
This version is available at https://strathprints.strath.ac.uk/2955/

Strathprints is designed to allow users to access the research output of the University of Strathclyde. Unless otherwise explicitly stated on the manuscript, Copyright © and Moral Rights for the papers on this site are retained by the individual authors and/or other copyright owners. Please check the manuscript for details of any other licences that may have been applied. You may not engage in further distribution of the material for any profitmaking activities or any commercial gain. You may freely distribute both the url (https://strathprints.strath.ac.uk/) and the content of this paper for research or private study, educational, or not-for-profit purposes without prior permission or charge.

Any correspondence concerning this service should be sent to the Strathprints administrator: strathprints@strath.ac.uk
Stable droplets and growth laws close to the modulational instability of a domain wall

Damià Gomila\textsuperscript{1,2}, Pere Colet\textsuperscript{1}, Gian-Luca Oppo\textsuperscript{2} and Maxi San Miguel\textsuperscript{1}

\textsuperscript{1}Instituto Mediterráneo de Estudios Avanzados, IMEDEA\textsuperscript{*} (CSIC-UIB),
Campus Universitat Illes Balears, E-07071 Palma de Mallorca, Spain.

\textsuperscript{2}Department of Physics and Applied Physics, University of Strathclyde,
107 Rottenrow, Glasgow G4 ONG, Scotland, UK.

We consider the curvature driven dynamics of a domain wall separating two equivalent states in systems displaying a modulational instability of a flat front. We derive an amplitude equation for the dynamics of the curvature close to the bifurcation point from growing to shrinking circular droplets. We predict the existence of stable droplets with a radius $R$ that diverges at the bifurcation point, where a curvature driven growth law $R(t) \approx t^{1/4}$ is obtained. Our general analytical predictions, which are valid for a wide variety of systems including models of nonlinear optical cavities and reaction-diffusion systems, are illustrated in the parametrically driven complex Ginzburg-Landau equation.

PACS numbers: 47.54.+r, 47.20.Ky, 42.65.Pc, 42.65.Sf

Growth of spatial domains of different phases in the transient regime of a system approaching thermodynamic equilibrium has been studied long ago \cite{1}. This phenomenon is a prototype of nonlinear dynamics of an extended system governed by the motion of domain walls. Power laws for the growth of a characteristic size and self-similar evolution (dynamical scaling) have been established. Clear physical mechanisms explaining the different asymptotic growth laws have also been identified \cite{1}. It is convenient to consider domain growth in systems with conserved and non-conserved order parameters separately. In the first case one talks of spinodal decomposition leading to the Lifshits-Slyozov $t^{1/3}$ power law. In the case of non-conserved order parameters, the dominant mechanism is curvature driven minimization of surface tension, leading to the Allen-Cahn (AC) $t^{1/2}$ power law \cite{2}.

The study of domain growth and domain wall motion in non-equilibrium systems that do not approach thermodynamic equilibrium is by far more complicated. There is presently only a partial understanding of a variety of possible situations \cite{3,4}. In particular a number of results have been recently reported for domain growth and domain wall motion in the transverse plane of nonlinear optical systems \cite{5,6}. However, these numerical results often fail to identify the physical mechanism responsible for the observed dynamics. Moreover, the power laws for domain growth do not always correspond unambiguously to an asymptotic and self-similar dynamics. An exception is the $t^{1/2}$ law obtained for two different optical systems for which evidence of dynamical scaling has been given \cite{7,8}. Visual inspection of the time dependent configurations clearly indicate curvature driven domain wall dynamics, but no derivation of such a law has been given for these systems. Surface tension, whose minimization may be used to explain the AC law, is not an appropriate concept for these optical systems.

In this letter we analyze the transition from a regime characterized by a $t^{1/2}$ growth law to one of labyrinthine pattern formation due to a modulational instability of a flat domain wall connecting two equivalent homogeneous solutions. Such a transition from coarsening to labyrinthine regimes has been observed experimentally in reaction-diffusion systems \cite{10} and in optical systems, and numerically in \cite{6}, as well as in Swift-Hohenberg models \cite{13}. At difference with systems approaching thermodynamic equilibrium, the coefficient of the $t^{1/2}$ power law can now change sign upon variations of a control parameter $p$ at $p = p_c$. For $p < p_c$ ($p > p_c$) a circular domain of radius $R$ of one solution embedded in the other grows (shrinks as in the AC regime) as $R(t) = \sqrt{R(0) - \gamma t}$ with $\gamma < 0$ ($\gamma > 0$). Moreover, for $p < p_c$ a flat front is modulationally unstable and a generic initial condition develops in a labyrinthine pattern. Close to the modulational instability at $p_c$, we derive an amplitude equation for the curvature of circular domains. At $p_c$, a circular domain grows as $R(t) \sim t^{1/4}$. For $p$ larger but close to $p_c$ an initially small (very large) domain grows (shrinks until a stable droplet (SD) is formed. The radius of the SD diverges at $p_c$. The SD should not be confused with other types of soliton-like localized structures (LS) appearing in the AC regime when the front oscillatory tail prevents the domain collapse \cite{3,4}. The SD are also different from the critical nucleus of nucleation theory \cite{1} where the droplet is unstable and inner and outer solutions are not equivalent. Note also that droplets found in reaction-diffusion systems \cite{14} involve two non-equivalent states.

Our analytical results are illustrated by considering a prototypical model, the parametrically driven complex Ginzburg-Landau equation (PCGLE) \cite{15,16}, which describes a oscillatory system parametrically forced at twice its natural frequency \cite{10}:

$$\partial_t A = (1 + i\alpha)\nabla^2 A + (\mu + i\nu)A - (1 + i\beta)|A|^2 A + pA^* ,$$

where $\mu$ measures the distance from the oscillatory insta-
bility threshold, \( \nu \) is the detuning parameter and \( p > 0 \) is the forcing amplitude. For \( p \sim \nu \ll \alpha \) large compared to other parameters, a finite wavelength instability forming hexagons takes place for \( p < p_w \), while for \( p > p_w \) there are two equivalent stable homogeneous solutions (frequency locked solutions) [16].

We consider a real \( N \) component vector field \( \vec{\Psi}(x) \) whose dynamical evolution in two spatial dimensions is

\[
\partial_t \vec{\Psi} = D \nabla^2 \vec{\Psi} + \vec{W}(\vec{\Psi}, p),
\]

where the matrix \( D \) describes the spatial coupling, \( \vec{W} \) is a local nonlinear function of the fields and \( p \) a control parameter. Eq. (2) is invariant under translations and under the change \( x \to -x \). In addition we assume that it has a discrete symmetry \( \mathcal{Z} \) that allows for the existence of two, and only two, equivalent stable homogeneous solutions, and that, in a 1d system, they are connected by a stable Ising front \( \vec{\Psi}_0(x, p) \). An Ising front satisfies \( \vec{\Psi}_0(x_0, p) = 2 \vec{\Psi}_0(x - x_0) \) where \( x_0 \) is the front location [17], thus the 1d front (and equivalently a flat front in 2d) is stationary, \( D \nabla^2 \vec{\Psi}_0 + \vec{W}(\vec{\Psi}_0, p) = 0 \).

For the PCGLE \( \vec{\Psi}(x) = (\Re A(\vec{x}), \Im A(\vec{x})) \), \( D = ((1, \alpha)^T, (-\alpha, 1)^T) \), \( \vec{\Psi}_0(x) \) describes a flat front connecting the two homogeneous solutions (we consider \( p > p_w \)) and \( \mathcal{Z} = -I \) where \( I \) is the identity matrix.

Let \( \vec{X}(s, t) \) represent the instantaneous position vector of the front in the \( \vec{x} \) plane, where \( s \) is the arclength. It is convenient to define a coordinate system \( (r, s) \) that moves with the front such that \( \vec{x} = \vec{X}(s, t) + r \hat{r}(s, t) \), where \( \hat{r} \) is a unit vector normal to the curve \( \vec{X} \) and the coordinate \( r \) is the distance of the point \( x \) to the front [3].

In the moving frame Eq. (2) becomes

\[
D \partial_s^2 \vec{\Psi} + \left( i v + \frac{\kappa}{1 + \kappa^2} D \right) \partial_r \vec{\Psi} + \frac{\kappa^2 D \partial_s^2 \vec{\Psi}}{(1 + \kappa^2)^2} + \vec{W}(\vec{\Psi}, p) = \partial_t \vec{\Psi} ,
\]

where \( \nu = \partial_r \vec{X} \cdot \hat{r} \) is the (normal) front velocity and \( \theta = \kappa s \) is the azimuthal angle. We analyze the dynamics of slightly curved fronts as a perturbation of the flat front \( \vec{\Psi}(r, s, t) = \vec{\Psi}_0(r) + \vec{\varphi}_1(r, s, t) \). We assume that i) \( \kappa \nu w \ll 1 \), with \( \kappa = \nabla \cdot \hat{r} \) the curvature and \( w \) the front width, ii) in the moving frame the front profile depends at most weakly on \( t \) \( (\partial_t \vec{\Psi} \ll |\kappa D \partial_r \vec{\Psi}|) \) and iii) \( \kappa \) is a function which depends at most weakly on \( s \), thus \( |\kappa D \partial_s^2 \vec{\Psi}| \ll |\partial_s \vec{\Psi}| \). Linearizing around \( \vec{\Psi}_0 \) we have

\[
M \vec{\varphi}_1 = -(i v + \kappa D) \partial_r \vec{\Psi}_0 ,
\]

where \( M \equiv D_j \partial_j^2 + \delta_{ij} W_j |\vec{\Psi}_0(p) \). Due to the translational invariance of \( M \) is singular, \( M \vec{e}_0 = 0 \) where \( \vec{e}_0 = \partial_r \vec{\Psi}_0 \) is the Goldstone mode. The solvability condition applied to (4) leads to \( v = -\gamma(p) \kappa \), where

\[
\gamma(p) = \frac{1}{\Gamma} \int_{-\infty}^{\infty} \vec{a}_0 \cdot D \vec{e}_0 dr ,
\]

\[
\Gamma \equiv \int_{-\infty}^{\infty} \vec{a}_0 \cdot \vec{e}_0 dr \] and \( \vec{a}_0 \) is the null mode of \( M \). For a circular domain \( \kappa = 1/R \) and

\[
v = \dot{R} = -\gamma(p) / R .
\]
instability leading to the formation of a labyrinthine pattern.

In Fig. 1 we show the value of $\gamma$ for the PCGLE calculated using definition (5), with the profile of the 1d front calculated numerically by solving the stationary form $\partial_t A = 0$ in 1d of (6). This calculation identifies $p_c$ for which $\gamma = 0$.

We are now ready to obtain an amplitude equation for the curvature in the vicinity of $p_c$. We start considering the case of a circular domain wall (for which $v = -k/k^2$). Close to $p_c$ ($\gamma \approx 0$) we perform a multiple scale analysis in $\epsilon$ of Eq. (3) with $p = p_c + \epsilon p_1$.

The solvability condition implies $\int_{-\infty}^{\infty} a_0 \cdot D\vec{c}_0d\epsilon = 0$, which is automatically satisfied at $p = p_c$. One finds $\vec{c}_1 = \vec{c}_1\vec{c}_2$ where $\vec{c}_2$ satisfies $M\vec{c}_1 = -D\vec{c}_0$. Due to the symmetry of the front the solvability condition at order $\epsilon$ is always fulfilled and we get $\vec{c}_2 = \epsilon p_1\vec{c}_2 + k_c^2\vec{c}_3$ with $M\vec{c}_2 = -\partial_\phi \vec{W}_0|0|$ and $M\vec{c}_3 = -D\vec{c}_0|0|e_r^0 - \frac{1}{2}\delta_{\bar{\psi}1}\vec{W}_0|0|\vec{c}_1^k$ where $|0|$ means evaluated at $\vec{W}_0$ and $p_c$. At order $\epsilon^{3/2}$, the amplitude equations for the curvature $k_1$ and the radius of the circular droplet

$$\frac{\partial_t k_1}{k_1} = c_1 p_1 k_1 + c_3 k_1^3$$

$$\partial_t R = -c_1 (p - p_c) \frac{1}{R} - c_3 \frac{1}{R^3}$$

where

$$c_1 = \frac{1}{\Gamma} \int_{-\infty}^{\infty} a_0 [D_1^2 \partial_\phi \vec{c}_2 + \delta_{\bar{\psi}1}\partial_\phi \vec{W}_0|0|\vec{c}_1 + \delta_{\bar{\psi}1}\vec{W}_0|0|\vec{c}_1^k]d\epsilon + \frac{1}{6}\delta_{\bar{\psi}1}\vec{W}_0|0|\vec{c}_1\vec{c}_1^k]d\epsilon$$

$$c_3 = \frac{1}{\Gamma} \int_{-\infty}^{\infty} a_0 [D_1^2 (\partial_\phi \vec{c}_2 - r\partial_\psi \vec{c}_1 + r^2 c_0^2) + \delta_{\bar{\psi}1}\vec{W}_0|0|\vec{c}_1\vec{c}_1^k]d\epsilon$$

are obtained from the solvability condition. The coefficient $c_1$ is positive since $\gamma = c_1 (p - p_c)$, and we are considering $\gamma > 0$ for $p > p_c$. If $c_1$ is negative (supercritical bifurcation) our analysis predicts just above the modulational instability the existence of stable stationary circular domains (SD) with a very large radius

$$R_0 = \frac{1}{\sqrt{\mu}} \frac{1}{p - p_c} \sqrt{\frac{c_3}{c_1}}$$

In Fig. 2 (left) we show the form of the SD for the PCGLE. At the center the field takes the value of one of the homogeneous solutions, so the wall of this structure is a heteroclinic orbit between the two homogeneous states. The radius of the SD can be extremely large diverging at $p = p_c$. Fig. 2 (right) displays the radius of the SD and that of the LS calculated solving numerically $(1+\alpha)(\partial^2_r + \mu \partial_\psi) A + (\mu + \nu) A - (1+i\beta) A^2 A + p A^4 = 0$. The inset in Fig. 2 (right) shows the linear dependence of $1/R^3_0$ with $p$ as predicted by (12). In spite of the fact that there is a smooth transition from LS to SD, they are intrinsically different. The interaction of the oscillatory tails which is responsible for the existence of LS does not play any role in the SD. The stabilization mechanism comes from the counterbalance between the $R^{-3}$ contribution to the front velocity and the shrinking due to the $R^{-1}$ contribution.

At the bifurcation point $p = p_c$, Eq. (8) becomes $\partial_t R = -c_3/R^3$ and any circular domain of one solution embedded in the other grows as $R(t) \sim t^{1/4}$. In Fig. 3 we show the time evolution of the radius of a circular domain for the PCGLE at $p = p_c$. It fits nicely the theoretical dependence we predict. Close to $p_c$, in the regime of existence of the SD, there is no asymptotic power law of domain growth since at very long times the SD is formed stopping the growth process. During the transient, an initially small (very large) circular domain will grow (shrink) following (13).

So far we have considered the dynamics of domains with radial symmetry. When the system evolves from random initial conditions other dynamical mechanisms come into play. Close to the bifurcation point the main non-radially symmetric contribution to the velocity comes from the variation of the curvature along the front. The derivation of the amplitude equation for the curvature leads to an additional term in Eq. (8): $c_2 \kappa^2 \partial_2^2 \kappa_1$ where $c_2 = \frac{1}{\Gamma} \int_{-\infty}^{\infty} a_0 \cdot D\vec{c}_0 d\epsilon$. The front velocity becomes $v = -c_1 (p - p_c) \kappa - c_3 \kappa^3 \partial_2 \kappa - c_3 \kappa^3$. Consistently with our approximations, $\partial_2 \kappa$ will change at most at order $\kappa^0$, so the non-radial contribution is at least of order $\kappa^2$. Close to the bifurcation point the term proportional to $\kappa$ can be neglected, and the term given by $-c_2 \kappa^2 \partial_2 \kappa$ might be dominant compared with the one proportional to $\kappa^3$. In this case the front velocity is proportional to $\kappa^2$. However, for any closed boundary $\partial_2 \kappa$ is positive in some parts of the wall and negative in others, so this term does not lead to an asymptotic growth law. For $c_2 < 0$, which is the case for the PCGLE, this term tends to reduce the curvature differences, so at $p_c$ an arbitrarily shaped domain first becomes circular until the contribution of $\partial_2 \kappa^3$ vanishes and then the circular domain grows as $R(t) \sim t^{1/4}$ due to the $c_3$ term (see Fig. 3).

In summary, we have analyzed a generic situation of domain wall motion driven by curvature effects in which the proportionality coefficient $\gamma$ between wall velocity and curvature changes sign at a bifurcation point. In optical systems, this change is a consequence of the diffractive coupling between real and imaginary parts of the complex field amplitude. The amplitude equation for the curvature in the vicinity of the bifurcation point pre-
dicts the existence of stable nonlinear solutions which are 
droplets of one phase embedded in a background of the 
second equivalent phase. Nonlinear dynamics of the cur-
vature leads to growth laws different from the AC \( t^{1/2} \)
growth law. The existence of a large characteristic length 
given by the radius of the SD destroys the possibility of 
self-similar evolution.

The authors acknowledge financial support from the 
EC TMR Network QSTRUCT (FMRXCT960077). GLO 
acknowledges SGI and EPSRC (grants M19727 and 
M31880) for financial support. DG, PC and MSM 
acknowledge financial support from MCyT (Spain, 
projects PB97-0141-C02-02 and BFM2000-1108) and 
helpful discussions with E. Hernández-García.

FIG. 1. Value of the \( \gamma \) as a function of the forcing amplitude 
\( p \) for the PCGLE calculated from (5). We take here \( \alpha = 2, \beta = 0, \nu = 2 \) and \( \mu = 0 \). For these values of the parameters 
\( p_h = 2.00 \) and \( p_c = 2.56629 \).

FIG. 2. Left: Spatial dependence and transverse section of 
a SD for the PCGLE. Right: Radius of SD (solid line) and LS 
(dotted line) as a function of the forcing for the PCGLE. The 
inset shows the linear dependence of \( 1/R_0^2 \) with \( p \) close to the 
bifurcation point as predicted by (12).

FIG. 3. Growth of a circular domain as function of the time 
at \( p = p_c \). The symbols correspond to the numerical integration of 
Eq. (3), the solid line is the theoretical prediction (3) with 
c\( c_3 = 0.3129 \) calculated from (11) and the dotted line has a 
slope 1/4 showing the asymptotic behavior.

FIG. 4. Evolution of an arbitrarily shaped domain at 
\( p = p_c \). From left to right: \( t=0, t=2400, t=80000 \) and \( t=1650000 \).

* Electronic address: http://www.ime.dea.uib.es/PhysDept

[1] J.D. Gunton, M. San Miguel and P. Sahni in Phase Transi-
tions and Critical Phenomena, 8, 269, edited by C. Domb 
Phys. 43, 357 (1994).
(1995); C. Josserand and S. Rica, ibidem. 69, 1215 
979 (1998); M. Tlidi et al., Optics Lett. 25, 487 (2000); 
2241 (2000).
(2000).
(1997).
[18] \( \Gamma \) vanishes at an Ising-Bloch transition [17]. Here we only 
consider parameter regions far away from any Ising-Bloch 
transition for which \( \Gamma \) is never zero.