average state variable uncertainty of 0.7 %

# Testing on microgrid



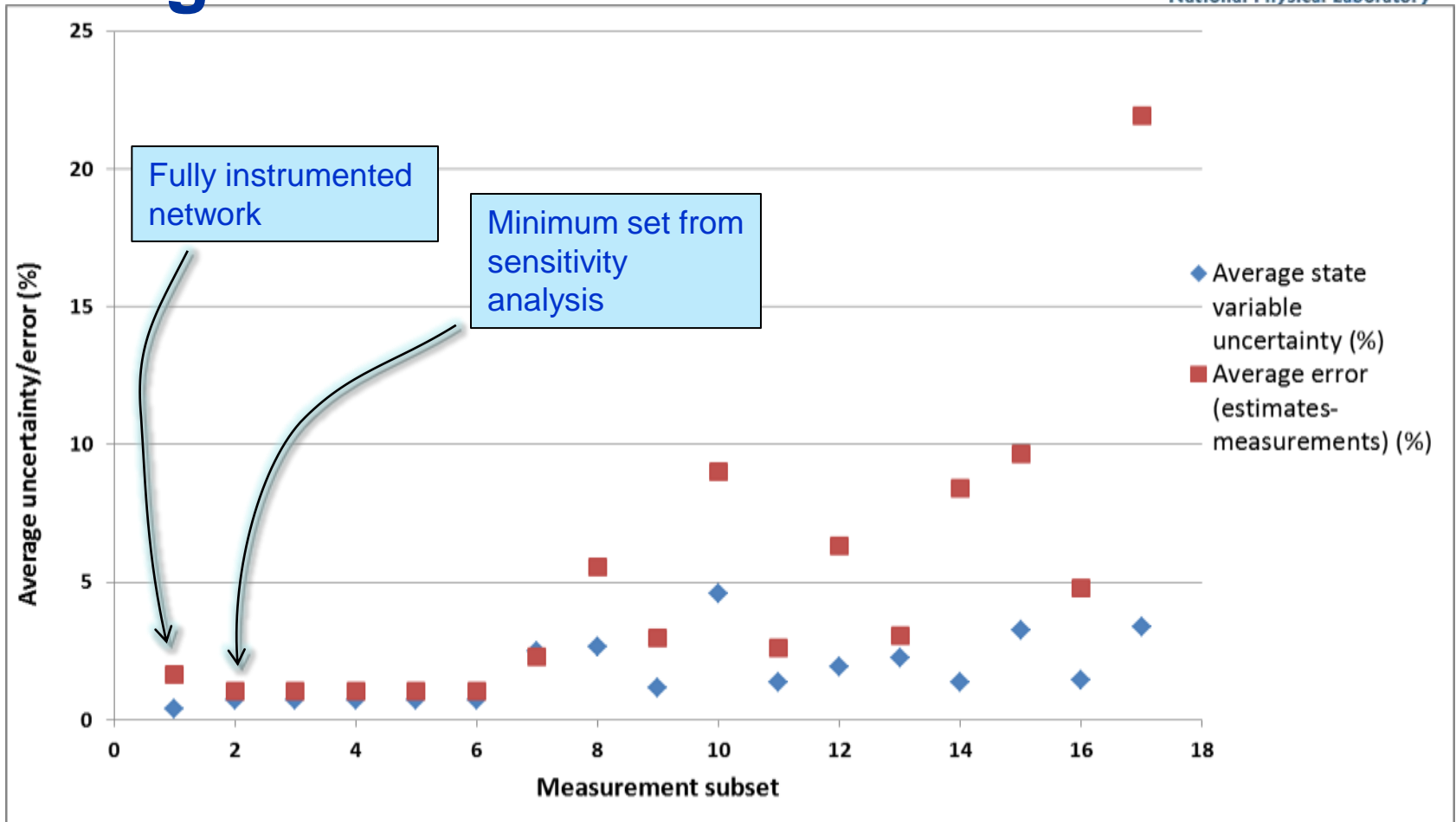
Compare with random selection of measurements

- ↓ Active power flow
- ↓ Reactive power flow
- Voltage magnitude
- Voltage angle

Average measurement error of 3.1 %

Average state variable uncertainty of 2.2 %

# Microgrid measurement errors



Comparison of measurement error and state variable uncertainty

# Summary



- Successfully modelled Strathclyde microgrid in MATLAB
- Applied state estimator to Strathclyde microgrid and larger simulated networks
- Verified uncertainty calculations against monte-carlo calculations
- Expanded state estimator to include uncertain impedances in the network interconnections
- Verified state variable uncertainty calculations against real measurements

# Next steps

- Improve speed of optimal measurement placement algorithm
- Sensitivity analysis with cable impedances included
- Apply techniques to estimate line impedances
- Expand to include unbalanced networks
- Test with distributed generation included
- Investigate use of PMU and smart meter data.
- Try on full size real networks – need to engage with DNO